TS Series Documentation Release 1

Magna-Power Electronics, Inc.

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CHAPTER

ONE

PREFACE

Thank you for choosing a Magna-Power Electronics product. This document provides user, service, and programming information the TS Series MagnaDC programmable DC power supply. If you have any suggestions or feedback for this document, please contact Magna-Power at feedback@magna-power.com.

1.1 Contact Magna-Power

Magna-Power support can be contacted for service, technical support, or spare parts:

• By Phone: +1-908-237-2200

• By Email: support@magna-power.com

Visit magna-power.com/support for more support resources and information about contacting Magna-Power world-wide.

1.2 Safety Notice

The following general safety precautions must be observed during all phases of operation of this instrument. Failure to comply with these precautions or with specific warnings elsewhere in this manual violates safety standards of design, manufacture, and intended use of the instrument. Neither Magna-Power Electronics nor any of the associated sales organizations accept responsibility for personal injury, consequential injury, loss, or damage resulting from improper use of the equipment and accessories.

Installation and service must be performed only by properly trained and qualified personnel who are aware of dealing with electrical hazards. Ensure that the AC power line ground is properly connected to the MagnaDC power supply chassis. Furthermore, other power grounds, including those connected to application maintenance equipment, must be grounded for both personnel and equipment safety.

This product is a Safety Class 1 instrument, provided with a protective earth terminal. The protective features of this product may be impaired if it is used in a manner not specified in the operation instructions.

Warning: Residiual voltage. Lethal voltages may be present inside the MagnaDC power supply even when the AC input voltage is disconnected. Only properly trained and qualified personnel should remove covers and access the inside of the MagnaDC power supply.

During normal operation, the operator does not have access to hazardous voltages within the product's chassis. Depending on the application, high voltages hazardous to human safety may be present on the DC power terminals. Ensure that the DC power cables are properly labeled as to the safety hazards and that any inadvertent contact with hazardous voltages is eliminated.

Do not install substitute parts or perform unauthorized maintenance on the product.

These operating instructions form an integral part of the equipment and must be available to the operating personnel at all times. All the safety instructions and advice notes are to be followed.

Warning: General. Do not use this product in any manner not specified by the manufacturer. The protective features of this product may be impaired if it is used in a manner not specified in the operating instructions.

Warning: Environmental Conditions. Never use the instrument outside of the specified environmental conditions described in the Environmental Characteristics of the specifications.

Warning: Ground the Instrument. This product is provided with protective earth terminals. To minimize shock hazard, the instrument must be connected to the AC mains through a grounded power cable, with the ground wire firmly connected to an electrical ground (safety ground) at the power outlet. Any interruption of the protective (grounding) conductor or disconnection of the protective earth terminal will cause a potential shock hazard that could result in injury or death.

Warning: Before Applying Power. Verify that all safety precautions are taken. All connections must be made with the unit turned off, and must be performed by qualified personnel who are aware of the hazards involved. Improper actions can cause fatal injury as well as equipment damage. Note the instrument's external markings described under "Safety Symbols".

Warning: Do Not Operate in an Explosive Atmosphere. Do not operate the instrument in the presence of flammable gases or fumes.

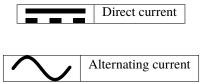
Warning: Do Not Remove the Instrument Cover. Only qualified, service-trained personnel who are aware of the hazards involved should remove instrument covers. Disconnect the power cable and any external circuits before removing instrument covers.

Warning: Do Not Modify the Instrument. Do not install substitute parts or perform any unauthorized modification to the product, except with the direction of Magna-Power support personnel. Return the product to a Magna-Power authorized service center for repair.

Warning: In Case of Damage. Instruments that are not functioning correctly, appear damaged or defective should be made inoperative and secured against unintended operation until they can be repaired by qualified service personnel.

2 Chapter 1. Preface

1.3 Safety Symbols

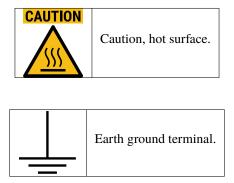




Caution. Refer to documentation or notation for more information before proceeding.



Caution, risk of electric shock. Refer to documentation or notation for more information before proceeding.





The ETL mark, which is a registered trademark of Intertek.



The CE mark, which is a registered trademark of the European Community.

1.4 Limited Warranty

The following is made in lieu of all warranties expressed or implied.

Magna-Power Electronics, Inc. warranties its products to be free of manufacturing defects for a period of two years from date of original shipment from its factory. Magna-Power Electronics, Inc. will repair, replace, or refund the purchase price at its discretion, which upon examination by Magna-Power Electronics, Inc., is determined to be defective in material or workmanship, providing such claimed defective material is returned upon written authorization of Magna-Power Electronics, Inc., freight and duties prepaid.

1.3. Safety Symbols

For products failing within the first 30 days of the warranty period, Magna-Power Electronics, Inc. will return the repaired product at its expense using a standard ground shipping method; after 30 days of the warranty period, the repaired product will be returned at the customer's expense using the customer's requested shipping method.

Damage due to corrosion, customer alterations, excessive dust, extreme environmental or electrical conditions, and/or misuse will be evaluated upon inspection. If inspection reveals that the cause of damage is not due to materials or workmanship, repair of the product will be treated on a non-warranty basis.

All electrical, commercial supply parts, and items not manufactured by Magna-Power Electronics, Inc. shall carry the warranty of the original manufacturer and no more, but under no circumstances to exceed the warranty period. Replacement parts shall be warranted for a period of 90 days. Warranty labor shall only apply if the product, assembly, or part is returned to the factory freight prepaid and insured. Damage or breakage while in transit is not covered by this warranty.

Magna-Power Electronics, Inc. assumes no responsibility to Buyer for labor to diagnose and remove defective product and installation of replacement product. Furthermore, Magna-Power Electronics, Inc. is not liable to Buyer or to any third party for consequential or incidental damages under any circumstances, whether due to defect in the product, due to delay or failure of delivery, due to a failure of the product to perform as specified, or for any other reason or cause. Buyer and Magna-Power Electronics, Inc. agree that Buyer's sole remedy and Magna-Power Electronics, Inc.'s sole liability to Buyer is limited to repair, replacement, or refund of the purchase price of the product as described herein, whether Buyer's claim arises out of contract or in tort.

All claims against the warranty shall be the final determination of Magna-Power Electronics, Inc.

1.5 User Manual Warranty

The material contained in this document is provided "as is," and is subject to being changed, without notice, in future editions. Further, to the maximum extent permitted by applicable law, Magna-Power disclaims all warranties, either express or implied, with regard to this manual and any information contained herein, including but not limited to the implied warranties of merchantability and fitness for a particular purpose. Magna-Power shall not be liable for errors or for incidental or consequential damages in connection with the furnishing, use, or performance of this document or of any information contained herein. Should Magna-Power and the user have a separate written agreement with warranty terms covering the material in this document that conflict with these terms, the warranty terms in the separate agreement shall control.

1.6 U.S. Government Rights

The Software is "commercial computer software," as defined by Federal Acquisition Regulation ("FAR") 2.101. Pursuant to FAR 12.212 and 27.405-3 and Department of Defense FAR Supplement ("DFARS") 227.7202, the U.S. government acquires commercial computer software under the same terms by which the software is customarily provided to the public. Accordingly, Magna-Power provides the Software to U.S. government customers under its standard commercial license, which is embodied in its End User License Agreement (EULA). The license set forth in the EULA represents the exclusive authority by which the U.S. government may use, modify, distribute, or disclose the Software. The EULA and the license set forth therein, does not require or permit, among other things, that Magna-Power: (1) Furnish technical information related to commercial computer software or commercial computer software documentation that is not customarily provided to the public; or (2) Relinquish to, or otherwise provide, the government rights in excess of these rights customarily provided to the public to use, modify, reproduce, release, perform, display, or disclose commercial computer software documentation. No additional government requirements beyond those set forth in the EULA shall apply, except to the extent that those terms, rights, or licenses are explicitly required from all providers of commercial computer software pursuant to the FAR and the DFARS and are set forth specifically in writing elsewhere in the EULA. Magna-Power shall be under no obligation to update, revise or otherwise modify the Software. With respect to any technical data as defined by FAR 2.101, pursuant to FAR 12.211

and 27.404.2 and DFARS 227.7102, the U.S. government acquires no greater than Limited Rights as defined in FAR 27.401 or DFAR 227.7103-5 (c), as applicable in any technical data

1.7 WEEE Directive 2002/96/EC

This product complies with the Waste Electrical and Electronic Equipment (WEEE) Directive 2002/96/EC marking requirement. The affixed product label (see below) indicates that you must not discard this electrical/electronic product in domestic household waste.



Product Category: With reference to the equipment types in the WEEE directive Annex 1, this product is classified as "Monitoring and Control instrumentation" product.

Do not dispose products in domestic household waste.

To return unwanted products, contact Magna-Power Electronics.

1.8 Declaration of Conformity

Magna-Power Electronics declares on its sole responsibility that the TS Series MagnaDC programmable DC power supply complies with the essential requirement of the relevant European Directives, and is eligible to carry the CE mark.

For more details, please review the TS Series Declaration of Conformity.

1.9 Document Conventions

This user's manual uses several conventions to highlight certain words and phrases and draw attention to specific pieces of information.

Note: Notes are tips, shortcuts or alternative approaches to the task at hand. Ignoring a note should have no negative consequences, but you might miss out on a time saving procedure.

Warning: The warning sign denotes a hazard, calling attention to a procedure or practice. If a warning is not correctly performed or adhered to, it could result in personal injury. Do not proceed beyond a warning sign until the conditions are fully understood or met.

Caution: The caution sign denotes a hazard, calling attention to a procedure or practice. If a caution is not correctly performed or adhered to, it could result in damage to the product. Do not proceed beyond a caution sign until the conditions are fully understood or met.

Source-code listings are also set in mono-spaced roman but add syntax highlighting as follows:

```
#!/usr/bin/python
# -*- coding: utf-8 -*-

from serial import Serial

class Magna(Serial):
    def __init__(self, port, expected_serial_number=None, log=None):
        super(Magna, self).__init__(port, baudrate=19200, timeout=2.0)
        self.log = log if log else self.magna_log
        self.write('*CLS\r\n')
```

1.10 Additional Help and Feedback

For additional help or to provide feedback about the product's design and features, please contact: support@magna-power.com.

6 Chapter 1. Preface

PRODUCT INTRODUCTION

2.1 Features at a Glance

The TS Series offers many models spanning a wide voltage and current range, while still maintaining among the highest power density rack-mount packaging. The TS Series covers voltages from 5 Vdc up to 6000 Vdc (floating) and current levels from 1.2 Adc up to 8000 Adc. Models 5 kW to 15 kW are available in a 3U chassis, models 20 kW and 25 kW are available in a 4U chassis, models 30 kW are available in a 6U chassis, models 40 kW and 50 kW are available in an 8U chassis with removable casters, models 75 kW models are available in a 12U chassis with removable casters, and 100 kW models are available in a 16U chassis with removable casters. In addition, there are several special low voltage high current models, enabling a more cost-effective solution for these requirements. All TS Series power supplies come standard with isolated 37-pin external I/O, RS232, Remote Interface Software, IVI drivers, and LabVIEW drivers for integration into a variety of programming environment.

A quick summary of the TS Series key features:

- SCPI Remote Programming API
- High Accuracy Measurements
- · Master-Slave Functionality
- Remote Sensing
- 37-Pin External User I/O
- RS232 Interface
- Ethernet and GPIB Available
- 0-10V External Analog Inputs
- Programmable Protection Limits
- Fast Transient Response
- Remote Interface Software
- NI LabVIEWTM and IVI Driver
- · Interlock Shutdown Input
- · Designed and manufactured in the USA

2.1.1 Output Features

- Robust Power Conversion Topology All MagnaDC programmable DC power supplies utilize high-frequency IGBT-based power processing in current-fed topology. This topology adds an additional stage over the conventional voltage-fed topology for enhanced control and system protection, ensuring that even under a fault condition, the power supply will self-protect. Due to the self-protecting characteristics of this topology, the possibility of fast rising current spikes and magnetic core saturation is elimated. Every power supply is tested at 90% to 125% nominal line to ensure satisfactory operation even under the worst line voltage conditions.
- Fast Transient Response Quick response to load changes, with 2 ms to recover within $\pm 1\%$ of regulated output with a 50% to 100% or 100% to 50% step load change.
- **Programmable Output Protection** Programmable over voltage trip (OVT) and over current trip (OCT) allow the user to program in soft latching fault trips when the threshold is exceeded. OVT and OCT settings can be programmed from 10% to 110% of the unit's max ratings.
- Wired Remote Sensing with Smart Detection A set of remote sensing terminals are provided to sense voltage at the load and compensate for voltage drop in the load cables. Compensation is provided up to 3% above the unit's max rated voltage.
- Leadless Remote Sensing Using the product's integrated modulation functionality, automatically compensate for voltage as a function of current. When the impedance between the power supply and load is known, this feature allows for remote sensing without leads, up to the max ratings of the product.

2.1.2 Programming Features

- High Accuracy Programming and Measurment \pm 0.075% of max rated voltage or current programming accuracy to ensures the output is following the desired programmed set point. \pm 0.2% of max rated voltage or current readback accuracy ensures high accuracy measurements. A NIST traceable calibration certificate is provided at no charge with all new units.
- **Simultaneous Measurement Interfaces** Voltage and current measurements are available simultaneously from the front panel meters, dedicated 0-10V analog output, and by computer command.
- SCPI Remote Programming API Compatible with the Standard Commands for Programmable Instruments (SCPI), allowing raw ASCII text commands to control all features, functions, and configurations of the product. Commands are consistent across all available interfaces.
- 37-pin External User I/O Port An isolated 37-pin external user I/O port is provided, which includes a variety of analog and digital inputs and outputs. Voltage, current, over voltage and over current set points can be set by applying a 0-10V analog signal. Each diagnostic condition is given a designated pin, which reads +5V when active. Reference +5V and +10V signals are provided, eliminating the need for external voltage signals and allowing the use of dry contacts. All these pins are isolated from the output terminals and referenced to earth-ground as standard—no additional isolation equipment or options necessary.

2.1.3 System Features

- AC Mechanical Contactor with In-rush Limiter An integrated mechanical contactor on the AC input circuit ensures the product is not processing power when in standby or fault. This contactor, coupled with step-start in-rush limiter circuitry, ensures no in-rush current will exceed peak input current rating of the product.
- **Designed for Safety** Extensive diagnostic functions are provided, including: AC phase loss (not on SL/XR Series), excessive thermal conditions, over voltage trip (programmable), over current trip (programmable), cleared fuse (not on SL/XR Series), excessive program line voltage, and interlock fault. A dedicated +5V interlock input pin and included +5V reference on all models, external emergency stop systems can be easily integrated using an external contact.

- High-Performance Plug and Play Master-Slaving Power capability can easily expanded with additional units by using the plug and play UID47 master-slaving device. In the MagnaDC master-slave scheme, the master sends gate drive signals directly to the slave units. This strategy eliminates the noise suceptibility commonly found when sending analog control references over long distances, in addition to enabling consistent performance by maintaining a single control loop.
- Tailor Performance with Integrated Options A variety of configured-to-order options are available for MagnaDC programmable power supplies are designed to be flexible, depending on the application's requirements.
- Designed and Manufactured in the USA For complete control of quality, MagnaDC programmable DC power supplies are designed and manufactured at Magna-Power's vertically integrated USA manufacturing facility in Flemington, New Jersey. Heat-sinks and chassis are machined from aluminum. All sheet metal is fabricated and powder coated in-house. Magnetics are wound-to-order from validated designs based on a model's voltage and current. An automated surface-mount production line places components on printed circuit boards for control, driver, auxiliary power, and display circuits. And finally after assembly, products undergo comprehensive test and NIST-traceable calibration, followed by an extended burn-in period.

2.2 Models

The following tables list the available models in the TS Series MagnaDC power supply. Ripple is specified for standard models. Ripple will be higher for models with the *High Slew Rate Output (+HS)*. Low voltage, high current models have a size size and input current rating that differ from the rated specifications for models within the same power level. Efficiency is measured at the model's maximum ratings.

2.2.1 Model Ordering Guide

The following ordering guide defines how an TS Series MagnaDC power supply is defined:

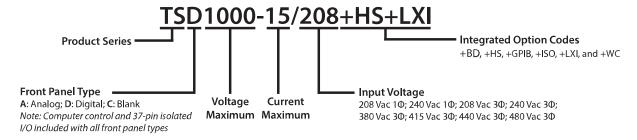


Fig. 2.1: TS Series MagnaDC power supply Model Ordering Guide

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2.2.2 5 kW TS Series Models

| Model | Maximum Voltage | Maximum Current | Ripple | Efficiency |
|-------------|-----------------|-----------------|-----------|------------|
| TSD5-900 | 5 Vdc | 900 Adc | 50 mVrms | 84% |
| TSD8-600 | 8 Vdc | 600 Adc | 40 mVrms | 85% |
| TSD10-500 | 10 Vdc | 500 Adc | 40 mVrms | 87% |
| TSD16-300 | 16 Vdc | 300 Adc | 35 mVrms | 87% |
| TSD20-250 | 20 Vdc | 250 Adc | 40 mVrms | 88% |
| TSD25-200 | 25 Vdc | 200 Adc | 40 mVrms | 89% |
| TSD32-150 | 32 Vdc | 150 Adc | 40 mVrms | 89% |
| TSD40-125 | 40 Vdc | 125 Adc | 40 mVrms | 89% |
| TSD50-100 | 50 Vdc | 100 Adc | 50 mVrms | 89% |
| TSD60-83 | 60 Vdc | 83 Adc | 60 mVrms | 87% |
| TSD80-62 | 80 Vdc | 62 Adc | 60 mVrms | 90% |
| TSD100-50 | 100 Vdc | 50 Adc | 60 mVrms | 90% |
| TSD125-40 | 125 Vdc | 40 Adc | 100 mVrms | 90% |
| TSD160-31 | 160 Vdc | 31 Adc | 120 mVrms | 90% |
| TSD200-25 | 200 Vdc | 25 Adc | 125 mVrms | 91% |
| TSD250-20 | 250 Vdc | 20 Adc | 130 mVrms | 91% |
| TSD300-16 | 300 Vdc | 16 Adc | 160 mVrms | 91% |
| TSD375-13 | 375 Vdc | 13 Adc | 170 mVrms | 92% |
| TSD400-12 | 400 Vdc | 12 Adc | 180 mVrms | 92% |
| TSD500-10 | 500 Vdc | 10 Adc | 220 mVrms | 92% |
| TSD600-8 | 600 Vdc | 8 Adc | 250 mVrms | 92% |
| TSD800-6 | 800 Vdc | 6 Adc | 300 mVrms | 92% |
| TSD1000-5 | 1000 Vdc | 5 Adc | 350 mVrms | 92% |
| TSD1250-4 | 1250 Vdc | 4 Adc | 375 mVrms | 92% |
| TSD1500-3.3 | 1500 Vdc | 3.3 Adc | 400 mVrms | 92% |
| TSD2000-2.5 | 2000 Vdc | 2.5 Adc | 600 mVrms | 92% |
| TSD3000-1.6 | 3000 Vdc | 1.6 Adc | 650 mVrms | 92% |
| TSD4000-1.2 | 4000 Vdc | 1.2 Adc | 700 mVrms | 92% |

2.2.3 10 kW TS Series Models

| Model | Maximum Voltage | Maximum Current | Ripple | Efficiency |
|-------------|-----------------|-----------------|-----------|------------|
| TSD10-900 | 10 Vdc | 900 Adc | 40 mVrms | 87% |
| TSD16-600 | 16 Vdc | 600 Adc | 35 mVrms | 87% |
| TSD20-500 | 20 Vdc | 500 Adc | 40 mVrms | 88% |
| TSD25-400 | 25 Vdc | 400 Adc | 40 mVrms | 89% |
| TSD32-300 | 32 Vdc | 300 Adc | 40 mVrms | 89% |
| TSD40-250 | 40 Vdc | 250 Adc | 40 mVrms | 89% |
| TSD50-200 | 50 Vdc | 200 Adc | 50 mVrms | 89% |
| TSD60-166 | 60 Vdc | 166 Adc | 60 mVrms | 87% |
| TSD80-124 | 80 Vdc | 124 Adc | 60 mVrms | 90% |
| TSD100-100 | 100 Vdc | 100 Adc | 60 mVrms | 90% |
| TSD125-80 | 125 Vdc | 80 Adc | 100 mVrms | 90% |
| TSD160-62 | 160 Vdc | 62 Adc | 120 mVrms | 90% |
| TSD200-50 | 200 Vdc | 50 Adc | 125 mVrms | 91% |
| TSD250-40 | 250 Vdc | 40 Adc | 130 mVrms | 91% |
| TSD300-32 | 300 Vdc | 32 Adc | 160 mVrms | 91% |
| TSD375-26 | 375 Vdc | 26 Adc | 170 mVrms | 92% |
| TSD400-24 | 400 Vdc | 24 Adc | 180 mVrms | 92% |
| TSD500-20 | 500 Vdc | 20 Adc | 220 mVrms | 92% |
| TSD600-16 | 600 Vdc | 16 Adc | 250 mVrms | 92% |
| TSD800-12 | 800 Vdc | 12 Adc | 300 mVrms | 92% |
| TSD1000-10 | 1000 Vdc | 10 Adc | 350 mVrms | 92% |
| TSD1250-8 | 1250 Vdc | 8 Adc | 375 mVrms | 92% |
| TSD1500-6.6 | 1500 Vdc | 6.6 Adc | 400 mVrms | 92% |
| TSD2000-5 | 2000 Vdc | 5 Adc | 600 mVrms | 92% |
| TSD3000-3.2 | 3000 Vdc | 3.2 Adc | 650 mVrms | 92% |
| TSD4000-2.4 | 4000 Vdc | 2.4 Adc | 700 mVrms | 92% |

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2.2.4 15 kW TS Series Models

| Model | Maximum Voltage | Maximum Current | Ripple | Efficiency |
|-------------|-----------------|-----------------|-----------|------------|
| TSD16-900 | 16 Vdc | 900 Adc | 35 mVrms | 87% |
| TSD20-750 | 20 Vdc | 750 Adc | 40 mVrms | 88% |
| TSD25-600 | 25 Vdc | 600 Adc | 40 mVrms | 89% |
| TSD32-450 | 32 Vdc | 450 Adc | 40 mVrms | 89% |
| TSD40-375 | 40 Vdc | 375 Adc | 40 mVrms | 89% |
| TSD50-300 | 50 Vdc | 300 Adc | 50 mVrms | 89% |
| TSD60-249 | 60 Vdc | 249 Adc | 60 mVrms | 87% |
| TSD80-186 | 80 Vdc | 186 Adc | 60 mVrms | 90% |
| TSD100-150 | 100 Vdc | 150 Adc | 60 mVrms | 90% |
| TSD125-120 | 125 Vdc | 120 Adc | 100 mVrms | 90% |
| TSD160-93 | 160 Vdc | 93 Adc | 120 mVrms | 90% |
| TSD200-75 | 200 Vdc | 75 Adc | 125 mVrms | 91% |
| TSD250-60 | 250 Vdc | 60 Adc | 130 mVrms | 91% |
| TSD300-48 | 300 Vdc | 48 Adc | 160 mVrms | 91% |
| TSD375-39 | 375 Vdc | 39 Adc | 170 mVrms | 92% |
| TSD400-36 | 400 Vdc | 36 Adc | 180 mVrms | 92% |
| TSD500-30 | 500 Vdc | 30 Adc | 220 mVrms | 92% |
| TSD600-24 | 600 Vdc | 24 Adc | 250 mVrms | 92% |
| TSD800-18 | 800 Vdc | 18 Adc | 300 mVrms | 92% |
| TSD1000-15 | 1000 Vdc | 15 Adc | 350 mVrms | 92% |
| TSD1250-12 | 1250 Vdc | 12 Adc | 375 mVrms | 92% |
| TSD1500-9.9 | 1500 Vdc | 9.9 Adc | 400 mVrms | 92% |
| TSD2000-7.5 | 2000 Vdc | 7.5 Adc | 600 mVrms | 92% |
| TSD3000-4.8 | 3000 Vdc | 4.8 Adc | 650 mVrms | 92% |
| TSD4000-3.6 | 4000 Vdc | 3.6 Adc | 700 mVrms | 92% |

2.2.5 20 kW TS Series Models

| Model | Maximum Voltage | Maximum Current | Ripple | Efficiency |
|--------------|-----------------|-----------------|-----------|------------|
| TSD10-2000 | 10 Vdc | 2000 Adc | 40 mVrms | 87% |
| TSD20-1000 | 20 Vdc | 1000 Adc | 40 mVrms | 88% |
| TSD25-800 | 25 Vdc | 800 Adc | 40 mVrms | 89% |
| TSD32-625 | 32 Vdc | 625 Adc | 40 mVrms | 89% |
| TSD40-500 | 40 Vdc | 500 Adc | 40 mVrms | 89% |
| TSD50-400 | 50 Vdc | 400 Adc | 50 mVrms | 89% |
| TSD60-333 | 60 Vdc | 333 Adc | 60 mVrms | 87% |
| TSD80-250 | 80 Vdc | 250 Adc | 60 mVrms | 90% |
| TSD100-200 | 100 Vdc | 200 Adc | 60 mVrms | 90% |
| TSD125-160 | 125 Vdc | 160 Adc | 100 mVrms | 90% |
| TSD160-125 | 160 Vdc | 125 Adc | 120 mVrms | 90% |
| TSD200-100 | 200 Vdc | 100 Adc | 125 mVrms | 91% |
| TSD250-80 | 250 Vdc | 80 Adc | 130 mVrms | 91% |
| TSD300-66.6 | 300 Vdc | 66.6 Adc | 160 mVrms | 91% |
| TSD375-53.3 | 375 Vdc | 53.3 Adc | 170 mVrms | 92% |
| TSD400-50 | 400 Vdc | 50 Adc | 180 mVrms | 92% |
| TSD500-40 | 500 Vdc | 40 Adc | 220 mVrms | 92% |
| TSD600-33.3 | 600 Vdc | 33.3 Adc | 250 mVrms | 92% |
| TSD800-25 | 800 Vdc | 25 Adc | 300 mVrms | 92% |
| TSD1000-20 | 1000 Vdc | 20 Adc | 350 mVrms | 92% |
| TSD1250-16 | 1250 Vdc | 16 Adc | 375 mVrms | 92% |
| TSD1500-13.3 | 1500 Vdc | 13.3 Adc | 400 mVrms | 92% |
| TSD2000-10 | 2000 Vdc | 10 Adc | 600 mVrms | 92% |
| TSD3000-6.6 | 3000 Vdc | 6.6 Adc | 650 mVrms | 92% |
| TSD4000-5 | 4000 Vdc | 5 Adc | 700 mVrms | 92% |

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2.2.6 25 kW TS Series Models

| Model | Maximum Voltage | Maximum Current | Ripple | Efficiency |
|--------------|-----------------|-----------------|-----------|------------|
| TSD20-1250 | 20 Vdc | 1250 Adc | 40 mVrms | 88% |
| TSD25-1000 | 25 Vdc | 1000 Adc | 40 mVrms | 89% |
| TSD32-781 | 32 Vdc | 781 Adc | 40 mVrms | 89% |
| TSD40-625 | 40 Vdc | 625 Adc | 40 mVrms | 89% |
| TSD50-500 | 50 Vdc | 500 Adc | 50 mVrms | 89% |
| TSD60-416 | 60 Vdc | 416 Adc | 60 mVrms | 87% |
| TSD80-312.5 | 80 Vdc | 312.5 Adc | 60 mVrms | 90% |
| TSD100-250 | 100 Vdc | 250 Adc | 60 mVrms | 90% |
| TSD125-200 | 125 Vdc | 200 Adc | 100 mVrms | 90% |
| TSD160-156 | 160 Vdc | 156 Adc | 120 mVrms | 90% |
| TSD200-125 | 200 Vdc | 125 Adc | 125 mVrms | 91% |
| TSD250-100 | 250 Vdc | 100 Adc | 130 mVrms | 91% |
| TSD300-83.3 | 300 Vdc | 83.3 Adc | 160 mVrms | 91% |
| TSD375-66.6 | 375 Vdc | 66.6 Adc | 170 mVrms | 92% |
| TSD400-62.5 | 400 Vdc | 62.5 Adc | 180 mVrms | 92% |
| TSD500-50 | 500 Vdc | 50 Adc | 220 mVrms | 92% |
| TSD600-41.6 | 600 Vdc | 41.6 Adc | 250 mVrms | 92% |
| TSD800-31.2 | 800 Vdc | 31.2 Adc | 300 mVrms | 92% |
| TSD1000-25 | 1000 Vdc | 25 Adc | 350 mVrms | 92% |
| TSD1250-20 | 1250 Vdc | 20 Adc | 375 mVrms | 92% |
| TSD1500-16.6 | 1500 Vdc | 16.6 Adc | 400 mVrms | 92% |
| TSD2000-12.5 | 2000 Vdc | 12.5 Adc | 600 mVrms | 92% |
| TSD3000-8.3 | 3000 Vdc | 8.3 Adc | 650 mVrms | 92% |
| TSD4000-6.2 | 4000 Vdc | 6.2 Adc | 700 mVrms | 92% |

2.2.7 30 kW TS Series Models

| Model | Maximum Voltage | Maximum Current | Ripple | Efficiency |
|--------------|-----------------|-----------------|-----------|------------|
| TSD16-1800 | 16 Vdc | 1800 Adc | 35 mVrms | 87% |
| TSD20-1500 | 20 Vdc | 1500 Adc | 40 mVrms | 88% |
| TSD25-1200 | 25 Vdc | 1200 Adc | 40 mVrms | 89% |
| TSD32-900 | 32 Vdc | 900 Adc | 40 mVrms | 89% |
| TSD40-750 | 40 Vdc | 750 Adc | 40 mVrms | 89% |
| TSD50-600 | 50 Vdc | 600 Adc | 50 mVrms | 89% |
| TSD60-498 | 60 Vdc | 498 Adc | 60 mVrms | 87% |
| TSD80-372 | 80 Vdc | 372 Adc | 60 mVrms | 90% |
| TSD100-300 | 100 Vdc | 300 Adc | 60 mVrms | 90% |
| TSD125-240 | 125 Vdc | 240 Adc | 100 mVrms | 90% |
| TSD160-186 | 160 Vdc | 186 Adc | 120 mVrms | 90% |
| TSD200-150 | 200 Vdc | 150 Adc | 125 mVrms | 91% |
| TSD250-120 | 250 Vdc | 120 Adc | 130 mVrms | 91% |
| TSD300-96 | 300 Vdc | 96 Adc | 160 mVrms | 91% |
| TSD375-78 | 375 Vdc | 78 Adc | 170 mVrms | 92% |
| TSD400-72 | 400 Vdc | 72 Adc | 180 mVrms | 92% |
| TSD500-60 | 500 Vdc | 60 Adc | 220 mVrms | 92% |
| TSD600-48 | 600 Vdc | 48 Adc | 250 mVrms | 92% |
| TSD800-36 | 800 Vdc | 36 Adc | 300 mVrms | 92% |
| TSD1000-30 | 1000 Vdc | 30 Adc | 350 mVrms | 92% |
| TSD1250-24 | 1250 Vdc | 24 Adc | 375 mVrms | 92% |
| TSD1500-19.8 | 1500 Vdc | 19.8 Adc | 400 mVrms | 92% |
| TSD2000-15 | 2000 Vdc | 15 Adc | 600 mVrms | 92% |
| TSD3000-9.6 | 3000 Vdc | 9.6 Adc | 650 mVrms | 92% |
| TSD4000-7.2 | 4000 Vdc | 7.2 Adc | 700 mVrms | 92% |

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2.2.8 40 kW TS Series Models

| Model | Maximum Voltage | Maximum Current | Ripple | Efficiency |
|--------------|-----------------|-----------------|-----------|------------|
| TSD10-4000 | 10 Vdc | 4000 Adc | 40 mVrms | 87% |
| TSD20-2000 | 20 Vdc | 2000 Adc | 40 mVrms | 88% |
| TSD25-1600 | 25 Vdc | 1600 Adc | 40 mVrms | 89% |
| TSD32-1250 | 32 Vdc | 1250 Adc | 40 mVrms | 89% |
| TSD40-1000 | 40 Vdc | 1000 Adc | 40 mVrms | 89% |
| TSD50-800 | 50 Vdc | 800 Adc | 50 mVrms | 89% |
| TSD60-666 | 60 Vdc | 666 Adc | 60 mVrms | 87% |
| TSD80-500 | 80 Vdc | 500 Adc | 60 mVrms | 90% |
| TSD100-400 | 100 Vdc | 400 Adc | 60 mVrms | 90% |
| TSD125-320 | 125 Vdc | 320 Adc | 100 mVrms | 90% |
| TSD160-250 | 160 Vdc | 250 Adc | 120 mVrms | 90% |
| TSD200-200 | 200 Vdc | 200 Adc | 125 mVrms | 91% |
| TSD250-160 | 250 Vdc | 160 Adc | 130 mVrms | 91% |
| TSD300-133.2 | 300 Vdc | 133.2 Adc | 160 mVrms | 91% |
| TSD375-106.6 | 375 Vdc | 106.6 Adc | 170 mVrms | 92% |
| TSD400-100 | 400 Vdc | 100 Adc | 180 mVrms | 92% |
| TSD500-80 | 500 Vdc | 80 Adc | 220 mVrms | 92% |
| TSD600-66.6 | 600 Vdc | 66.6 Adc | 250 mVrms | 92% |
| TSD800-50 | 800 Vdc | 50 Adc | 300 mVrms | 92% |
| TSD1000-40 | 1000 Vdc | 40 Adc | 350 mVrms | 92% |
| TSD1250-32 | 1250 Vdc | 32 Adc | 375 mVrms | 92% |
| TSD1500-26.6 | 1500 Vdc | 26.6 Adc | 400 mVrms | 92% |
| TSD2000-20 | 2000 Vdc | 20 Adc | 600 mVrms | 92% |
| TSD3000-13.2 | 3000 Vdc | 13.2 Adc | 650 mVrms | 92% |
| TSD4000-10 | 4000 Vdc | 10 Adc | 700 mVrms | 92% |

2.2.9 50 kW TS Series Models

| Model | Maximum Voltage | Maximum Current | Ripple | Efficiency |
|--------------|-----------------|-----------------|-----------|------------|
| TSD20-2500 | 20 Vdc | 2500 Adc | 40 mVrms | 88% |
| TSD25-2000 | 25 Vdc | 2000 Adc | 40 mVrms | 89% |
| TSD32-1562 | 32 Vdc | 1562 Adc | 40 mVrms | 89% |
| TSD40-1250 | 40 Vdc | 1250 Adc | 40 mVrms | 89% |
| TSD50-1000 | 50 Vdc | 1000 Adc | 50 mVrms | 89% |
| TSD60-832 | 60 Vdc | 832 Adc | 60 mVrms | 87% |
| TSD80-625 | 80 Vdc | 625 Adc | 60 mVrms | 90% |
| TSD100-500 | 100 Vdc | 500 Adc | 60 mVrms | 90% |
| TSD125-400 | 125 Vdc | 400 Adc | 100 mVrms | 90% |
| TSD160-312 | 160 Vdc | 312 Adc | 120 mVrms | 90% |
| TSD200-250 | 200 Vdc | 250 Adc | 125 mVrms | 91% |
| TSD250-200 | 250 Vdc | 200 Adc | 130 mVrms | 91% |
| TSD300-166.6 | 300 Vdc | 166.6 Adc | 160 mVrms | 91% |
| TSD375-133.2 | 375 Vdc | 133.2 Adc | 170 mVrms | 92% |
| TSD400-125 | 400 Vdc | 125 Adc | 180 mVrms | 92% |
| TSD500-100 | 500 Vdc | 100 Adc | 220 mVrms | 92% |
| TSD600-83.2 | 600 Vdc | 83.2 Adc | 250 mVrms | 92% |
| TSD800-62.4 | 800 Vdc | 62.4 Adc | 300 mVrms | 92% |
| TSD1000-50 | 1000 Vdc | 50 Adc | 350 mVrms | 92% |
| TSD1250-40 | 1250 Vdc | 40 Adc | 375 mVrms | 92% |
| TSD1500-33.2 | 1500 Vdc | 33.2 Adc | 400 mVrms | 92% |
| TSD2000-25 | 2000 Vdc | 25 Adc | 600 mVrms | 92% |
| TSD3000-16.6 | 3000 Vdc | 16.6 Adc | 650 mVrms | 92% |
| TSD4000-12.4 | 4000 Vdc | 12.4 Adc | 700 mVrms | 92% |

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2.2.10 75 kW TS Series Models

| Model | Maximum Voltage | Maximum Current | Ripple | Efficiency |
|-------------|-----------------|-----------------|------------|------------|
| TS10-6000 | 10 Vdc | 6000 Adc | 40 mVrms | 87% |
| TS20-3750 | 20 Vdc | 3750 Adc | 40 mVrms | 88% |
| TS25-3000 | 25 Vdc | 3000 Adc | 40 mVrms | 89% |
| TS32-2343 | 32 Vdc | 2343 Adc | 40 mVrms | 89% |
| TS40-1875 | 40 Vdc | 1875 Adc | 40 mVrms | 89% |
| TS50-1500 | 50 Vdc | 1500 Adc | 50 mVrms | 89% |
| TS60-1248 | 60 Vdc | 1248 Adc | 60 mVrms | 90% |
| TS80-937.5 | 80 Vdc | 937.5 Adc | 60 mVrms | 90% |
| TS100-750 | 100 Vdc | 750 Adc | 60 mVrms | 90% |
| TS125-600 | 125 Vdc | 600 Adc | 100 mVrms | 90% |
| TS160-468 | 160 Vdc | 468 Adc | 120 mVrms | 90% |
| TS200-375 | 200 Vdc | 375 Adc | 125 mVrms | 91% |
| TS250-300 | 250 Vdc | 300 Adc | 130 mVrms | 91% |
| TS300-249.9 | 300 Vdc | 249.9 Adc | 160 mVrms | 91% |
| TS375-199.8 | 375 Vdc | 199.8 Adc | 170 mVrms | 92% |
| TS400-187.2 | 400 Vdc | 187.2 Adc | 180 mVrms | 92% |
| TS500-150 | 500 Vdc | 150 Adc | 220 mVrms | 92% |
| TS600-124.8 | 600 Vdc | 124.8 Adc | 250 mVrms | 92% |
| TS800-93.6 | 800 Vdc | 93.6 Adc | 300 mVrms | 92% |
| TS1000-75 | 1000 Vdc | 75 Adc | 350 mVrms | 92% |
| TS1250-60 | 1250 Vdc | 60 Adc | 375 mVrms | 92% |
| TS1500-49.8 | 1500 Vdc | 49.8 Adc | 400 mVrms | 92% |
| TS2000-37.5 | 2000 Vdc | 37.5 Adc | 600 mVrms | 92% |
| TS3000-24.9 | 3000 Vdc | 24.9 Adc | 650 mVrms | 92% |
| TS4000-18.6 | 4000 Vdc | 18.6 Adc | 700 mVrms | 92% |
| TS5000-15 | 5000 Vdc | 15 Adc | 1500 mVrms | 92% |
| TS6000-12.3 | 6000 Vdc | 12.3 Adc | 1700 mVrms | 92% |

2.2.11 100 kW TS Series Models

| Model | Maximum Voltage | Maximum Current | Ripple | Efficiency |
|-------------|-----------------|-----------------|------------|------------|
| TS10-8000 | 10 Vdc | 8000 Adc | 40 mVrms | 87% |
| TS20-5000 | 20 Vdc | 5000 Adc | 40 mVrms | 88% |
| TS25-4000 | 25 Vdc | 4000 Adc | 40 mVrms | 89% |
| TS32-3124 | 32 Vdc | 3124 Adc | 40 mVrms | 89% |
| TS40-2500 | 40 Vdc | 2500 Adc | 40 mVrms | 89% |
| TS50-2000 | 50 Vdc | 2000 Adc | 50 mVrms | 89% |
| TS60-1664 | 60 Vdc | 1664 Adc | 60 mVrms | 90% |
| TS80-1250 | 80 Vdc | 1250 Adc | 60 mVrms | 90% |
| TS100-1000 | 100 Vdc | 1000 Adc | 60 mVrms | 90% |
| TS125-800 | 125 Vdc | 800 Adc | 100 mVrms | 90% |
| TS160-624 | 160 Vdc | 624 Adc | 120 mVrms | 90% |
| TS200-500 | 200 Vdc | 500 Adc | 125 mVrms | 91% |
| TS250-400 | 250 Vdc | 400 Adc | 130 mVrms | 91% |
| TS300-333.2 | 300 Vdc | 333.2 Adc | 160 mVrms | 91% |
| TS375-266.4 | 375 Vdc | 266.4 Adc | 170 mVrms | 92% |
| TS400-249.6 | 400 Vdc | 249.6 Adc | 180 mVrms | 92% |
| TS500-200 | 500 Vdc | 200 Adc | 220 mVrms | 92% |
| TS600-166.4 | 600 Vdc | 166.4 Adc | 250 mVrms | 92% |
| TS800-124.8 | 800 Vdc | 124.8 Adc | 300 mVrms | 92% |
| TS1000-100 | 1000 Vdc | 100 Adc | 350 mVrms | 92% |
| TS1250-80 | 1250 Vdc | 80 Adc | 375 mVrms | 92% |
| TS1500-66.4 | 1500 Vdc | 66.4 Adc | 400 mVrms | 92% |
| TS2000-50 | 2000 Vdc | 50 Adc | 600 mVrms | 92% |
| TS3000-33.2 | 3000 Vdc | 33.2 Adc | 650 mVrms | 92% |
| TS4000-24.8 | 4000 Vdc | 24.8 Adc | 700 mVrms | 92% |
| TS5000-20 | 5000 Vdc | 20 Adc | 1500 mVrms | 92% |
| TS6000-16.4 | 6000 Vdc | 16.4 Adc | 1700 mVrms | 92% |

2.2.12 Low Voltage, High Current TS Series Models

| Model | Maximum Voltage | Maximum Current | Ripple | Efficiency | Size |
|------------|-----------------|-----------------|----------|------------|------|
| TSD5-1800 | 5 Vdc | 1800 Adc | 50 mVrms | 85% | 6U |
| TSD5-2700 | 5 Vdc | 2700 Adc | 50 mVrms | 85% | 9U |
| TSD10-2700 | 10 Vdc | 2700 Adc | 50 mVrms | 85% | 9U |

2.3 Specifications

2.3.1 AC Input Specifications

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| 1Φ AC Input Voltage 1Φ , 2-wire + ground Available on 5 kW models | 208 Vac (208SP: operating range 187-229 Vac) 240 Vac (240SP; operating range 216-264 Vac) |
|---|---|
| 3Ф AC Input Voltage 3Ф, 3-wire + ground | 208 Vac (operating range 187 to 229 Vac) 240 Vac (operating range 216 to 264 Vac) 380/400 Vac (operating range 342 to 440 Vac) 415 Vac (operating range 373 to 456 Vac) 440 Vac (operating range 396 to 484 Vac) 480 Vac (operating range 432 to 528 Vac) |
| AC Input Current | Refer to installation-input-current |
| AC Input Frequency | 50-400 Hz |
| Power Factor | >0.92 at max power; models with 3Φ AC input >0.70 at max power; models with 1Φ AC input |
| AC Input Isolation | ± 2500 Vac, maximum input voltage to ground |

2.3.2 Output Specifications

| Voltage Ripple | Refer to chart of available models. |
|---------------------------|---|
| Line Regulation | |
| | Voltage mode: $\pm0.004\%$ of full scale |
| | Current mode: \pm 0.02% of full scale |
| | |
| Load Regulation | |
| | Voltage mode: $\pm0.01\%$ of full scale |
| | Current mode: $\pm 0.04\%$ of full scale |
| | |
| Load Transient Response | 2 ms to recover within $\pm 1\%$ of regulated output with a 50% to 100% or 100% |
| _ | to 50% step load change |
| Stability | $\pm0.10\%$ for 8 hrs. after 30 min. warm-up |
| Efficiency | 85% to 95%; refer to chart of available models |
| | $\pm 1000 \mathrm{Vdc}$ max output voltage to ground |
| DC Output Isolation | |
| Models Rated 1000 Vdc | |
| | |
| | \pm (2000 Vdc + Vo/2), max output voltage to ground, where Vo is the max |
| DC Output Isolation | rated voltage |
| Models Rated >1000 Vdc or | |
| Models with +ISO Option | |
| x | |
| | |

2.3.3 Programming Specifications

| Programming Accuracy | Voltage: $\pm 0.075\%$ of max voltage rating Current: $\pm 0.075\%$ of max current rating |
|---|--|
| Measurement Accuracy | Voltage: $\pm 0.2\%$ of max voltage rating Current: $\pm 0.2\%$ of max current rating |
| Maximum Slew Rate Standard Models | 100 ms, output voltage change from 0 to 63% 100 ms, output current change from 0 to 63% |
| Maximum Slew Rate Models with High Slew Rate Option (+HS) | 4 ms, output voltage change from 0 to 63% 8 ms, output current change from 0 to 63% |
| Trip Settings Range | Over Voltage: 10% to 110% max voltage rating Over Current: 10% to 110% max current rating |
| Computer Command Protocol Remote Sense Limits Wired | Standard Commands for Programmable Instruments (SCPI) 3% maximum voltage drop from output to load |

2.3.4 Connectivity Specifications

| Communication Interfaces (Stan- | |
|---------------------------------|----------------------------------|
| dard) | RS232: DB-9, Female |
| | External User I/O: DB-37, Female |
| | |
| Communication Interfaces (Op- | |
| tional) | LXI TCP/IP Ethernet: RJ-45 |
| | GPIB: IEEE-488 |
| | |

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2.3.5 External User I/O Specifications

| Digital Inputs | 5 V, 10 k impedance |
|------------------------------|----------------------------------|
| Digital Monitoring Signals | 5 V, 5 mA capacity |
| Digital Reference Signal | 5 V output, 25 mA capacity |
| Analog Programming Input | 0-10 V |
| Analog Programming Impedance | 10 k |
| Analog Monitoring Signals | 0-10 V, 5 mA capacity |
| Analog Monitoring Impedance | 100 |
| Analog Monitoring Accuracy | 0.2% of max rating |
| Analog Reference Signal | 10 V, 5 mA capacity, 1 impedance |

For more details about the External User I/O, see: Operation: External User I/O.

2.3.6 Physical Specifications

| Power Level | Rack Units | Size | Weight |
|--|------------|--|--------------------|
| 5 kW | 3U | 5.25" H x 19" W x 24" D (13.34 x 48.26 x 60.96 cm) | 74 lbs (34.57 kg) |
| 10 kW | 3U | 5.25" H x 19" W x 24" D (13.34 x 48.26 x 60.96 cm) | 94 lbs (42.64 kg) |
| 15 kW | 3U | 5.25" H x 19" W x 24" D (13.34 x 48.26 x 60.96 cm) | 125 lbs (56.70 kg) |
| 20 kW Models with 380/415 Vac and 440/480 Vac, 3Φ input | 4U | 7" H x 19" W x 24" D (17.8 x 48.2 x 60.9 cm) | 160 lbs (72.6 kg) |
| 20 kW Models with 208/240 Vac, 3Φ input | 6U | 10.5" H x 19" W x 24" D (26.67 x 48.26 x 60.96 cm) | 185 lbs (83.9 kg) |
| 25 kW Models with 380/415 Vac and 440/480 Vac, 3Φ input | 4U | 7" H x 19" W x 24" D (17.8 x 48.2 x 60.9 cm) | 180 lbs (81.7 kg) |

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Table 2.6 – continued from previous page

| Power Level | Rack Units | Size | Weight |
|--------------------------|------------|---------------------------|---------------------|
| | 6U | | 220 lbs (99.79 kg) |
| 25 kW | | 10.5" H x 19" W x 24" D | |
| Models with 208/240 Vac, | | (26.67 x 48.26 x 60.96 | |
| 3⊕ input | | cm) | |
| | | | |
| 30 kW | 6U | | 245 lbs (111.13 kg) |
| | | 10.5" H x 19" W x 24" D | |
| | | (26.67 x 48.26 x 60.96 | |
| | | cm) | |
| 40.1337 | OXI | | 217 11 (142.01) |
| 40 kW | 8U | With and an annual | 315 lbs (142.9 kg) |
| | | With casters removed: | |
| | | 14" H x 19" W x 24" D | |
| | | (35.6 x 48.2 x 60.9 cm) | |
| | | | |
| | | With casters attached: | |
| | | 17.75" H x 19" W x 24" | |
| | | D | |
| | | (45.1 x 48.2 x 60.9 cm) | |
| 50 kW | 8U | | 355 lbs (161.0 kg) |
| JU KVV | 80 | With casters removed: | 333 lbs (101.0 kg) |
| | | 14" H x 19" W x 24" D | |
| | | (35.6 x 48.2 x 60.9 cm) | |
| | | (33.0 x 46.2 x 00.9 cm) | |
| | | With casters attached: | |
| | | 17.75" H x 19" W x 24" | |
| | | D 17.73 H X 19 W X 24 | |
| | | (45.1 x 48.2 x 60.9 cm) | |
| | | (43.1 x 48.2 x 00.9 cm) | |
| 75 kW | 12U | | 540 lbs (244.9 kg) |
| | | With casters removed: | |
| | | 21" H x 19" W x 24" D | |
| | | (53.3 x 48.2 x 60.9 cm) | |
| | | (200 H 1012 H 0015 CHI) | |
| | | With casters attached: | |
| | | 24.75" H x 19" W x 24" | |
| | | D 24.73 11 x 19 W x 24 | |
| | | (62.9 x 48.2 x 60.9 cm) | |
| | | (02.) A TO.2 A OU.) CIII) | |
| | | | |

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Table 2.6 – continued from previous page

| Power Level | Rack Units | Size | Weight |
|-------------|------------|--|--------------------|
| 100 kW | 16U | | 725 lbs (328.9 kg) |
| | | With casters removed: | |
| | | 28" H x 19" W x 24" D | |
| | | (71.1 x 48.2 x 60.9 cm) | |
| | | With casters attached: 31.75" H x 19" W x 24" D (80.7 x 48.2 x 60.9 cm) | |
| | | | |

2.3.7 Environmental Specifications

| Ambient Operating Temperature | 0°C to 50°C |
|-------------------------------|---|
| Storage Temperature | -25°C to +85°C |
| Humidity | Relative humidity up to 95% non-condensing |
| | Side air inlet, rear exhaust |
| Air Cooling | |
| Standard | |
| 3U and 6U models | |
| | |
| | Front and side air inlet, rear exhaust |
| Air Cooling | |
| Standard | |
| 4U and 8U models | |
| | |
| W. C. P | 2500 |
| Water Cooling | 25°C maximum inlet temperature |
| With +WC Option | 1.5 GPM minimum flow rate for 5-15 kW units |
| | 3.0 GPM minimum flow rate for 20-30 kW units |
| | 4.5 GPM minimum flow rate for 40-100 kW units |
| | 80 PSI maximum pressure |
| | 1/4" NPT female pipe size |
| Temperature Coefficient | |
| | 0.04%/°C of maximum output voltage |
| | 0.06%/°C of maximum output current |
| | |

2.3.8 Regulatory Compliance

| EMC | Complies with 2014/30/EU (EMC Directive) CISPR 22 / EN 55022 Class A |
|----------------|--|
| Safety | Complies with EN61010-1 and 2014/35/EU (Low Voltage Directive) |
| CE Mark | Yes |
| RoHS Compliant | Yes |

2.4 Dimensional Diagrams

2.4.1 TS Series - 3U Models

2.4.2 TS Series - 4U Models

2.4.3 TS Series - 6U Models

2.4.4 TS Series - 8U Models

2.4.5 TS Series - 12U Models

2.4.6 TS Series - 16U Models

2.5 Principle of Operation

This section provides a general overview of the technology and power processing stages in the TS Series MagnaDC power supply. fig-block-diagram and fig-block-diagram2 provides an visual overview of the power supply's main power and control stages. As illustrated, TS Series MagnaDC power supply are comprised of either master or master/slave modules. Master and slave modules have a power ratings of 5 kW, 10 kW, 15 kW, 20 kW (4U), or 25 kW (4U). One module is required for 5 kW to 15 kW models, and one module is required for 20 kW to 25 kW 4U models with 380/415 Vac and 440/480 Vac 3-phase input. Two modules are required for 20 kW to 25 kW models with 208/240 Vac 3-phase input, as well as for 30 kW to 50 kW models. Three modules are required for 75 kW models and four modules are required for 100 kW models. TS Series MagnaDC power supply have a number of shared feedback loops to ensure balance between modules. The details of the modules are described below.

2.5.1 Master Module

Power is fed through AC fuses and is distributed to the driver board, inrush limiter, and main 3 contactor. The driver board contains a switching power supply and supplies power to the other printed circuit boards in the system. The inrush limiter is a step start device which is used to initially charge capacitors on the input DC bus and limit the inrush of current. The inrush limiter is initiated when the power supply is switched from a standby to a power state. After the charge cycle, the main 3 contactor is energized and power is allowed to flow to the load. The optional EMI filter filters common mode and differential mode noise emanating from the supply.

Output power is controlled through a polyphase chopper. For the 15 kW master module, three choppers, phased 120° apart, provide a current source to a current fed inverter. The 10 kW TS uses two choppers, phased 180° apart, and the 5 kW supply uses only one chopper. The choppers are controlled with current mode, pulse width modulation (PWM).

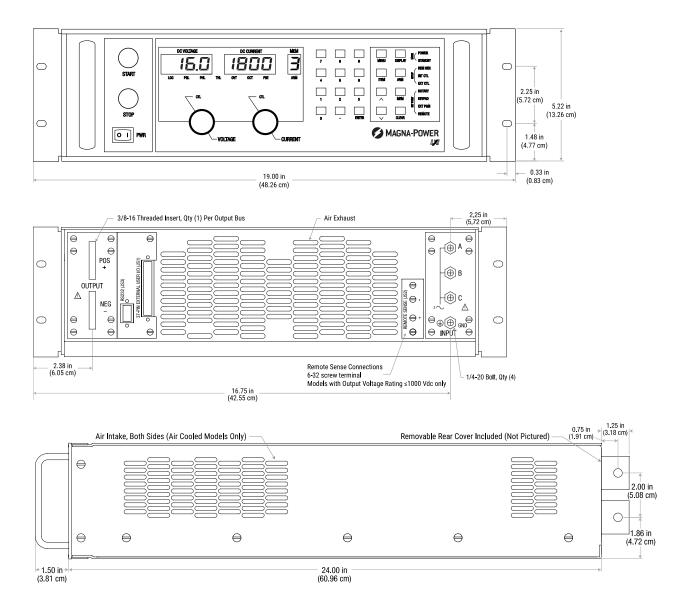


Fig. 2.2: TS Series 3U models front panel, rear panel, and side panel (top to bottom).

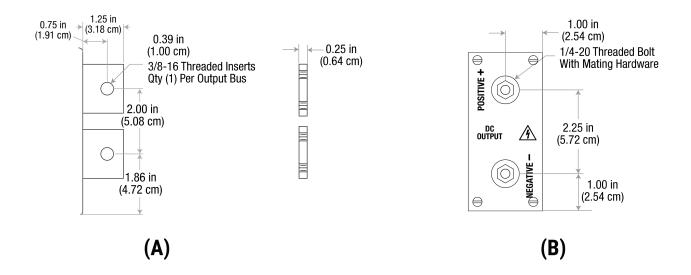


Fig. 2.3: TS Series 3U output bus configurations. (A) 6U models, rated 1000 Vdc and below; (B) 6U models, rated above 1000 Vdc or with High Isolation Output Option (+ISO).

This modulation scheme provides a quick response for transients and filtering harmonics on the DC bus. As illustrated, chopper output current is monitored for balancing and for sensing overload current conditions. The polyphase chopper has been engineered to eliminate harmonic components minimizing currents circulating in the power supply.

The polyphase chopper produces a controlled DC bus which is connected to DC link inductors and current fed, IGBT medium frequency link inverter. The inverter, which operates at 400 Hz to 600 Hz, excites the main transformer at higher than normal line frequencies. This operation produces ohmic isolation between the input and output of the power supply using a transformer of dramatically reduced size.

The inverter operates with a 50% duty cycle and its frequency of operation is transparent to the performance of the power supply.

The output of the main power transformer is converted to DC via rectifiers. Low voltage versions of the TS Series power supply use midpoint diode configurations and higher voltage versions use bridge configurations.

The DC output voltage is filtered with a pie section filter. This, in combination with the DC link inductors, form a double stage inductive capacitive (LC) filter.

The gate driver board supports a synchronized modulation scheme which integrates power semiconductor switching of the switching power supply, polyphase chopper, and medium frequency link inverter.

The fuse/phase detector senses input line voltage on each phase and continuity of each fuse. Upon detection of a problem, the control board is signaled to shutdown the system. The control board, which is referenced to earth ground, contains optically isolated amplifiers to sense output voltage and current. This circuitry allows the output to be referenced ± 1000 Vdc above earth ground.

The display board contains light-emitting diodes for displaying diagnostic conditions and provides an interface for meters and switches.

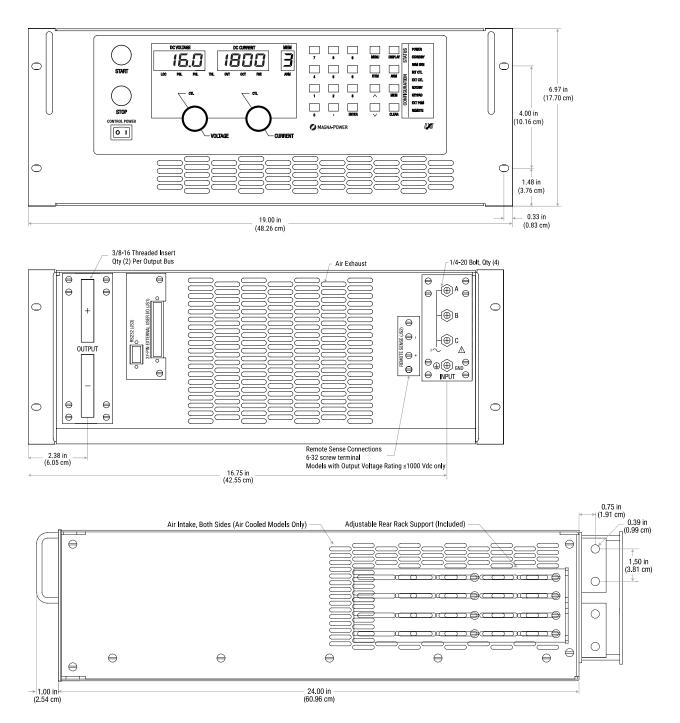


Fig. 2.4: TS Series 4U models front panel, rear panel, and side panel (top to bottom).

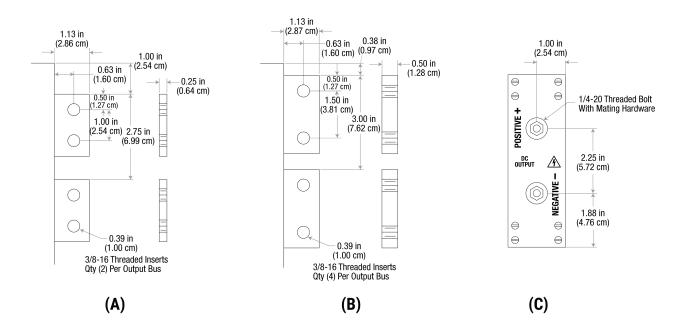


Fig. 2.5: TS Series 4U output bus configurations. (A) 4U models, rated below 125 Vdc; (B) 4U models, rated 125 Vdc to 1000 Vdc; (C) 4U models, rated above 1000 Vdc or with High Isolation Output Option (+ISO).

2.5.2 Slave Module

The slave module is very similar to the master module. Like the master module, output power is controlled through a polyphase chopper. For the 15 kW, 20 kW, and 25 kW slave modules, three choppers, phased 120° apart, provide a current source to the current fed inverter. The 10 kW TS power supply uses two choppers, phased 180° apart, and the 5 kW supply uses only one chopper.

The choppers are controlled with current mode, pulse width modulation (PWM) from signals derived from the master module gate driver board. The second set of chopper signals are displaced 60° from the first set of chopper signals in the master module. Together, 30 kW, 40 kW, 50 kW, 75 kW, and 100 kW models have six chopper modules phased 60° apart. The current fed inverter in the slave module uses the same driver signals as the master module.

The slave module's diagnostic features are coordinated with the master module to provide high performance with virtually any combination of modules. Balance between chopper currents is insured by independent sampling and feedback control. Power supply, chopper, and inverter modules are synchronized to avoid instabilities at different operating points.

2.6 Options

2.6.1 Blocking Diode (+BD)

The integrated Blocking Diode (+BD) option provides an internally heat-sunk protection diode on the positive output terminal of a MagnaDC programmable DC power supply. This diode protects the product's output from reverse voltage up to 1200 Vdc. All voltage sensing is performed after the protection diode—at the product's output terminals—making the diode's operation completely transparent to the performance of the power supply.

The +BD option is recommended for applications where there is significant back-emf or the possibility of a DC output voltage that could exceed the power supply's output voltage rating, such as:

· DC motor drives

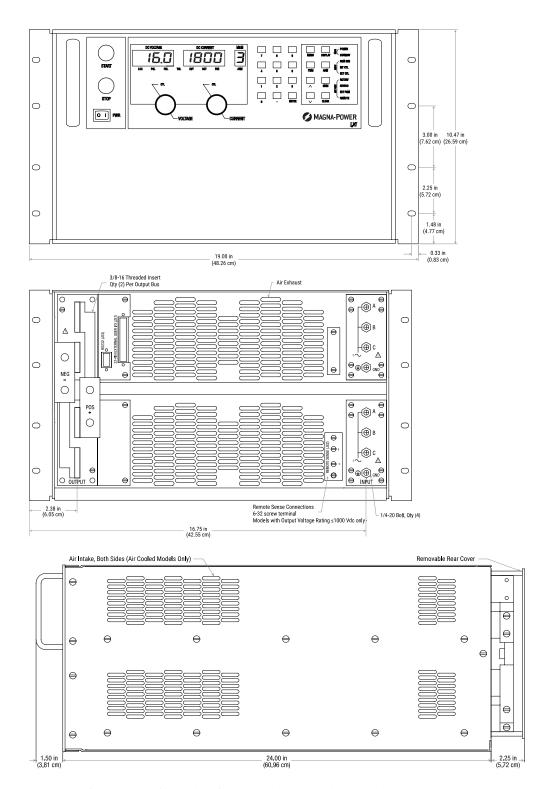


Fig. 2.6: TS Series 6U models front panel, rear panel, and side panel (top to bottom).

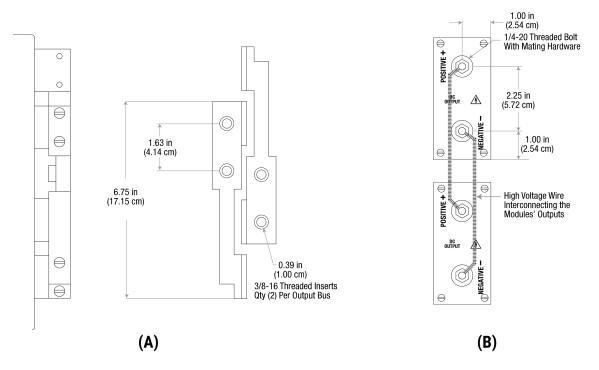


Fig. 2.7: TS Series 6U output bus configurations. (A) 6U models, rated 1000 Vdc and below; (B) 6U models, rated above 1000 Vdc or with High Isolation Output Option (+ISO).

- · Battery and capacitor charging
- Large electromagnets

In these applications, the integrated blocking diode can be used to prevent back-emf from the energy stored in the load into the power supply's output. Furthermore, the integrated blocking diode will prevent the power supply's internal bleed resistance from discharging the energy storaged in the load when the power supply is off or in standby.

Availability

The +BD option is available for models with maximum output voltage rating as specified for the following product series:

- TS Series, models rated from 100 Vdc to 1000 Vdc
- MS Series, models rated from 100 Vdc to 1000 Vdc
- MT Series, models rated from 125 Vdc to 1000 Vdc

Note: The +BD option cannot be combined with the +ISO option.

Table 2.9: Additional specifications for Blocking Diode (+BD) option

| Reverse Voltage Rating | 1200 Vdc |
|------------------------|------------|
| Additional Losses | Up to 1.4% |

2.6.2 High Isolation Output (+ISO)

Certain applications require floating the output voltage to values beyond the power supply isolation rating. Magna-Power's High Isolation Output Option (+ISO) enables a TS Series, MS Series or MT Series model with a peak output voltage rating of 250 Vdc through 1000 Vdc to be rated for a higher voltage output isolation. Improved **Exist Options** is a novel output stage with improved controller isolation. In addition to being able to float the power supply to a higher output voltage, this option also enables lower voltage units to be tied together in series up to its new higher isolation rating, in accordance with the table in the Specifications section below.

Availability

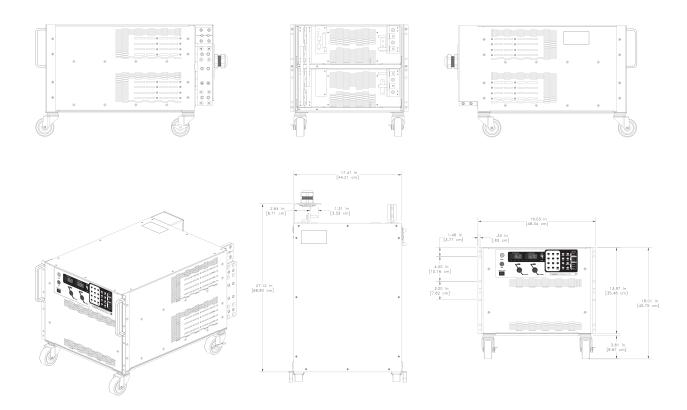


Fig. 2.8: TS Series 8U models front panel, rear panel, and side panel (top to bottom).

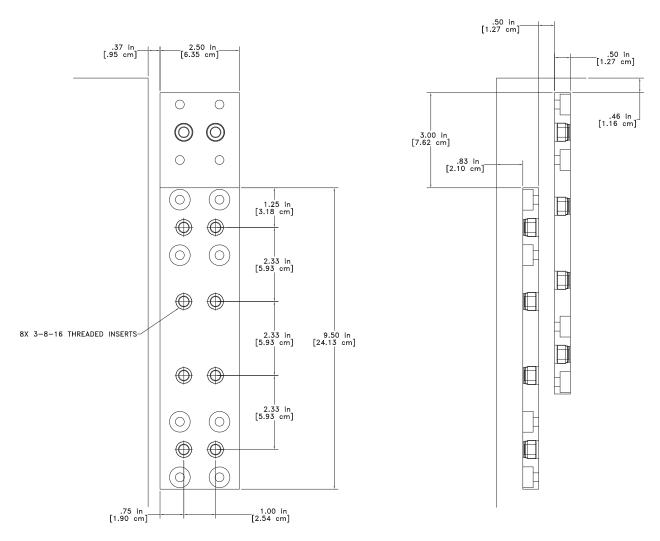


Fig. 2.9: TS Series 8U output bus configurations for models rated below 125 Vdc.

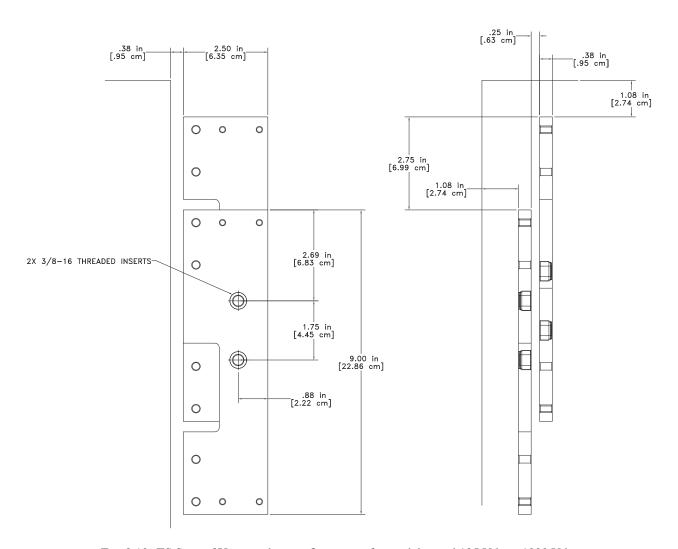


Fig. 2.10: TS Series 8U output bus configurations for models rated 125 Vdc to 1000 Vdc.

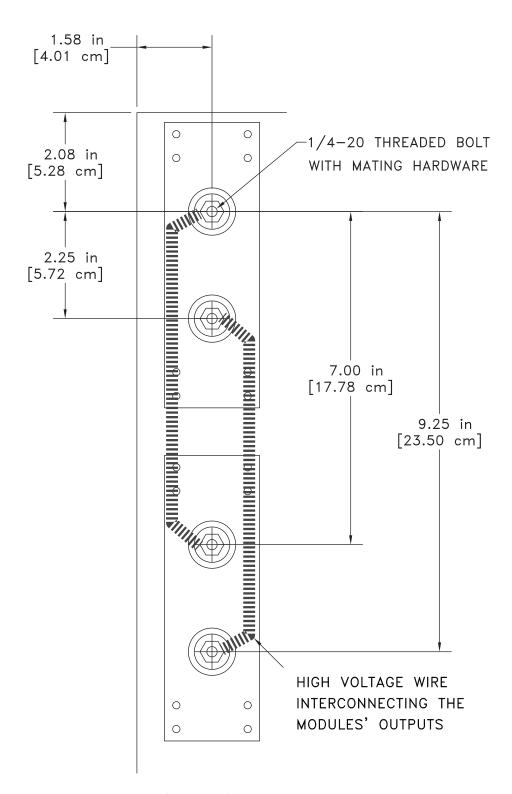


Fig. 2.11: TS Series 8U output bus configurations for models rated above 1000 Vdc or with High Isolation Output Option (+ISO)

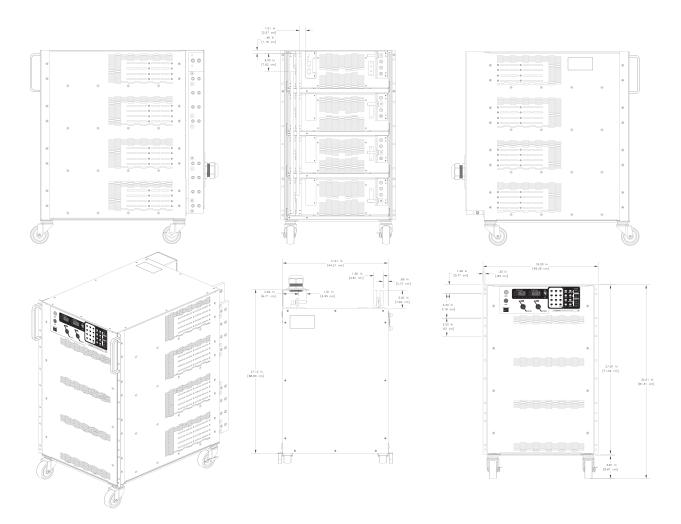


Fig. 2.12: TS Series 12U models front panel, rear panel, and side panel (top to bottom).

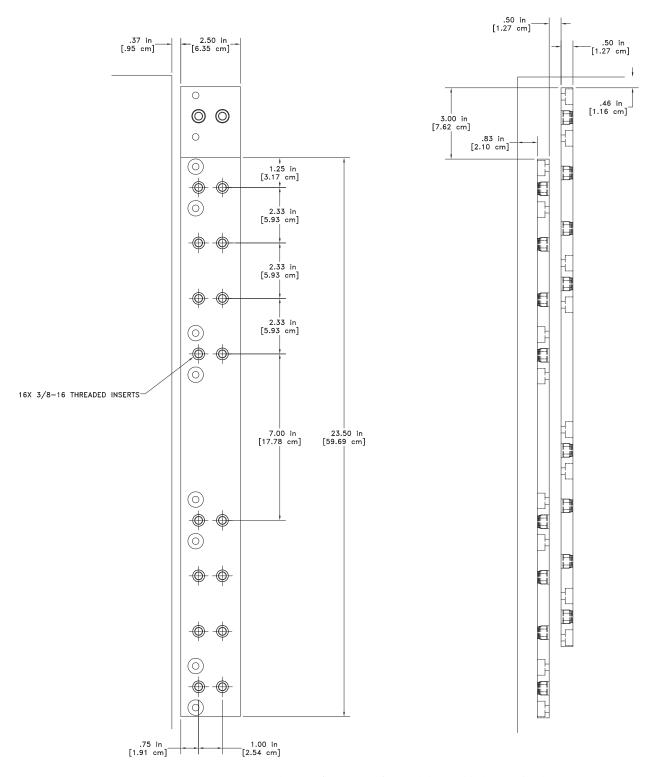


Fig. 2.13: TS Series 12U output bus configurations for models rated below 125 Vdc.

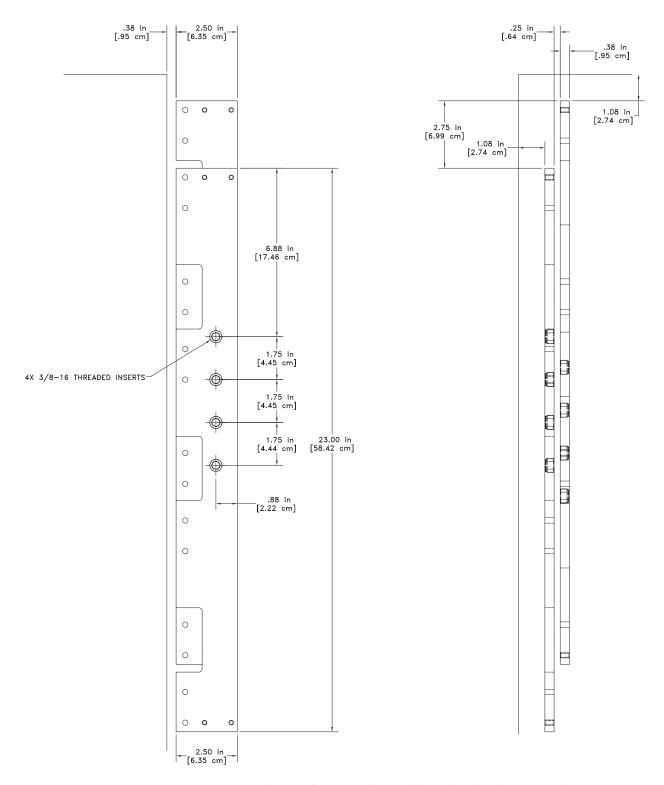


Fig. 2.14: TS Series 12U output bus configurations for models rated 125 Vdc to 1000 Vdc.

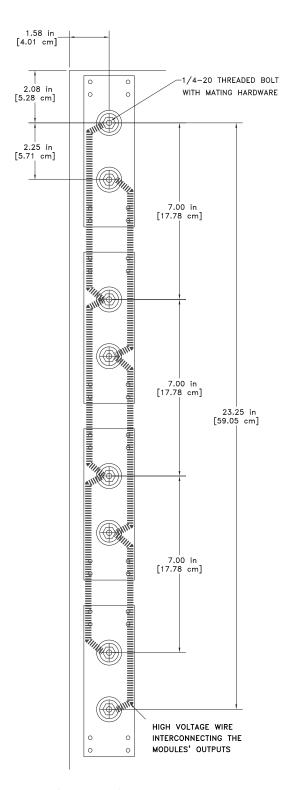


Fig. 2.15: TS Series 12U output bus configurations for models rated above 1000 Vdc or with High Isolation Output Option (+ISO)

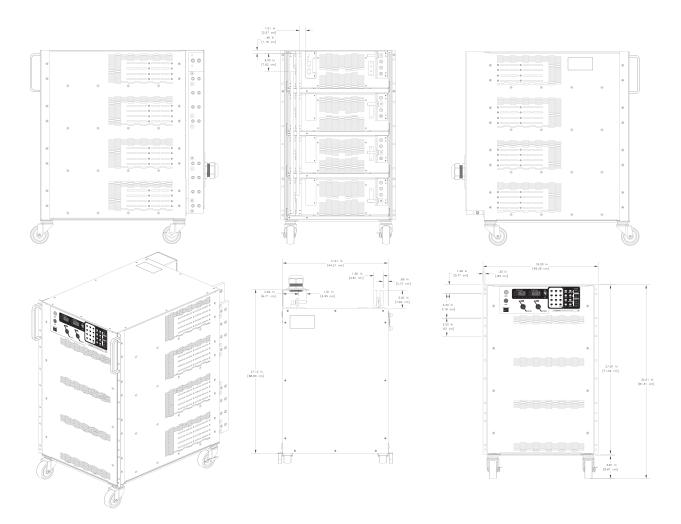


Fig. 2.16: TS Series 16U models front panel, rear panel, and side panel (top to bottom).

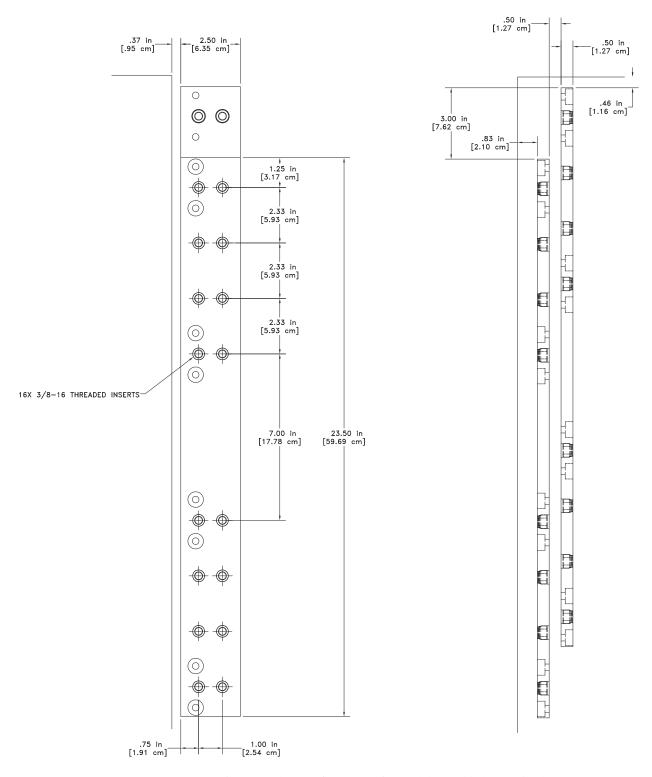


Fig. 2.17: TS Series 16U output bus configurations for models rated below 125 Vdc.

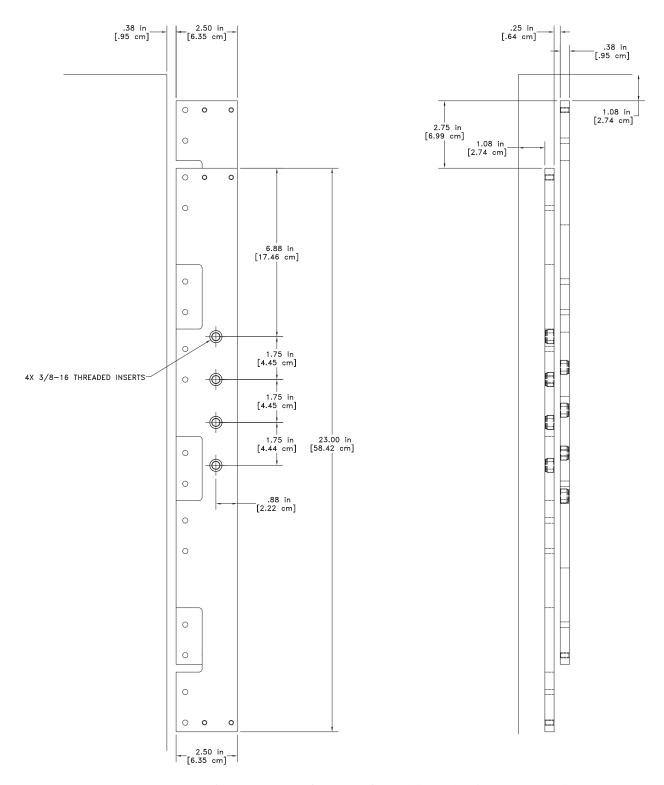


Fig. 2.18: TS Series 16U output bus configurations for models rated 125 Vdc to 1000 Vdc.

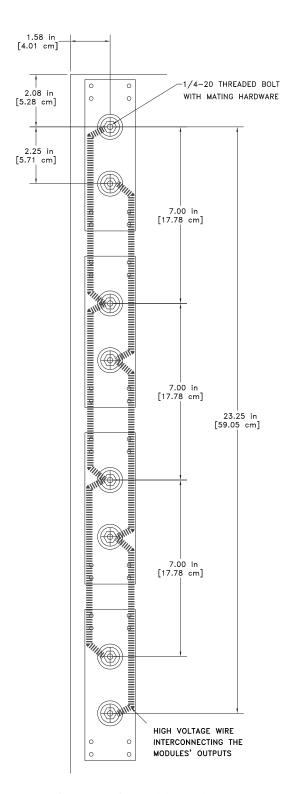


Fig. 2.19: TS Series 16U output bus configurations for models rated above 1000 Vdc or with High Isolation Output Option (+ISO)

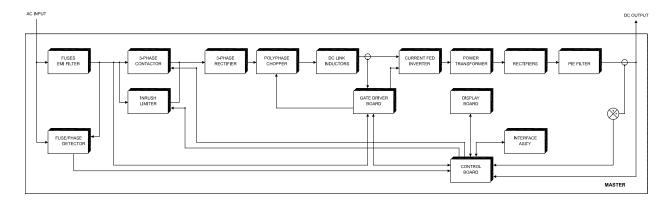


Fig. 2.20: TS Series MagnaDC power supply functional block diagram for 5 kW to 15 kW models, and 20 kW to 25 kW 4U models with 380/415 Vac and 440/480 Vac 3-phase input

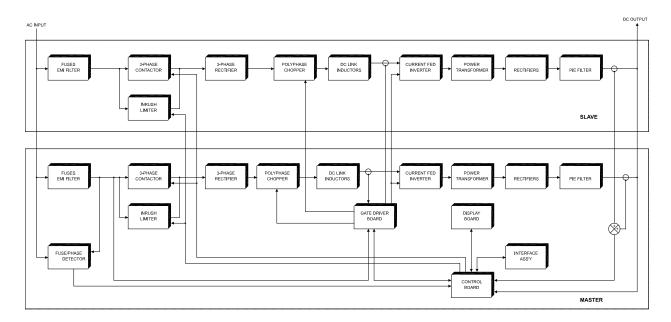


Fig. 2.21: TS Series MagnaDC power supply functional block diagram for 20~kW to 25~kW 6U models with 208/240~kW vac 3-phase input, as well as for 30~kW to 100~kW models

| Product Series | Output Isolation Standard, No Option | Output Isolation for Models Rated 250-1000 Vdc With +ISO Option | Output Isolation for Models Rated Above 1000 Vdc; Standard, No Option Necessary |
|----------------|--|--|---|
| SL Series | ±1000 Vdc | N/A | N/A |
| XR Series | ±1000 Vdc | N/A | $\pm (2000 \text{ Vdc} + \text{Vo/2})$ |
| TS Series | ±1000 Vdc | $\pm (2000 \text{ Vdc} + \text{Vo/2})$ | $\pm (2000 \text{ Vdc} + \text{Vo/2})$ |
| MS Series | ±1000 Vdc | $\pm (2000 \text{ Vdc} + \text{Vo/2})$ | $\pm (2000 \text{ Vdc} + \text{Vo/2})$ |
| MT Series | ±1000 Vdc | ±4000 Vdc | ±4000 Vdc |

Table 2.10: Option isolation rating for various configurations

2.6.3 High Slew Rate Output (+HS)

The High Slew Rate Output (+HS) solves several limitations inherent in switching power supply design. Rapid voltage transitions require internal electronics to supply the energy to charge and discharge output capacitors. Peak currents internal to the power supply define slew rate; utilizing less capacitance enables voltage transitions in shorter time periods. Additionally, less capacitance reduces requirements for discharge demands during open circuit conditions.

The standard output stage Magna-Power Electronics power supplies has been designed to provide the lowest possible output ripple voltage within the constraints of available components, size, and cost. Part of the output stage consists of a bank of aluminum electrolytic capacitors which has the desired electrical properties to provide this function. These components require bleed resistors to discharge any voltage when the power supply has no load and is disabled. While the presence of these components and the resulting performance are normally industry accepted, there are applications where lower output capacitance and lower loss bleed resistors are extremely desirable and higher ripple voltage is acceptable. To meet this need, a high-slew rate option is available which has an output stage consisting of low capacitance film and aluminum electrolytic capacitors and lower loss bleed resistors. Applications for the high-slew rate option include battery charging, photovoltaic emulation, power waveform generation, and medium speed power pulsing. These applications all benefit from higher bandwidth and in many cases, can tolerate increased ripple voltage.

Key Applications

For battery charger applications, output capacitance and internal bleed resistors present themselves as a load to the connecting batteries. One common practice is to use a series diode to block reverse current flow with the sacrifice of increased cost and lower efficiency. The high slew rate option, with its lower output capacitance and lower loss bleed resistors, enables direct connection to batteries without series blocking diodes.

For photovoltaic emulation applications, higher bandwidth and lower output capacitance enable improved performance with higher speed, maximum power tracker algorithms. Maximum power tracker circuitry deviates the operating point of photovoltaic arrays to determine maximum power output. Slow responding emulation sources can present a problem when the speed of the algorithm exceeds that of the source. Furthermore, with lower output capacitance, changes in the operating point and transients, caused by shorting the solar inverter input, produce lower unwanted input currents.

The high-slew rate option enables the power supply to operate as a low frequency, power pulse generator. With the special capacitors selected for this option, it is possible to superimpose waveforms or produce a medium speed pulse on top of the dc output and expect normal capacitor life. It is important to note that the power supply output is single quadrant; that is, the output voltage or current cannot reverse.

Availability

The +HS option is available for the following product series: * SL Series * XR Series * TS Series * MS Series * MT Series

Note: XR Series models greater than 2000 Vdc already include a high slew rate output stage and no additional +HS option is available for these models.

Table 2.11: Additional specifications for High Slew Rate Output (+HS) option

| Max Voltage Rat- | | | | Ripple (Vrms) |
|------------------|----------------|----------------|--------------------------|---------------|
| ing | Output | Output | Output | |
| | Capacitance | Capacitance | Capacitance | |
| | SL Series (ţF) | XR Series (ţF) | TS Series and MS | |
| | | | Series (ţF) ¹ | |
| | | | | |
| 5 | 4235 | 13200 | 13200 | 0.5 |
| 8 | N/A | N/A | 9000 | 0.5 |
| 10 | 1740 | 4080 | 9000 | 0.5 |
| 16 | 1740 | 4080 | 4080 | 0.5 |
| 20 | 775 | 2340 | 2340 | 0.7 |
| 25 | 775 | 1170 | 2340 | 0.7 |
| 32 | 775 | 1170 | 1170 | 1.4 |
| 40 | 760 | 240 | 1170 | 1.5 |
| 50 | 760 | 240 | 1170 | 1.5 |
| 60 | 760 | 240 | 300 | 1.5 |
| 80 | 110 | 240 | 300 | 1.5 |
| 100 | 110 | 160 | 200 | 1.6 |
| 125 | 70 | 160 | 200 | 1.6 |
| 160 | 70 | 160 | 200 | 1.6 |
| 200 | 70 | 160 | 200 | 1.6 |
| 250 | 70 | 160 | 200 | 1.6 |
| 300 | 70 | 160 | 200 | 1.8 |
| 375 | 70 | 160 | 200 | 1.8 |
| 400 | 70 | 160 | 200 | 1.8 |
| 500 | 40 | 56 | 200 | 2.1 |
| 600 | 40 | 56 | 120 | 2.3 |
| 800 | 30 | 52 | 70 | 2.5 |
| 1000 | 30 | 52 | 60 | 3.0 |
| 1250 | N/A | 18 | 18 | 3.5 |
| 1500 | N/A | 18 | 18 | 3.5 |
| 2000 | N/A | 18 | 18 | 3.5 |
| 3000 | N/A | N/A | 9 | 4.0 |
| 4000 | N/A | N/A | 9 | 4.0 |
| 6000-10000 | N/A | N/A | N/A | N/A |

¹ For 20 to 30 kW models, multiply capacitance by 2; 45 kW models, multiply capacitance by 3; 60 kW models, multiply capacitance by 4; 75 kW models, multiply capacitance by 5; TS Series 4U/8U models and MT Series models, please contact Magna-Power support.

2.6.4 IEEE-488 GPIB (+GPIB)

The IEEE-488 GPIB (+GPIB) option, sometimes called the General Purpose Interface Bus (GPIB), is a general purpose digital interface system that can be used to transfer data between two or more devices. It is particularly well-suited for interconnecting computers and instruments. Some of its key features are:

- Up to 15 devices may be connected to one bus
- Total bus length may be up to 20 m and the distance between devices may be up to 2 m
- Communication is digital and messages are sent one byte (8 bits) at a time
- · Message transactions are hardware handshaked
- Data rates may be up to 1 Mbyte/sec

The IEEE-488 GPIB interface in integrated with the power supply's rear communication ports. The IEEE 488 interface offers full compatibility with Magna-Power provided drivers, software and SCPI command set.

Availability

The +GPIB option is available for the following product series:

- SL Series
- · XR Series
- TS Series
- · MS Series
- · MT Series

2.6.5 LXI TCP/IP Ethernet (+LXI)

Certified to the LXI Standard (Class C), version 1.4, the LXI TCP/IP Etherent (+LXI) allows the product to be fully controlled over an integrated TCP/IP Ethernet interface. LXI is an instrumentation platform based on industry standard Ethernet technology designed to provide modularity, flexibility, and performance to small- and medium-sized systems. All of the product's standard SCPI commands are supported over the +LXI option, along with all provided software and drivers.

LXI's advantages are exemplified in its compact, flexible package providing high-speed I/O and reliable measurements. The Magna-Power Electronics LXI TCP/IP Ethernet option includes an embedded web-server, allowing web browser power supply control and monitoring from virtually anywhere.

Availability

The +LXI option is available for the following product series:

- SL Series
- · XR Series
- TS Series
- MS Series
- MT Series

2.6.6 Ruggedized (+RUG)

The Ruggedized Option (+RUG) provides additional mechanical security for large power components and sub-assemblies within SL Series and XR Series products.

SL Series and XR Series units with the Ruggedized Option have been independently tested to comply with the following MIL-STD-810G shock and vibration specifications:

- MIL-STD-810G CHG1 Method 516.7 Functional Shock, Procedure I; which subjects the product to 40G, 11 ms terminal saw tooth pulse; three shocks in each direction along three mutually perpendicular axes
- MIL-STD-810G CHG1 Method 514.7 Vibration; which subjects the product to two hours of vibration per axis along three mutually perpendicular axes

All products with the Ruggedized Option maintain ambient operating temperatures from 0° C to 50° C and ambient storage temperatures from -25° C to $+85^{\circ}$ C.

Availability

The +RUG option is available for the following product series:

- SL Series
- · XR Series

2.6.7 Water Cooling (+WC)

The Water Cooling (+WC) option is available for Magna-Power power supplies for use in densely packaged system cabinets, where heat removal by the product's standard air cooling presents a challenge. Water cooling is accomplished with chill plates and an integrated central heat exchanger. The chill plates provides a thermal conduction path for heat sensitive components and the central heat exchanger removes heat from air internal to the enclosure. An internal solenoid valve enables water flow when the chill plate reaches 60°C. Operation of the solenoid prevents internal condensation.

Each 3U and 4U module has a 1/4" NPT male inlet and outlet for water flow. For 6U and 8U, external plumbing interconnects power supply modules, providing a single 1/2" NPT male inlet and outlet. A minimum of 2.50" is recommended behind the enclosure for this hardware and user connections. For systems requiring more than one power supply, plumbing connections must be paralleled; that is, water should not flow from one power supply into another.

When water cooled power supplies are ordered in combination with the Cabinet and Integration accessory, Magna-Power will parallel the water inlet connections and parallel the water outlet connections, providing a single inlet and outlet for the rack.

Availability

The +WC option is available for models with maximum output voltage rating as specified for the following product series:

- TS Series, models rated from 1000 Vdc and below
- MS Series, models rated from 1000 Vdc and below

Note: The +WC option cannot be combined with the +ISO option.

For detailed specifications on the +WC, including flow rate and pressure, please refer to the individual product specifications.

2.7 Accessories

2.7.1 Cabinet and Integration

Cabinet and integration services are offered for the rack-mount programmable DC power supply products. Cabinets are supplied with fans rated to installed products. Key features of the cabinet and integration option are as follows:

- Internally fabricated, heavy duty welded cabinet frames
- Casters installed, including (2) locking casters
- · Special circuitry for product integration with cabinet fans
- · Installation and testing as a complete system

Table 2.12: Specifications for Cabinet and Integration

| Cabinet Item Name | Dimensions | Internal Rack Space |
|-------------------|---------------------------|---------------------|
| CAB1 | | 12U |
| | 31.5" H x 24" W x 31.5" D | |
| | (80.0 x 55.6 x 80.0 cm) | |
| CAB2 | | 24U |
| | 51" H x 24" W x 31.5" D | |
| | (129.5 x 61.0 x 80.0 cm) | |
| CAB3 | | 30U |
| | 67" H x 24" W x 31.5" D | |
| | (170.2 x 61.0 x 80.0 cm) | |
| CAB4 | | 36U |
| | 74" H x 24" W x 31.5" D | |
| | (188.0 x 61.0 x 80.0 cm) | |
| CAB3x2 | | 60U |
| | 67" H x 48" W x 31.5" D | |
| | (170.2 x 122.0 x 80.0 cm) | |
| CAB4x2 | | 72U |
| | 74" H x 48" W x 31.5" D | |
| | (188.0 x 122.0 x 80.0 cm) | |
| | | |

2.7.2 DC Power Cables

Utilizing Magna-Power's internal cable manufacturing operations, custom-made DC power cables are offered as an accessory. The following table identifies the various cables and voltage ratings that are offered:

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| Cable Gauge (AWG) | Voltage Rating (Vdc) | Per Cable Ampacity Rating |
|-------------------|----------------------|---------------------------|
| | | (90°C) |
| 10 | 15000 | 55 |
| 4 | 600 | 100 |
| 4 | 4000 | 100 |
| 1 | 600 | 160 |
| 1 | 4000 | 160 |
| 2/0 | 600 | 223 |
| 2/0 | 4000 | 223 |
| 4/0 | 600 | 310 |
| 4/0 | 4000 | 310 |

Table 2.13: Specifications for Magna-Power DC power cables

Use the following cable configuration guide and the table above to define the appropriate cable for your application and product:

CBL-[Feet]-[Cable Gauge]-[Voltage Rating]-[Termination 1]-[Termination 2]

For example: CBL-10-4/0-600-3/8-3/8; 10-feet, 4/0 cable rated for 600 Vdc terminated with 3/8" lugs on both ends.

Refer to the product diagrams for the respective product series for the DC output bus thread size and number of connection points.

2.7.3 Universal Interface Device (UID47)

Magna-Power Electronics UID47 is a general purpose device for connection to Magna-Power Electronics' power supplies. The device contains the necessary circuitry for configuring power supplies for master/slave parallel or series operation.

Master/slave parallel operation allows two or more power supplies to equally share output current when connected together. Master/slave series operation allows two or more power supplies to equally share output voltage when connected together. In either operation mode, the master unit will command the slave units to the proper voltage and current. Each unit will display its own individual voltage and current. Installation requires setting jumpers, placing included 37-conductor cables between the UID47 and power supplies, and wiring the power supply outputs in either parallel or series.

The UID47 can be used as an interface for connecting control and monitoring lines to external circuitry. It also contains an area on the printed circuit board for interconnecting wires and placing components for specific user applications.

Key features of the UID47 option are as follows:

- Compatible with all Magna-Power Electronics power supplies
- Interface for series and parallel master/slave operation
- User configurable screw terminal connector
- Pad area for custom circuitry
- Qty (2) 6-foot 37-pin shielded cables included

| Connectors | |
|-------------------------------|---|
| | Master 1: DB-37, Female |
| | Master 2: DB-37, Female |
| | Slave: DB-37, Female |
| | User Interface Circuitry: 10-pin plug connector |
| Ambient Operating Temperature | 0°C to 50°C |
| Ambient Operating Temperature | |
| Storage Temperature | -25°C to +85°C |
| Size | |
| | 1.24" H x 7.14" W x 4.01" D |
| | (3.15 x 18.14 x 10.19 cm) |
| Weight | 0.5 lbs (0.23 kg) |

Table 2.14: Specifications for Universal Interface Device 47 (UID47)

For more detailed information about the UID47, refer to its User Manual.

2.7.4 RS485 (Converter)

The industrial RS232 to Addressable RS485 Converter allows non-addressable, "dumb" RS-232 devices to be connected on an addressable RS-485 network. The master node controls all communications to connected devices. By distributing the switching intelligence along the RS-485 network, wiring cost savings are substantial compared to a single switched "star" configuration.

Devices can either be polled by the master node or request access to the bus through a RS-232 handshake line. This provides a versatile system for interconnecting devices that are designed for point to point communications. Because the units communicate using standard RS-485 signals, RS-232 devices can form their own network or be added to an existing system. Up to 32 nodes at up to 4000 feet can be on one bus without a repeater, and the 485DSS's addressing scheme allows up to 256 units on a single network with repeaters.

2.7.5 USB (Converter)

The industrial RS232 to USB Converter offers instant I/O expansion for peripheral device connectivity. An out-of-the-box (external) alternative to PCI cards, Edgeport makes it easy to add serial port to a PC, server or thin client in minutes without opening the chassis, reconfiguring or rebooting the system.

The USB Converter device plugs directly into the back of the power supply, creating a seamless USB interface. Feature-rich design, reliability and unmatched operating system support make Edgeport USB-to-serial converters ideal for mission-critical enterprise applications. USB cable included along with associated drivers on the Magna-Power Electronics software CD.

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CHAPTER

THREE

INSTALLATION

3.1 Inspection

Carefully unpack the TS Series MagnaDC power supply and accessories saving all packing materials and included enclosures. Inspect product for possible shipping damage. Check that there are no broken knobs or connectors, the external surface is not scratched or dented, the meter faces are not damaged, and all controls move freely. Any external damage may be an indication of internal damage. If there is any damage, notify the shipping carrier and Magna-Power immediately: magna-power.com/support.

The following parts are included with all MagnaDC power supply models:

3.2 Rack Installation

The 3U, 4U, and 6U TS Series MagnaDC power supply is intended for rack mount installations only into standard 19-inch EIA equipment racks. The 8U, 12U, and 16U TS Series MagnaDC power supply comes on casters and is designed to be used either standalone or installed into standard 19-inch EIA equipment racks.

Additional support, other than that provided by the front panel, is required when installing the TS Series MagnaDC power supply into an equiopment rack. Fixed rear support rails are provided for all models, which can be adjusted at time of installation to fit a variety of equipment rack depths. These included rails are designed to mate to inserts on the TS Series side panels using included hardware. Alternatively, angle slides, shelves, or cross beam supports can be used to securely fasten the product to the rack and support the rear weight. The unit should be always be horizontally mounted.

When using Magna-Power's provided fixed rear support rails, it's recommend to install these rear rails into the rack first, at the location desired. Using a pallet jack or fork lift, lift the power supply into the rack and align the holes of the rear rails with the inserts on the rear of the power supply's side panels. Once the holes are aligned, secure the rear support rails to the power supply side panel inserts using the provided 10-32 1/2" mating hardare, including screws, flat washer, and lock washers. Remove the casters of the 8U, 12U, and 16U models.

3.2.1 Cooling Requirements

Each TS Series MagnaDC power supply is cooled by suitable fans exhausting warm air to the rear of the cabinet. Depending on the power level, fresh air intake is either from the sides or from both the front and sides, allowing two or more TS Series supplies to be stacked without any clearance required. Equipment racks should be equipped with fans or blowers to remove heat generated by the power supplies. Magna-Power recommends fresh air intake at the bottom of the cabinet and exhaust fans at the top pulling air out of the cabinet.

The TS Series MagnaDC power supply features integrated fans that pull in cool air from the front and/or sides and exhausts warm air from the rear. Equipment racks housing the TS Series MagnaDC power supply should be equipped with either an open back, back with grills, or closed back with cabinet fans to remove heat generated by the TS Series

MagnaDC power supply. For fully enclosed cabinets, Magna-Power recommends fresh air intake from the bottom of the cabinet and exhaust at the top.

For cabinet fans to be effective, the ambient intake air temperature outside the rack must be less than the air temperature inside the rack. The TS Series MagnaDC power supply is rated for $50~^{\circ}$ C ambient operating temperature. In the case of rack installation, this corresponds to the temperature inside the rack and adequate cooling measures must be taken to ensure the rack's internal temperature stays below $50~^{\circ}$ C.

The following table provides Magna-Power's recommended per unit cabinet air flow when installing the TS Series MagnaDC power supply in a fully enclosed cabinet:

| TS Series Model Power Level | Maximum Heat Produced | Recommended Cabinet Air Flow 77 °F (25 °C) Room Temperature | Recommended Cabinet Air Flow 104 °F (40 °C) Room Temperature |
|--------------------------------|--------------------------|--|---|
| 5 kW | 1.7 kBTU/hr | 40 CFM | 100 CFM |
| 10 kW | 3.4 kBTU/hr | 80 CFM | 200 CFM |
| 15 kW | 5.1 kBTU/hr | 120 CFM | 290 CFM |
| 20 kW | 6.8 kBTU/hr | 160 CFM | 390 CFM |
| 25 kW | 8.5 kBTU/hr | 200 CFM | 490 CFM |
| 30 kW | 10.2 kBTU/hr | 240 CFM | 580 CFM |
| 40 kW | 13.6 kBTU/hr | 310 CFM | 775 CFM |
| 50 kW | 17.1 kBTU/hr | 390 CFM | 965 CFM |
| 75 kW | 25.5 kBTU/hr | 590 CFM | 1450 CFM |
| 100 kW | 34.2 kBTU/hr | 780 CFM | 1930 CFM |

Note: The table above accounts for only a single power supply at each respective power level. When sizing cabinet fans, it is necessary to account for the heat produced by all the products in the cabinet.

Caution: Do not block the air intake on the front or sides of the instrument, nor the exhaust at the rear of the instrument. Blocking these vents could cause the product to overheat. The recommended minimum clearances are 2 inches (5.1 cm) along the sides and back.

3.3 AC Input Connection

Warning: Disconnect AC power from the mains and measure the AC input terminals to ground to ensure 0 Vac is present before attempting any installation procedure.

AC power is wired to the TS Series MagnaDC power supply by attaching three cables plus ground for 3-phase installations or two cables plus ground for 1-phase installations. The TS Series MagnaDC power supply is phase orientation insensitive, allowing the phases to be connected in any order; the ground connection, however, must be connected to ground stud labeled with a *ground symbol*.

Magna-Power recommends cables per the recommendations of the National Electrical Code or Suggested Ampacities of 4-Conductor Type S or SO Cable, with one end stripped of 0.5 in (12.7 mm) of insulation and securely crimped to

a 1/4 in (6.3 mm) ring terminal in accordance with UL486A.

Remove the nut and mating lock washer from the TS Series MagnaDC power supply 1/4"-20 threaded AC input studs. Then place the ring terminal crimped to the AC input wire through the AC input stud, reattach and securely fasten the lock washer and mating nut. The recommended torque for the AC input connection is 4.2 lb-ft (5.7 Nm).

6U and 9U TS Series models have external cables that parallel the modules' AC input studs to a single module's AC input studs. Ensure that your external AC input wiring is made only to the AC input studs that have the mating nuts and lock washers. No additional connections are necessary for the module that has metal caps on its AC input studs. In addition, the two modules are grounded together internally; only one ground connection is required, which is on the same module where the external AC input wiring is made.

8U, 12U, and 16U TS Series models have only one exposed AC connection point for each phase. AC cabling should be routed through the provided grommet and connected to the studs behind the AC input cover.

Note: The cable recommendations provided are for reference purposes only. Always consult local electrical code requirements to ensure compliance.

After connections are made, the provided protective covers for the AC input and DC output can optionally be installed and securely fastened to the chassis using three screws per cover. This programmable DC power supply is designed to be permanently connected to the power source requiring a readily accessible disconnect device incorporated into the fixed wiring.

Table 3.1: Suggested Ampacities of Various Conductors as Recommended by the National Electrical Code

| Wire Size | 60 °C Types | 75 °C Types | 85 °C Types | 90 °C Types |
|-----------|-------------|---------------|-------------|-------------------|
| | RUW, T, TW | FEPW, RH, RH, | V, MI | TA, TBS, SA, AVB, |
| | | RUH, THW, | | SIS, FEP, FEPB, |
| | | THWN, XHHW, | | RHH, THHN, |
| | | ZW | | XHHW |
| 14 AWG | 25 Aac | 30 Aac | 30 Aac | 35 Aac |
| 12 AWG | 30 Aac | 35 Aac | 40 Aac | 40 Aac |
| 10 AWG | 40 Aac | 50 Aac | 55 Aac | 55 Aac |
| 8 AWG | 60 Aac | 70 Aac | 75 Aac | 80 Aac |
| 6 AWG | 80 Aac | 95 Aac | 100 Aac | 105 Aac |
| 4 AWG | 105 Aac | 125 Aac | 135 Aac | 140 Aac |
| 3 AWG | 120 Aac | 145 Aac | 160 Aac | 165 Aac |
| 2 AWG | 140 Aac | 170 Aac | 185 Aac | 190 Aac |
| 1 AWG | 165 Aac | 195 Aac | 215 Aac | 220 Aac |
| 10 AWG | 195 Aac | 230 Aac | 250 Aac | 260 Aac |
| 20 AWG | 225 Aac | 265 Aac | 290 Aac | 300 Aac |
| 30 AWG | 260 Aac | 310 Aac | 335 Aac | 350 Aac |
| 40 AWG | 300 Aac | 360 Aac | 390 Aac | 405 Aac |
| 250 MCM | 340 Aac | 405 Aac | 440 Aac | 455 Aac |
| 300 MCM | 375 Aac | 445 Aac | 485 Aac | 505 Aac |
| 350 MCM | 420 Aac | 505 Aac | 550 Aac | 570 Aac |

Table 3.2: Suggested Ampacities of 4-Conductor Type S or SO Cable

| Wire Size | Maximum Current |
|-----------|-----------------|
| 18 AWG | 7 Aac |
| 16 AWG | 10 Aac |

continues on next page

| Table 3.2 – continued from previous | ous page |
|-------------------------------------|----------|
|-------------------------------------|----------|

| Wire Size | Maximum Current |
|-----------|-----------------|
| 14 AWG | 15 Aac |
| 12 AWG | 20 Aac |
| 10 AWG | 25 Aac |
| 8 AWG | 35 Aac |
| 6 AWG | 45 Aac |
| 4 AWG | 60 Aac |
| 2 AWG | 80 Aac |

3.3.1 AC Input Current

The AC input current rating is specified on the product's serial label, typically located on the top cover near the AC input terminals.

The following tables provides the per phase maximum input current rating for the available AC input voltages and power levels of the TS Series. All AC input currents factor in efficiency and power factor. With the product's AC soft-start circuitry, there is no additional in-rush current; the numbers in the following table provides the peak AC current draw at full load. These same AC input current ratings are also specified on the product's serial label.

Table 3.3: AC input current ratings for TS Series MagnaDC power supply

| Power Level | AC Input Voltage | AC Input Current |
|-------------|------------------|------------------|
| 5 kW | 208/240 Vac, 1Φ | 41 Aac |
| 5 kW | 208/240 Vac, 3Φ | 18 Aac |
| 5 kW | 380/415 Vac, 3₽ | 10 Aac |
| 5 kW | 440/480 Vac, 3Φ | 9 Aac |
| 10 kW | 208/240 Vac, 3Φ | 36 Aac |
| 10 kW | 380/415 Vac, 3₽ | 20 Aac |
| 10 kW | 440/480 Vac, 3Φ | 17 Aac |
| 15 kW | 208/240 Vac, 3Φ | 52 Aac |
| 15 kW | 380/415 Vac, 3₽ | 29 Aac |
| 15 kW | 440/480 Vac, 3Φ | 25 Aac |
| 20 kW | 208/240 Vac, 3Φ | 69 Aac |
| 20 KW | 380/415 Vac, 3₽ | 38 Aac |
| 20 KW | 440/480 Vac, 3Φ | 33 Aac |
| 25 kW | 208/240 Vac, 3Ф | 85 Aac |
| 25 kW | 380/415 Vac, 3₽ | 47 Aac |
| 25 kW | 440/480 Vac, 3Φ | 40 Aac |
| 30 kW | 208/240 Vac, 3Ф | 105 Aac |
| 30 kW | 380/415 Vac, 3Ф | 57 Aac |
| 30 kW | 440/480 Vac, 3Φ | 50 Aac |
| 40 kW | 380/415 Vac, 3₽ | 76 Aac |
| 40 kW | 440/480 Vac, 3Φ | 66 Aac |
| 50 kW | 380/415 Vac, 3₽ | 94 Aac |
| 50 kW | 440/480 Vac, 3Φ | 82 Aac |
| 75 kW | 380/415 Vac, 3Φ | 141 Aac |
| 75 kW | 440/480 Vac, 3Φ | 120 Aac |
| 100 kW | 380/415 Vac, 3Φ | 188 Aac |
| 100 kW | 440/480 Vac, 3Φ | 160 Aac |

The following table provides the per phase maximum input current rating for the available AC input voltage and power

levels for specific models of the TS Series that fall outside of the standard power levels in the table above.

Table 3.4: AC input current ratings for TS Series MagnaDC power supply the fall outside of standard power ranges

| Model | AC Input Voltage | AC Input Current |
|------------|------------------|------------------|
| TSD5-1800 | 208/240 Vac, 1Φ | 36 Aac |
| TSD5-1800 | 380/415 Vac, 3Ф | 20 Aac |
| TSD5-1800 | 440/480 Vac, 3Φ | 17 Aac |
| TSD5-2700 | 208/240 Vac, 1Φ | 52 Aac |
| TSD5-2700 | 380/415 Vac, 3Ф | 29 Aac |
| TSD5-2700 | 440/480 Vac, 3Φ | 25 Aac |
| TSD10-2700 | 208/240 Vac, 1Φ | 108 Aac |
| TSD10-2700 | 380/415 Vac, 3Φ | 60 Aac |
| TSD10-2700 | 440/480 Vac, 3Φ | 24 Aac |
| TSD10-6000 | 380/415 Vac, 3Φ | 114 Aac |
| TSD10-6000 | 440/480 Vac, 3Φ | 99 Aac |
| TSD10-8000 | 380/415 Vac, 3Ф | 152 Aac |
| TSD10-8000 | 440/480 Vac, 3Φ | 132 Aac |

3.3.2 Fuse Rating

MagnaDC power supplies contain a variety of power and control fuses. For TS Series MagnaDC power supply products with a 1-phase input, there are two (2) power fuses and two (2) control fuses. For TS Series products with a 3-phase input, there are three (3) power fuses per module and two (2) control fuses per module. table-installation-fuse provides the fuses ratings and recommended replacements. Magna-Power recommends using a time-delay fuse.

In the event of a fuse fault, power must be removed from the supply and the fuse must be replaced to correct this condition. A cleared power fuse usually indicates a power stage failure, often requiring factory attention. In addition, a cleared fuse can be caused by power surges from lightning storms or other AC transient events.

Warning: To avoid personal injury or damage to the TS Series MagnaDC power supply, use only the specified replacement fuses.

Note: MT Series Products Only. For the power processing circuitry, MT Series programmable DC power supplies are equipped with a 3-phase AC breaker instead of fuses. In the event the breaker is tripped or if the breaker is not engaged after applying turning on control power via the front panel control power switch, the FSE alarm will indicate. After engaging the breaker to the on position and pressing the Clear button, the FSE alarm will no longer be present.

Table 3.5: Fuse ratings for TS Series MagnaDC power supply

| Power | AC Input Volt- | Power Fuse Rating | | Control Fuse Rat- | |
|-------|----------------|-----------------------|---------|----------------------|--------------|
| Level | age | | Recom- | ing | Recom- |
| | | | mended | | mended |
| | | | Power | | Control Fuse |
| | | | Fuse(s) | | |
| | | | | | |
| 5 kW | 208/240 Vac | Qty (3) at 20 Aac ea. | FNQ20 | Qty (2) at 1 Aac ea. | FNQ1 |
| 5 kW | 380/415 Vac | Qty (3) at 15 Aac ea. | FNQ15 | Qty (2) at 1 Aac ea. | FNQ1 |

continues on next page

Table 3.5 – continued from previous page

| Power | AC Input Volt- | Power Fuse Rating | | Control Fuse Rat- | |
|--------|----------------|------------------------|----------|----------------------|--------------|
| Level | age | | Recom- | ing | Recom- |
| | | | mended | | mended |
| | | | Power | | Control Fuse |
| | | | Fuse(s) | | |
| | | | , | | |
| 5 kW | 440/480 Vac | Qty (3) at 15 Aac ea. | FNQ15 | Qty (2) at 1 Aac ea. | FNQ1 |
| 10 kW | 208/240 Vac | Qty (3) at 40 Aac ea. | SC40 | Qty (2) at 1 Aac ea. | FNQ1 |
| 10 kW | 380/415 Vac | Qty (3) at 25 Aac ea. | FNQ25 | Qty (2) at 1 Aac ea. | FNQ1 |
| 10 kW | 440/480 Vac | Qty (3) at 20 Aac ea. | FNQ20 | Qty (2) at 1 Aac ea. | FNQ1 |
| 15 kW | 208/240 Vac | Qty (3) at 60 Aac ea. | SC60 | Qty (2) at 1 Aac ea. | FNQ1 |
| 15 kW | 380/415 Vac | Qty (3) at 35 Aac ea. | ATM30/35 | Qty (2) at 1 Aac ea. | FNQ1 |
| 15 kW | 440/480 Vac | Qty (3) at 30 Aac ea. | FNQ30 | Qty (2) at 1 Aac ea. | FNQ1 |
| 30 kW | 208/240 Vac | Qty (6) at 60 Aac ea. | SC60 | Qty (2) at 1 Aac ea. | FNQ1 |
| 30 kW | 380/415 Vac | Qty (6) at 30 Aac ea. | ATM30/35 | Qty (2) at 1 Aac ea. | FNQ1 |
| 30 kW | 440/480 Vac | Qty (6) at 30 Aac ea. | FNQ30 | Qty (2) at 1 Aac ea. | FNQ1 |
| 20 kW | 380/415 Vac | Qty (3) at 50 Aac ea. | ATM30/50 | Qty (2) at 1 Aac ea. | FNQ1 |
| 20 kW | 440/480 Vac | Qty (3) at 50 Aac ea. | ATM30/50 | Qty (2) at 1 Aac ea. | FNQ1 |
| 25 kW | 380/415 Vac | Qty (3) at 50 Aac ea. | ATM30/50 | Qty (2) at 1 Aac ea. | FNQ1 |
| 25 kW | 440/480 Vac | Qty (3) at 50 Aac ea. | ATM30/50 | Qty (2) at 1 Aac ea. | FNQ1 |
| 40 kW | 380/415 Vac | Qty (6) at 50 Aac ea. | ATM30/50 | Qty (2) at 1 Aac ea. | FNQ1 |
| 40 kW | 440/480 Vac | Qty (6) at 50 Aac ea. | ATM30/50 | Qty (2) at 1 Aac ea. | FNQ1 |
| 50 kW | 380/415 Vac | Qty (6) at 50 Aac ea. | ATM30/50 | Qty (2) at 1 Aac ea. | FNQ1 |
| 50 kW | 440/480 Vac | Qty (6) at 50 Aac ea. | ATM30/50 | Qty (2) at 1 Aac ea. | FNQ1 |
| 75 kW | 380/415 Vac | Qty (9) at 50 Aac ea. | ATM30/50 | Qty (2) at 1 Aac ea. | FNQ1 |
| 75 kW | 440/480 Vac | Qty (9) at 50 Aac ea. | ATM30/50 | Qty (2) at 1 Aac ea. | FNQ1 |
| 100 kW | 380/415 Vac | Qty (12) at 50 Aac ea. | ATM30/50 | Qty (2) at 1 Aac ea. | FNQ1 |
| 100 kW | 440/480 Vac | Qty (12) at 50 Aac ea. | ATM30/50 | Qty (2) at 1 Aac ea. | FNQ1 |

3.4 DC Output Connection

Warning: SHOCK HAZARD. Turn off AC power before making any rear panel connections. Ensure that MagnaDC power supply connections, load wiring, and load connections are either insulated or covered so that no accidental contact with lethal output voltages can occur.

The DC output of the TS Series MagnaDC power supply connects to the DC bus by attaching two cables to the output bus bars. Magna-Power recommends DC power cables be crimped to ring terminals and securely fastened to bus bars using the included 3/8" bolts, washers, and lock washers. The bus bars contain 3/8"-16 threaded inserts. The recommended torque for the DC connection is 240 in-lbf (27.1 N-m).

Select a wire size sufficient to handle the maximum output current of the unit, no matter what the intended load current or current limit setting.

The recommended wire size for different current levels are shown in the table below.

| Wire Size (USA) | | Wires Per Output Termi- | Maximum Current |
|-----------------|----------------------|-------------------------|-----------------|
| | Equivalent Wire Size | nal | |
| | (International) | | |
| | | | |
| 6 AWG | 10 mm ² | 1 | 85 Adc |
| 4 AWG | 25 mm ² | 1 | 110 Adc |
| 3 AWG | 25 mm ² | 1 | 130 Adc |
| 2 AWG | 35 mm ² | 1 | 150 Adc |
| 1 AWG | 50 mm ² | 1 | 170 Adc |
| 1/0 AWG | 50 mm ² | 1 | 200 Adc |
| 2/0 AWG | 70 mm ² | 1 | 235 Adc |
| 3/0 AWG | 95 mm ² | 1 | 275 Adc |
| 4/0 AWG | 120 mm ² | 1 | 315 Adc |
| 1/0 AWG | 50 mm ² | 2 | 400 Adc |
| 2/0 AWG | 70 mm ² | 2 | 470 Adc |
| 3/0 AWG | 95 mm ² | 2 | 550 Adc |
| 4/0 AWG | 120 mm ² | 2 | 630 Adc |
| 1/0 AWG | 50 mm ² | 4 | 800 Adc |
| 2/0 AWG | 70 mm ² | 4 | 940 Adc |
| 3/0 AWG | 95 mm ² | 4 | 1100 Adc |
| 4/0 AWG | 120 mm ² | 4 | 1260 Adc |

Notes:

- 1. Capacity for AWG wires derived from the National Electric Code. Maximum ambient temperature: 40°C. Maximum wire temperature: 90°C. Continuous duty with wires in free air, not bundled or in conduit.
- 2. Capacity of aluminum wire is approximately 84% of the capacity listed for copper wire.
- 3. For higher current levels, it's recommended to use bus bars with holes for additional cable feeds or direct bus bar connection to the load.

Warning: FIRE HAZARD. Select a wire size large enough to carry the TS Series MagnaDC power supply model's maximum rated current to prevent overheating of the wires. Make sure power cable connections are secured tightly in accordance with the torque recommendation to prevent overheating of the bus bars.

3.4.1 Grounding the DC Output

The output of the TS Series MagnaDC power supply is floating up to the DC output isolation specifications. A floating output means the output terminals are not connected electrically to ground and the produced output voltage is from the positive terminal with respect to the negative terminal. Neither output terminal needs to be connected to ground, however if desired, either the positive or negative terminal can be connected to earth ground.

3.5 Remote Sense Connection

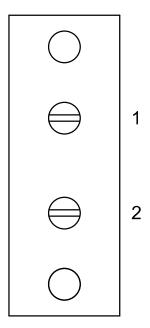


Fig. 3.1: Remote sense connector

Note: Wired remote sense is only available for models rated 1000 Vdc and without the High Isolation Output (+ISO) option.

Remote sensing can improve regulation at a remote reference point. Appreciable voltage drop can occur in the wire between the power supply and load as the current increases. By default, the load operates in local sense, where feedback is internally connected at the power supply's outputs terminals. However, the power supply can also operate in remote sense, and compensate for wire voltage drop by connecting its high-impedance sense wires to the load terminals. When the remote sense setting is enabled the feedback measurements are taken from the remote sense leads.

The remote sense setting is accessible from either the *front panel* configuration or by *computer command*. Magna-Power recommends using 20 AWG wires with the remote sense screw terminals. Connect the MagnaDC power supply's positive remote sense lead to the positive of the DC source terminals. Connect the MagnaDC power supply's negative remote sense lead to the negative terminal of the DC source. Both remote sense terminals are 6-32 screw connections. Connect the sense leads as close to the load as possible. Do not bundle the sense wire-pair together with the load leads; keep the load wires and sense wires separate.

Caution: Always ensure that the positive remote sense lead corresponds to the positive DC bus and, likewise, that the the negative remote sense lead corresponds to the negative DC bus. Connecting sense wires with an incorrect polarity can result in equipment damage.

Enabling remote sense activates the remote sense lead detector. The remote sense lead detector checks that the remote sense leads have been connected to the load. With the power supply configured for remote sensing and upon enabling power output, the sense location is initially set to local. The sense location is switched to remote upon reaching 7.5% of full scale output voltage. Once the power supply is sensing the voltage remote, as long as the voltage detected is greater than 4.5% of full scale output voltage, the sense location remains remote; if the output voltage detected is less than 4.5%, then the sense location will automatically revert back to local.

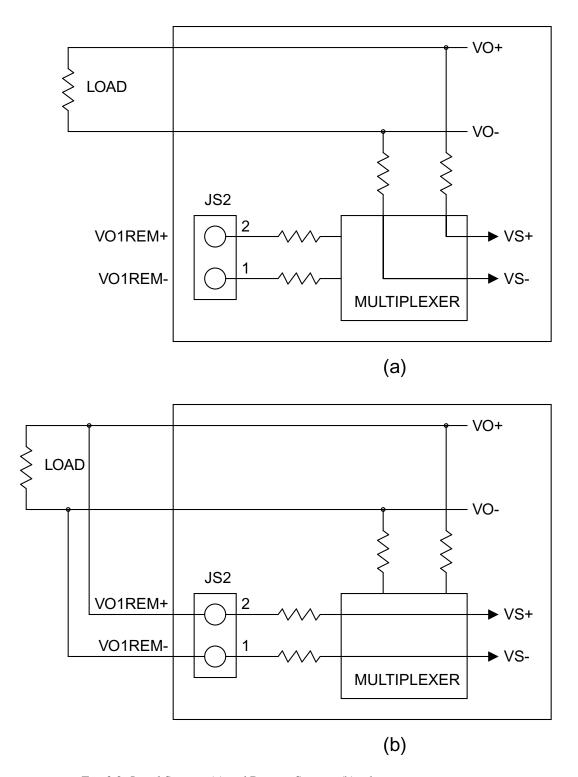


Fig. 3.2: Local Sensing (a) and Remote Sensing (b) schematic representation

Caution: WARNING. Switching remote sense leads or disconnecting remote sense leads while the output is enabled can cause device failure. Only switch or disconnect remote sense leads while the power supply is in standby or turned off.

The remote sense indicator on the front panel will flash when the remote sense functionality has been enabled, but the power supply is remaining in local sense. The power supply will remain in local sense with the REM SEN light flashing if the output voltage never exceeds 7.5% of full scale output voltage or the remote sense lead detector has determined sense leads are not connected. The remote sense indicator will remain flashing until the remote sense detector has detected the presence of remote sense voltage within the limits described above.

3.6 Electrical Check

This section describes the electrical checkout procedure for the TS Series MagnaDC power supply. This brief electrical checkout procedure validates the product's power circuitry and safety features. This procedure should be followed upon receipt of the product and before it is placed into use.

The electrical check for models with the C Version front panel require use of the Remote Interface Software described in Chapter 4, Remote Interface Software. With the software installed and the power supply connected to the desired communications interface, select the appropriate equivalent front panel in the Configuration Setup Panel. Select the Virtual Control Panel in the View Menu to display the virtual SL Version front panel. Follow the procedure below using the Virtual Control Panel from within the Remote Interface Software.

With the power supply off, disconnect the load, set voltage and current potentiometer controls fully counterclockwise, and set the over voltage trip and over current trip settings to maximum, fully clockwise. Connect the power supply to a suitable source of AC voltage. For this test, only 50% of rated AC current is required. Turn the power switch on and observe the indicator lights going through the startup routine. After initialization, the following indicator lights should be on: STANDBY, INT CTL, EXT CTL, and ROTARY. This is the default configuration from the factory.

Maximum Voltage, Open-Circuit

Press the start switch and advance the current control one turn clockwise. The power and voltage control indicators should light. Increase the voltage set point to maximum and then to minimum. DC voltage should increase smoothly from minimum to maximum to minimum as indicated on the meter. Return the voltage control full counterclockwise. Press the stop switch.

Over Voltage Trip, Open-Circuit

To check over voltage trip, press the menu key. This places the power supply in data entry mode to set over voltage trip. Using the up/down arrow keys, enter an over voltage trip set point at half the rating of the power supply. Once the over voltage trip set point has been entered, press the enter key to save the information.

Press the start switch and slowly increase the voltage set point. Over voltage trip should operate at the over voltage trip set point. The over voltage trip (OVT) indicator should turn on, the power and voltage control indicators should turn off, and the supply should shut down. Press the clear key. Now set the over voltage trip set point to maximum which is 110% the full scale rating of the power supply. Again start the supply and observe that the power supply operates normally. With the main power disconnected, connect a short to the power output terminals on the rear panel. Reconnect the main power, set voltage and current controls full counterclockwise, and turn the power switch on.

Maximum Current, Short-Circuit

With the main power disconnected, connect a short across the output terminals of the power supply. Reconnect the main power, set voltage and current controls full counterclockwise and turn the power switch on.

Press the start switch and advance the voltage control one turn clockwise. Increase the current set point to maximum and then to minimum. The power and current control indicators should light. DC current should increase smoothly

from minimum to maximum to minimum as indicated on the meter. Return the current control full counterclockwise. Press the stop switch.

Over Current Trip, Short-Circuit

To check over current trip, press the menu key and then the item key one time. This places the power supply in data entry mode to set over current trip. Using the up/down arrow keys, enter an over current trip set point at half the rating of the power supply. Once the over current trip set point has been entered, press the enter key to save the information.

Press the start switch and slowly increase the current set point. Over current trip should operate at the over current trip set point. The over current trip (OCT) indicator should turn on, the power and current control indicators should turn off, and the supply should shut down. Press the clear key. Now set the over current trip set point to maximum which is 110% the full scale rating of the power supply. Again start the supply and observe that the power supply operates normally.

If any of these events do not occur, the supply is defective and should not be operated. Depending on the circumstances, either warranty service or troubleshooting is required.

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CHAPTER

FOUR

FEATURES AND FUNCTIONS

4.1 Output Regulation States

The TS Series MagnaDC power supply can operate in either constant voltage or constant current output regulation. The MagnaDC power supply will automatically switch between the two regulation states as a function of the programmed set points and the load impedance. The regulation state is indicated by an illuminated LED above the respective programming knob, also via the external user I/O connector or by computer command.

The TS Series MagnaDC power supply will make a seamless autocrossover from voltage mode control to current mode control, as determined by the voltage and current set points and/or load impedance. If either set point is set to zero, the other set point control will have little or no effect, forcing either a zero voltage limit or zero current limit and preventing output from the MagnaDC power supply.

4.1.1 Constant Voltage

When the constant voltage regulation state is indicated, the MagnaDC power supply is maintaining fixed voltage at the programmed set point, while the output current flucuates as a function of the load impedance, as illustrated by Fig. 4.1.

To force the TS Series MagnaDC power supply to constant voltage mode, begin with the product in standby and set both voltage and current set points to zero. While pressing the V/I DIS key on the front panel, advance the voltage and current set points for the desired output voltage and the desired crossover current. The crossover current is the maximum desired current, at which the power supply crosses over to current mode control to become a constant current source.

Connect the load and command the power supply to start. The output voltage should be close to the voltage set point. If a load change causes the programmed current set point to be exceeded, the power supply will automatically crossover to constant current output at the programmed current set point and the output voltage will drop proportionately. When setting the current limit, allowance must be made for high peak currents which can cause unwanted crossover.

4.1.2 Constant Current

When the constant current regulation state is indicated, the MagnaDC power supply is maintaining fixed current at the programmed set point, while the output voltage flucuates as a function of the load impedance, as illustrated by Fig. 4.2.

To force the TS Series MagnaDC power supply to constant current mode, begin with the product in standby and set both voltage and current set points to zero. While pressing the V/I DIS key on the front panel, advance the voltage and current set points for the desired output current and the desired crossover voltage. The crossover voltage is the maximum desired voltage, at which the power supply crosses over to voltage mode control to become a constant voltage source.

Connect the load and command the power supply to start. The output current should be close to the current set point. If a load change causes the programmed voltage set point to be exceeded, the power supply will automatically crossover to constant voltage output at the programmed voltage set point and the output current will drop proportionately.

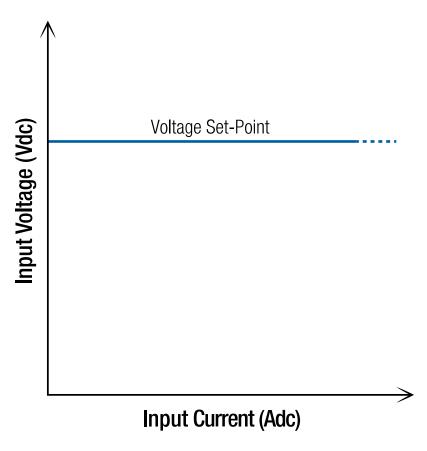


Fig. 4.1: Operating range in constant voltage mode

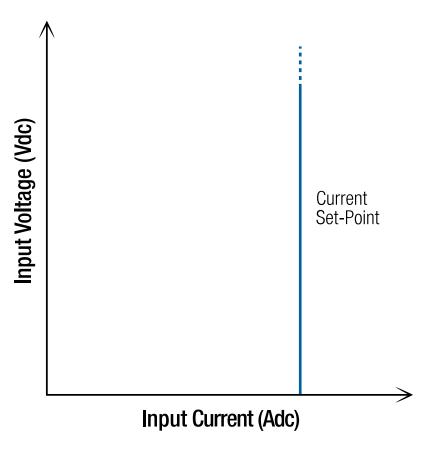


Fig. 4.2: Operating range in constant currnet mode

4.2 Commands

The following commands allow the user to control when the TS Series MagnaDC power supply's power processing circuitry is engaged and when faults are cleared. These commands are available from the front panel, external user I/O and computer commands. To control which interfaces these commands are available from, the user can control these settings with the following configuration settings:

- INT CTL: Front panel control for Start, Stop, and Clear.
- EXT CTL: External user I/O and computer control for Start, Stop, and Clear.

INT EXT and EXT CTL can both be enabled simulatenously, if desired, for Start, Stop, and Clear control from a variety of interfaces.

Caution: Only disable INT CTL if verified external or computer controls are in place, as it will prevent the user from stopping the product from the front panel.

4.2.1 Start

The Start command engages the power processing circuitry, signaled by a click of the product's AC input contactor engaging, placing the product in a powered state. The Start command can only be issued when the product is in standby. If the product is either in a alarm state or in a power state, the Start command will have no effect.

After issuing the Start command, the product enters in a soft start, which is a pre-charge circuit used to prevent in-rush current.

Note: For applications demanding fast and/or high repetition cycle times off and on, once in a powered state, it's recommended to program the product to zero and then back up to the desired set point, instead of using Stop/Start commands. Programming the product down to zero and then back up to the set point eliminates soft start circuitry delay and provides the fastest achievable rise time.

For more information on the Start command:

- · Commanding Start from the front panel
- Commanding Start from external user I/O
- · Commanding Start from computer command

4.2.2 Stop

The Stop command disengages the power processing circuitry, signaled by a click of the product's AC input contactor disengaging, placing the product in a standby state. The Stop command can only be issued when the product is in a powered state. If the product is either in an alarm state or in standy state, the Stop command will have no effect.

For safety, the Stop command always takes precedence over any other active command, regardless of the interface. If a Start command is issued while the Stop command is active, the product will not engage.

For more information on the Stop command:

- Commanding Stop from the front panel
- Commanding Stop from external user I/O
- Commanding Stop from computer command

4.2.3 Clear

The Clear command unlatches a fault from memory and transitions the front from an alarm state to standby state. After a fault has occurred, the Clear command must be issued before the product is able to resume operation. Alternatively, the product can be power cycled. The Clear command will only unlatch a fault from memory if the fault condition has been resolved.

For more information on the Clear command:

- · Commanding Clear from the front panel
- Commanding Clear from external user I/O
- · Commanding Clear from computer command

4.3 Protection and Diagnostics

4.3.1 Over Voltage Trip (OVT)

The TS Series MagnaDC power supply has a programmable Over Voltage Trip setting used to shutdown the product if an undesired maximum voltage value is measured across the DC output. The OVT setting can be adjusted to a maximum of 110% of the specific MagnaDC power supply's full scale voltage rating. An over-voltage condition must be sustained for ~ 30 ms for the OVT fault to register.

When an OVT fault occurs, a contactor on the AC input opens, providing a mechanical break to the power processing circuits, but leaving the control power in place. An OVT alarm is indicated by red OVT LED illumination on the front panel, +5V on Pin 34 of the external user I/O and by computer command by querying the Questionable Register. To resume operation, the DC output voltage must be drop below the MagnaDC power supply's OVT setting, the *Clear* function must be issued, and the input re-energized with the *Start* function.

The OVT setting can be programmed through the front panel, through 0-10V analog input on Pin 4 of the external user I/O, or programmatically through software.

The factory default OVT setting is 110% of the specific MagnaDC power supply's maximum voltage rating.

For more information on setting OVT:

- Setting OVT from the front panel
- Setting OVT from external user I/O
- Setting OVT from computer command

4.3.2 Over Current Trip (OCT)

The TS Series MagnaDC power supply has a programmable Over Current Trip setting used to shutdown the product if an undesired maximum current value is measured across the DC output. The OCT setting can be adjusted to a maximum of 110% of the specific MagnaDC power supply's full scale current rating. An over current condition must be sustained for ~ 60 ms for the OCT fault to register; this fault is purposely delayed to avoid nuisance trips.

When an OCT fault occurs, a contactor on the AC input opens, providing a mechanical break to the power processing circuits, but leaving the control power in place. An OCT alarm is indicated by red OCT LED illumination on the front panel, +5V on Pin 32 of the external user I/O and by computer command by querying the Questionable Register. To resume operation, the DC output current must be drop below the MagnaDC power supply's OCT setting, the *Clear* function must be issued, and the input re-energized with the *Start* function.

The OCT setting can be programmed through the front panel, through 0-10V analog input on Pin 23 of the external user I/O, or programmatically through software.

The factory default OCT setting is 110% of the specific MagnaDC power supply's maximum current rating.

For more information on setting OCT:

- Setting OCT from the front panel
- Setting OCT from external user I/O
- Setting OCT from computer command

4.3.3 Thermal Fault (THL)

The TS Series MagnaDC power supply has internal thermal switches on its various heatsinks to ensure operation at temperatures within the product's design specifications. A thermal fault typically results from one of the following conditions:

- Operating in an environment above the maximum ambient temperature specification.
- Blocking the air intake.
- Internal fan or solenoid failure.
- Broken electrical contact to thermal switches.
- Coolant intake temperatures are above those recommended (water cooled units only).

When a thermal fault occurs, a contactor on the AC input opens, providing a mechanical break to the power processing circuits, but leaving the control power and fan power in place. The user is prevented from enabling the MagnaDC power supply through the front panel, external interface, or computer command. A thermal alarm is indicated by red THL LED illumination on the front panel, +5V on Pin 9 of the external user I/O and by computer command by querying the Questionable Register.

To resume operation, the internal thermal temperature must return to return to safe operating temperatures, the *Clear* function must be issued, and the input re-energized with the *Start* function. Allow sufficient time for the MagnaDC power supply to cool after a thermal fault occurs, otherwise, the product will enter immediately back into a thermal fault after starting.

4.3.4 Interlock (LOC)

The Interlock feature disables the MagnaDC power supply by entering a soft fault state. The safety feature is triggered whenever the +5V signal applied to the interlock pin is broken. By default, interlock is disabled when the MagnaDC power supply ships from the factory. Interlock can be enabled from the front panel, *computer interface*. Once interlock is assigned to one of the pins listed in *external user I/O* +5V must be present to operate the product. There are two method to providing +5V to the interlock pin:

- Providing a physical short from the provided external user I/O +5V signal (Pin 14) to the interlock digital input.
- Using an external user supplied +5V signal with reference to the external user I/O GND signal (Pin 25).

With either method, an external dry contact may be used to trigger the interlock.

When the +5V interlock signal is broken, the dissipative elements are switched out of the DC bus using a high-speed switching device, the MagnaDC power supply is placed in a soft fault state.

To resume normal operation, the +5V signal must first be restored to the interlock input and the Clear command issued.

By factory default, the TS Series MagnaDC power supply ships with Interlock functionality disabled. For more information on enabling or disabling the interlock feature:

- Enabling or disabling interlock via the front panel
- Enabling or disabling interlock via computer command

4.3.5 Phase Loss (PHL)

MagnaDC power supplies monitor that AC input voltages to ensure the rated input voltage is present. In the event that Phase A falls below 10% of the rated input voltage, the product will trip with a phase loss alarm.

When a phase loss occurs while the product is operating, a contactor on the AC input opens, providing a mechanical break to the power processing circuits, but leaving the control power and fan power in place. The user is prevented from enabling the MagnaDC power supply through the front panel, external interface, or computer command. When a phase loss occurs while the product is in standby, the user will also be prevented from enabling the product through the front panel or external interface. A phase loss alarm is indicated by red PHL LED illumination on the front panel or by computer command by querying the Questionable Register.

The product should not be operated with a phase imbalance. When a phase loss alarm occurs, inspect the AC input connections to ensure secure connections. Investigae the AC power system and monitor the bus voltage to ensure it is providing a steady line-to-line voltage in accordance with the power supply's rated AC input voltage requirements.

To resume operation, the AC line voltage must return to within 10% of the product's nominal AC input voltage requirement, the *Clear* function must be issued, and the input re-energized with the *Start* function.

4.3.6 Program Line Fault (PGL)

The TS Series MagnaDC power supply monitors the 0-10V analog programming inputs on the external user I/O connector for erroneous input. In the event that any applied analog input voltage is greater than 12.5 V, a contactor on the AC input opens, providing a mechanical break to the power processing circuits, but leaving the control power in place. An PGL alarm is indicated by red PGL LED illumination on the front panel, +5V on Pin 27 of the external user I/O and by computer command by querying the Questionable Register.

To resume operation, the analog input voltages must return to return to under 12.5 Vdc, the *Clear* function must be issued, and the input re-energized with the *Start* function. Investigae the source of the erroneous analog input voltage to prevent possible damage.

Caution: Analog input programming voltages in excess of 20 Vdc will damage integrated circuits on the control board and require control board replacement. Always verify analog input signals with an external voltmeter before connecting them to the MagnaDC power supply.

4.3.7 Fuse (FSE)

MagnaDC power supplies contain a variety of power and control fuses. An fuse alarm is indicated by red FSE LED illumination on the front panel, +5V on Pin 15 of the external user I/O and by computer command by querying the Questionable Register. The fuse alarm indicates that one of the three main fuses has cleared.

Note: MT Series Products Only. For the power processing circuitry, MT Series programmable DC power supplies are equipped with a 3-phase AC breaker instead of fuses. In the event the breaker is tripped or if the breaker is not engaged after applying turning on control power via the front panel control power switch, the FSE alarm will indicate. After engaging the breaker to the on position, the procedures to the clear the FSE alarm are as noted below.

To resume operation, the fuse must be replaced, the *Clear* function must be issued, and the input re-energized with the *Start* function.

For more details on fuse ratings and replacement, see installation-input-fuse.

OPERATION: PARALLEL AND SERIES

5.1 Parallel

Two or more SL Series power supplies can be connected in parallel to obtain a total output current greater than that available from one power supply. The total output current is the sum of the output currents of the individual power supplies. Each power supply can be turned on or off separately.

5.1.1 Parallel - Direct

The simplest parallel connection involves attaching the positive terminals of all supplies to be paralleled to the positive point of the load and attaching the negative terminals to the negative point of the load. The output current controls of each power supply can be separately set. The output voltage control of one power supply (master) should be set to the desired output voltage; the other power supply (slave) should be set for a slightly higher output voltage. The master will act as a constant voltage source; the slave will act as a constant current source, dropping its output voltage to equal that of the master.

5.1.2 Parallel - Master-Slave

Master-slave parallel operation permits equal current sharing under all load conditions and allows complete control of output current from one master power supply. With Magna-Power's master-slave parallel scheme, the master sends signals to control the slave unit's gate driver, ensuring only one control loop and consistent transient response performance.

Fig. 5.1 illustrates the terminal connection for master/slave parallel operation and salient control circuitry. The control cable can be fabricated by the user or purchased as an accessory, *Universal Interface Device (UID47)*, from the factory. These connections perform the following functions:

- Jumper connection between ISO (Pin 16) of the slave power supplies and ISI (Pin 35) of the master power supply
 connects the slave power supplies current monitoring outputs to the master power supply current monitoring
 input. This connection allows the current of all slave power supplies to be summed along with that of the master
 power supply.
- Jumper connection between CONTROL (Pin 31) of the master and slave power supplies connects the control lines between the master and slave power supplies. Command of the control line is automatically selected with the jumper connections.
- Jumper connection between REF GND (Pin 2), VREF EXT (Pin 3), IREF EXT (Pin 22) of the slave power supplies to REF GND (Pin 2) of the master power supply enables control of the slave power supplies from the master power supply.

- Jumper connection between POWER (Pin 8) of the master power supply to START (Pin 17) of the slave power supplies connects the power output digital control line of the master power supply to the start digital control line of the slave power supplies. This connection causes slave units to turn on when the master unit is turned on.
- Jumper connection between STANDBY/ALM (Pin 12) of the master power supply and STOP (Pin

19) of the slave power supplies connects the STANDBY/ALM digital control line of the master power supply to the STOP digital control line of the slave power supplies. This connection causes the slaves units to turn off when the master unit is turned off or when a diagnostic condition appears. * Jumper connections between TVREF EXT (Pin 4), +10V REF (Pin 21), and TIREF EXT (Pin 23) of the slave power supplies sets the slave voltage trip and over current trip set points just beyond full scale values.

The master unit can configured for rotary, external program, or remote input. The slave power supply must be configured for external program (EXT PGM) input.

For more information on setting the slave unit to EXT PGM:

- Configuring the product for EXT PGM from the front panel
- Configuring the product for EXT PGM from computer command

To add a second slave unit, connect the output terminals of the second slave in parallel with the other two power supplies. Furthermore, connect a second control cable between the second slave unit and the master unit, or use an additional *Universal Interface Device (UID47)* accessory from the factory.

5.2 Series

Two or more power supplies can be connected in series to obtain a total output voltage greater than that available from one power supply. The total output voltage is the sum of the output voltage of the individual power supplies. Each power supply can be turned on or off separately.

Caution: No plus or minus voltage should exceed the product's output isolation specification with respect to ground.

5.2.1 Series - Direct

The simplest series connection involves attaching the positive terminal of the first supply to the negative terminal of the second supply. The load is connected between the negative terminal of the first supply and the positive terminal of the second supply. The output current controls of each power supply are operative and the current limit is equal to the lowest control setting. If any one output current control is set too low with respect to the total output current, the series power supplies will automatically crossover to constant current operation and the output voltage will drop.

5.2.2 Series - Master-Slave

Master-slave series operation permits equal voltage sharing under all load conditions and allows complete control of output voltage from one master power supply. Fig. 5.2 illustrates the terminal connection for master/slave series operation and salient control circuitry. The control cable can be fabricated by the user or purchased as an accessory, *Universal Interface Device (UID47)*, from the factory. These connections perform the following functions:

• Jumper connection between VO2 (Pin 5) of the master power supply and VREF EXT (Pin 3) of the slave power supplies connects the voltage monitoring voltage on the master power supply to the external voltage set point input on the slave power supplies. This makes the slave power supplies operate at the same voltage output as the master power supply.

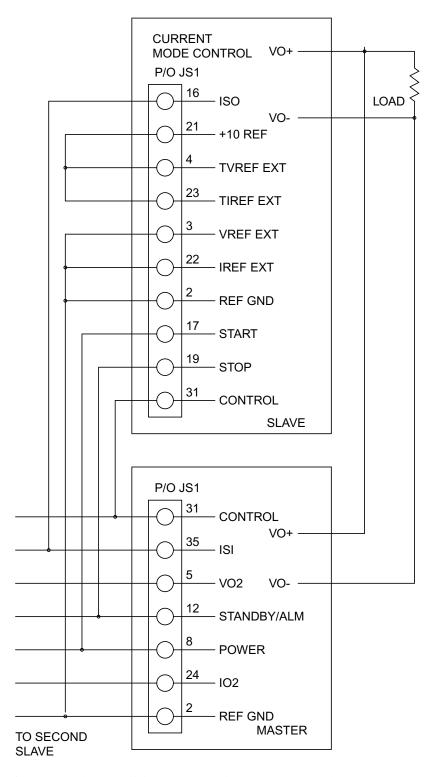


Fig. 5.1: Master-slave parallel DC output and JS1 37-pin external user I/O connections

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- Jumper connection between POWER (Pin 8) of the master power supply to START (Pin 17) of the slave power supplies connects the power output digital control line of the master power supply to the start digital control line of the slave power supplies. This connection causes slave units to turn on when the master unit is turned on.
- Jumper connection between STANDBY/ALM (Pin 12) of the master power supply and STOP (Pin 19) of the slave power supplies connects the STANDBY/ALM digital control line of the master power supply to the STOP digital control line of the slave power supplies. This connection causes the slaves units to turn off when the master unit is turned off or when a diagnostic condition appears.
- Jumper connections between TVREF EXT (Pin 4), +10V REF (Pin 21), IREF EXT (Pin 22), and TIREF EXT (Pin 23) of the slave power supplies sets the slave current control to maximum and sets the voltage trip and over current trip set points just beyond full scale values.

The master unit can configured for rotary, external program, or remote input. The slave power supply must be configured for external program input.

For more information on setting the slave unit to EXT PGM:

- Configuring the product for EXT PGM from the front panel
- Configuring the product for EXT PGM from computer command

To add a second slave unit, connect the output terminals of the second slave in series with the other two power supplies. Furthermore, connect a second control cable between the second slave unit and the master unit, or use an additional *Universal Interface Device (UID47)* accessory from the factory.

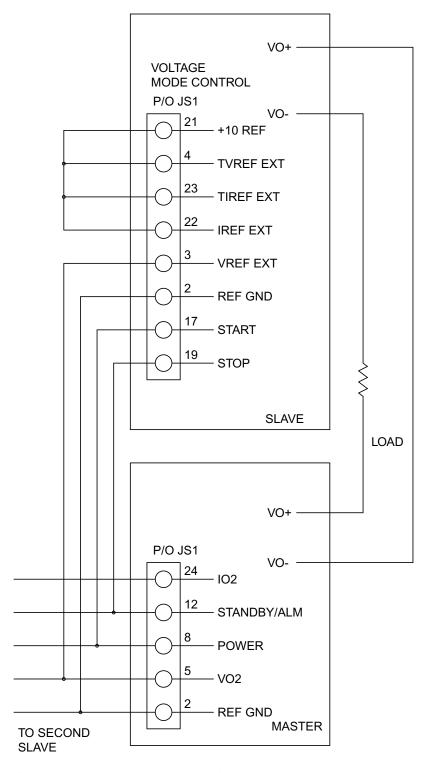


Fig. 5.2: Master-slave series DC output and JS1 37-pin external user I/O connection

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OPERATION: FRONT PANEL

The standard D Version front panel, shown in Fig. 6.1, offers front panel provides a digital display with rotary front panel input, isolated 37-pin analog/digital I/O, and a RS232 computer interface. In addition, the D Version front panel provides digital 10-key entry, auto-sequencing with memory capability, and modulation for non-linear power profile emulation. The C Version front panel, shown in Fig. 6.2, is blank, providing on a switch to enable control power. For the C Version front panel, all control must be performed by the provided isolated 37-pin analog/digital I/O or through a computer interface.

A numbered list corresponding to the indicators on the front panels is located below the front panel figures.



Fig. 6.1: Standard D Version TS Series front panel

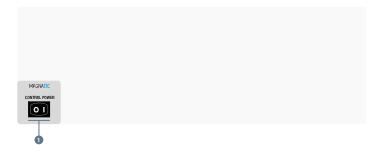


Fig. 6.2: Blank C Version TS Series front panel

- 1. Control Power Switch. Power switch energizes control circuits without engaging main power.
- 2. Start and Stop Buttons. Engages and disengages main power via integrated mechanical contactor.
- 3. **Voltage and Current Displays.** Meters display output voltage, output current, voltage set point, current set point, over voltage trip and over current trip.
- 4. Voltage and Current Knobs. Stepless rotary knob to set voltage and current.
- 5. Status Indicators

• POWER: Indicates power output

• STANDBY: Indicates control power only

6. Configuration Indicators

• REM SEN: Remote sense enabled. See Remote Sense Connection for more information.

• INT CTL: Front panel start/stop/clear enabled

• EXT CTL: External start/stop/clear enabled

• ROTARY: Front panel rotary knob input

• **KEYPAD:** 10-digit keypad control is enabled

• EXT PGM: External analog voltage-current control

• **REMOTE:** Computer control

7. Diagnostic Alarms

• LOC: Interlock

• PGL: External input voltage beyond limits

• PHL: Indicates input AC phase loss

• THL: Over-temperature condition

• **OVT:** Over-voltage protection has tripped

• OCT: Over-current protection has tripped

• FSE: Indicates a fuse has cleared

8. Function Keys.

• MENU: Selects function

• ITEM: Selects item within function

• **DISPLAY:** Displays voltage and current set points. Also functions as the up arrow.

• TRIP DIS: Displays OVT and OCT set points Also functions as the down arrow.

• CLEAR: Clears settings or resets fault

• ENTER: Select item

• MEM: Sets the memory location for auto-sequencing

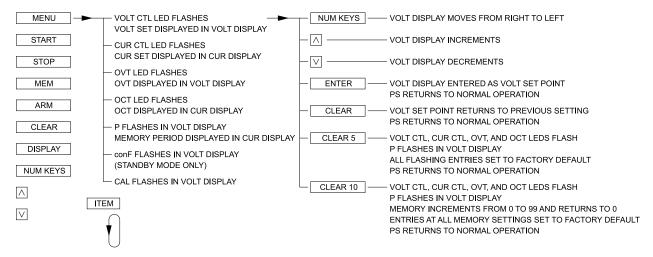
By factory deafult, the TS Series MagnaDC power supply is configured for local sensing, rotary control, internal programming, and voltage input as specified on the rear serial label. TS Series power supplies with the C Version front panel cannot be controlled through the front panel other than engaging the control power using the black rocker switch. While in ROTARY configuration, the front panel voltage and current controls set the boundary limits for output voltage and current, respectively. The following sections describe how to use all of the front panel features. Front panel commands are broken into four groups: run mode commands, set point commands, configuration commands, and calibration commands.

6.1 Setting Set Points

6.1.1 Voltage

When in KEYPAD mode, the voltage set point can be programmed using the numeric keypad or up/down arrows.

MENU Button → Keypad to enter number, Up Arrow to raise, Down Arrow to lower, ENTER Button to save



NOTES:

- 1. CLEAR 5: CLEAR PRESSED FOR 5 SECONDS
- 2. CLEAR 10: CLEAR PRESSED FOR 10 SECONDS

Fig. 6.3: Set the voltage set point from the front panel in KEYPAD mode

6.1.2 Current

When in KEYPAD mode, the current set point can be programmed using the numeric keypad or up/down arrows.

 $MENU\ Button o ITEM\ Button o Keypad\ to\ enter\ number,\ Up\ Arrow\ to\ raise,\ Down\ Arrow\ to\ lower,\ ENTER\ Button\ to\ save$

6.1.3 Period

When in *KEYPAD mode*, program the period (seconds), which is the time interval for the present voltage and current set points, when using the auto-sequencing functionality.

MENU Button \rightarrow ITEM Button $x4 \rightarrow$ Keypad, Up Arrow to raise, Down Arrow to lower, ENTER Button to save

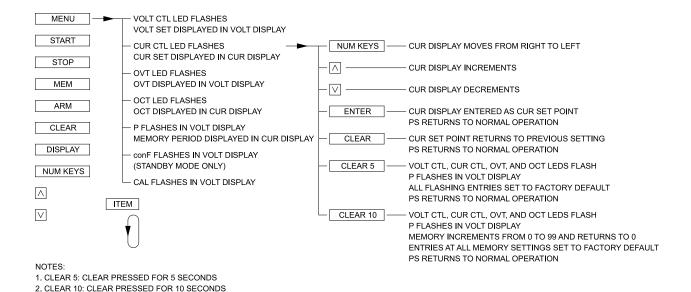


Fig. 6.4: Set the current set point from the front panel in KEYPAD mode

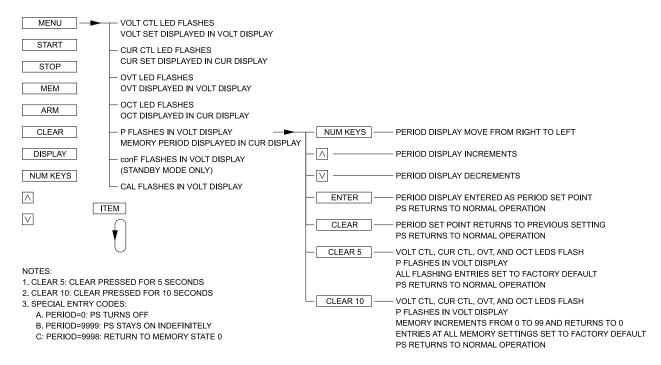


Fig. 6.5: Set the period (PER) from the front panel

6.2 Setting Trip Points

6.2.1 Over Voltage Trip

Program the voltage trip setting used to shut the product off with a fault. The product must be in ROTARY set point source to program over voltage trip from the front panel.

MENU Button \rightarrow ITEM Button $x2 \rightarrow$ ENTER Button \rightarrow Up Arrow to raise, Down Arrow to lower, ENTER Button to save

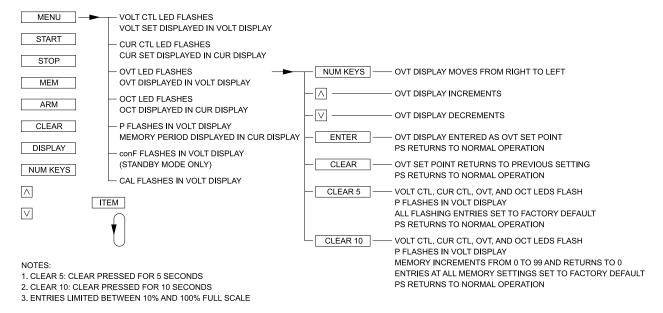


Fig. 6.6: Set the over voltage trip (OVT) from the front panel

6.2.2 Over Current Trip

Program the current trip setting used to shut the product off with a fault. The product must be in ROTARY set point source to program over current trip from the front panel.

MENU~Button
ightarrow ITEM~Button~x3
ightarrow ENTER~Button
ightarrow Up~Arrow~to~raise,~Down~Arrow~to~lower,~ENTER~Button~to~save

6.3 Configuring Set Point Source

The set point source determines where the TS Series MagnaDC power supply will receive its voltage, current, over voltage trip, and over current trip set points. The instructions below detail how to enable the various set point source configurations. Only one set point source can be enabled at a time.

Note: The product must be in Standby when configuring the set point source.

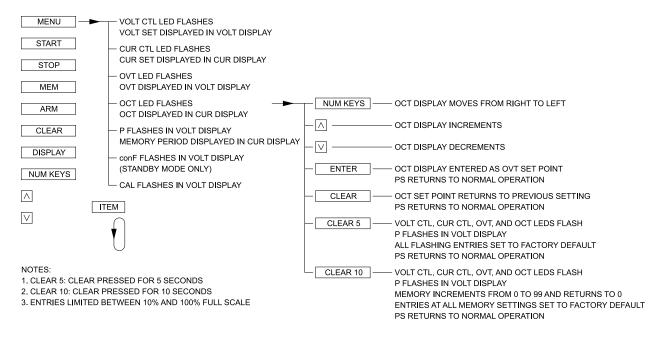


Fig. 6.7: Set the over current trip (OCT) from the front panel

6.3.1 Rotary (ROTARY)

Set point control from the front panel knobs.

 $MENU~Button \rightarrow ITEM~Button~x5 \rightarrow ENTER~Button \rightarrow ITEM~Button~x3 \rightarrow ENTER~Button~(Enable)$

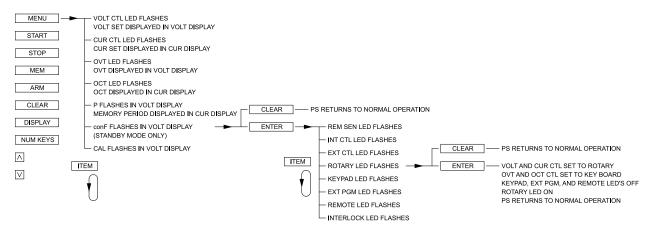


Fig. 6.8: Enable rotary (ROTARY) set point source from the front panel

6.3.2 Keypad (KEYPAD)

Set point control from the front panel 10-digit keypad or through memory auto-sequencing

 $MENU~Button \rightarrow ITEM~Button~x5 \rightarrow ENTER~Button \rightarrow ITEM~Button~x4 \rightarrow ENTER~Button~(Enable)$

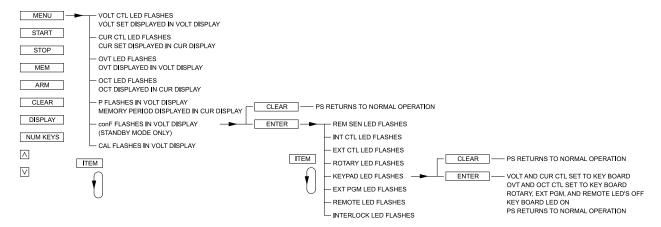


Fig. 6.9: Enable keypad (KEYPAD) set point source from the front panel

6.3.3 External Program (EXT PGM)

Set point control from the 0-10V analog inputs on the JS1 external user I/O connector.

 $MENU~Button \rightarrow ITEM~Button~x5 \rightarrow ENTER~Button \rightarrow ITEM~Button~x5 \rightarrow ENTER~Button~(Enable)$

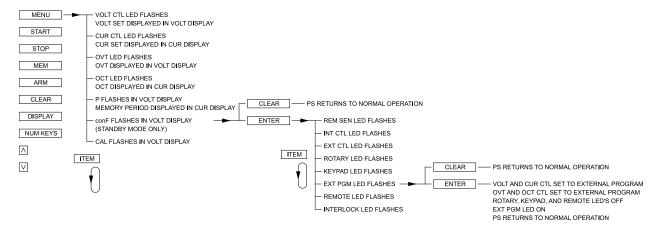


Fig. 6.10: Enable external program (EXT PGM) set point source from the front panel for external user I/O control

6.3.4 Remote (REMOTE)

Set point control from any computer interface.

 $MENU~Button \rightarrow ITEM~Button~x5 \rightarrow ENTER~Button \rightarrow ITEM~Button~x6 \rightarrow ENTER~Button~(Enable)$

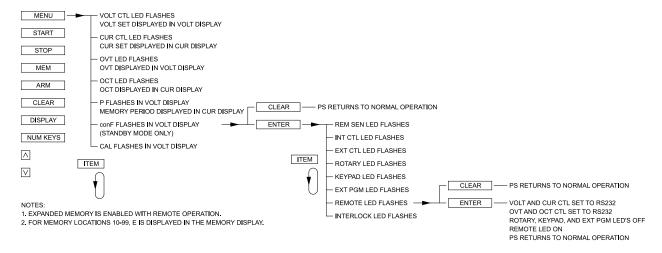


Fig. 6.11: Enable remote (REMOTE) computer programming set point source from the front panel

6.4 Configuring Functionality

6.4.1 Remote Sense (REM SEN)

Set the product to enable or disable voltage sensing from the high impedance *remote sense leads*, to provide compenstation for voltage drop in the cables.

 $MENU\ Button
ightarrow ITEM\ Button\ x5
ightarrow ENTER\ Button
ightarrow ENTER\ Button\ (Enable)\ or\ CLEAR\ Button\ (Disable)$

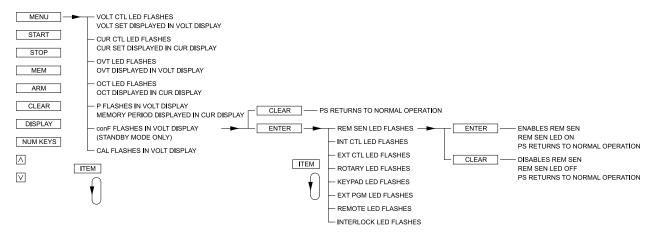


Fig. 6.12: Enable or disable remote sense functionality

6.4.2 Internal Control (INT CTL)

Allows for front panel control of Start, Stop, and Clear functions.

 $MENU\ Button \rightarrow ITEM\ Button\ x5 \rightarrow ENTER\ Button \rightarrow ITEM\ Button\ x1 \rightarrow ENTER\ Button\ (Enable)\ or\ CLEAR\ Button\ (Disable)$

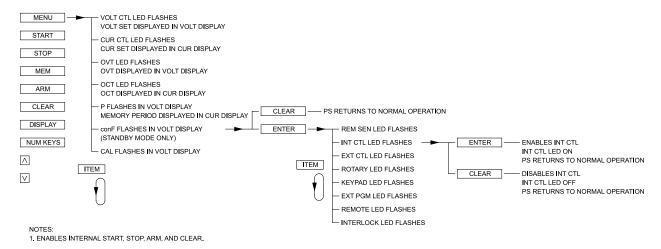


Fig. 6.13: Enable or disable internal control functionality

6.4.3 External Control (EXT CTL)

Allows for JS1 37-pin external user I/O digital input control of Start, Stop, and Clear functions.

 $MENU~Button \rightarrow ITEM~Button~x5 \rightarrow ENTER~Button \rightarrow ITEM~Button~x2 \rightarrow ENTER~Button~(Enable)~or~CLEAR~Button~(Disable)$

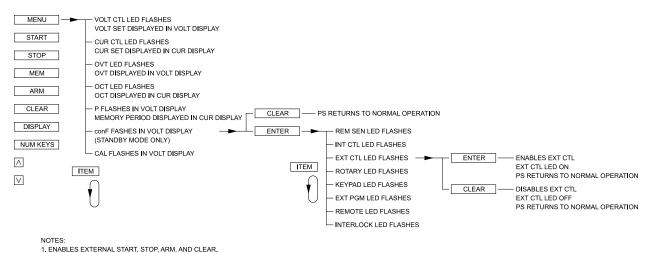


Fig. 6.14: Enable or disable external control functionality

6.4.4 Interlock (LOC)

Enable or disable interlock functionality.

 $MENU~Button \rightarrow ITEM~Button~x5 \rightarrow ENTER~Button \rightarrow ITEM~Button~x7 \rightarrow ENTER~Button~(Enable)~or~CLEAR~Button~(Disable)$

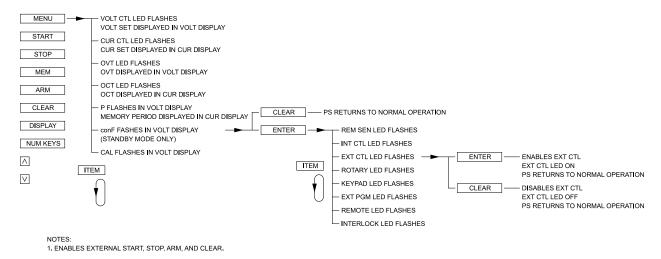


Fig. 6.15: Enable or disable interlock functionality

6.5 Calibration

This section details how to access and change the digital calibration potentiometers from the front panel. For more details on the calibration procedure for the TS Series MagnaDC power supply, refer to *Calibration*.

Fig. 6.16 illustrates how to utilize the calibration commands using the front panel. Calibration commands allow calibration of five digital potentiometers, display of the firmware and hardware revisions, and reset the digital potentiometers to the factory calibration settings. All of these commands can be made when the power supply is in either the standby or power mode state.

To enter the calibration commands, first press the menu key. The over voltage trip LED will initially flash. Then press the item key 3 times. The voltage display will flash CAL (calibration). Press enter for 10 seconds or press clear to exit the calibration command menu. Upon entering the calibration commands, the output voltage will be displayed in the voltage display, the potentiometer setting, 0 to 255, will be displayed in the right three digits of the current display, and P and 1 will alternately flash in the left digit of the current display. Potentiometer 1 adjusts the gain of the voltage feedback amplifier, potentiometer 2 adjusts the input offset voltage of the voltage feedback amplifier, potentiometer 3 adjusts the gain of the current feedback amplifier, and potentiometer 5 adjusts the gain of the reference which is used for the digital to analog and analog to digital converters.

Pressing the item key advances control to potentiometer 2. The left digit of the current display will alternately flash P and 2, the output voltage will be displayed in the voltage display, and the potentiometer setting, 0 to 255, will be displayed in the right three digits of the current display.

Pressing the item key again will advance the control to potentiometer 3. Now the output current will be displayed in the current display, the potentiometer setting, 0 to 255, will be displayed in the right three digits of the voltage display, and the left digit of the voltage display will alternately flash P and 3.

Press the item key again will advance to control potentiometer 4. The left digit of the voltage display will alternately flash P and 4, the output current will be displayed in the current display, and potentiometer, 0 to 255, will be displayed

in the right three digits of the voltage display.

To advance adjustment to potentiometer 5, press the item key again. The left digit of the current display will alternately flash P and 5, the output voltage will be displayed in the voltage display, and the potentiometer setting, 0 to 255, will be displayed in the right three digits of the current display.

Once a digital potentiometer has been selected for adjustment, pressing the up/down keys increments or decrements the potentiometer setting, respectively. To save the new setting, press the enter key or press the clear key to exit the routine. Instructions for the calibration procedure are discussed in *Calibration*.

After selecting digital potentiometer 5, pressing the item key displays the firmware revision in the voltage display and the hardware revision in the current display. Pressing the item key again displays dEF (default) in the voltage display. Pressing the enter key resets the five digital potentiometers to the factory default settings.

To exit the calibration menu, press the item key until rEt (return) appears in the voltage display. Press the enter key to exit the calibration menu.

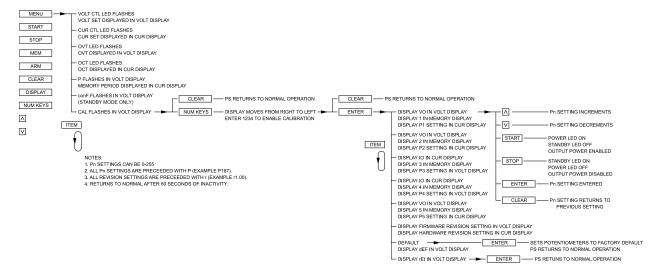


Fig. 6.16: Front panel calibration menu

6.5. Calibration 89

OPERATION: EXTERNAL USER I/O

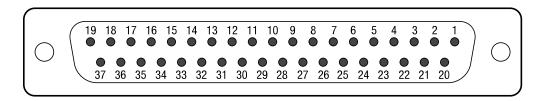


Fig. 7.1: TS Series MagnaDC power supply D-Sub JS1 37-pin external user I/O connector (female) pin numbering

Table 7.1: Complete pin listing and definitions available on the JS1 37-pin external user I/O port

| User I/O Pin | Definition | Signal Type | Description |
|-----------------|------------------|----------------------|---|
| 1 | REF GND | Reference Ground | Ground to be used as analog voltage input-output reference |
| 2 | REF GND | Reference Ground | Ground to be used as analog voltage input-output reference |
| 7 | GND | Ground | Ground to be used as digital input-output reference |
| 6 | +2.5V REF CAL | Reference Voltage | 2.5 V reference voltage used for calibration purposes |
| 21 | +10V REF | Reference Voltage | 10.0 V reference supply, relative to the REF GND pins. Reference capable of supplying a maximum of 25 mA. |
| 26 | +5V REF | Reference Voltage | 5.0 V reference supply, relative to the REF GND pins. Reference capable of supplying a maximum of 25 mA. |
| 3 | VREF EXT | Analog Input | External voltage set point reference, 0-10 Vdc , proportional to the power supply output voltage. 0 Vdc on VREF EXT is equivalent to 0 Vdc output voltage, and 10 Vdc is equivalent to 100% full scale output voltage. |
| 4 | TVREF EXT | Analog Input | External over voltage trip set point reference, 0-10 Vdc , proportional to the power supply output voltage. 0 Vdc on TVREF EXT is equivalent to 0 Vdc trip reference, and 10 Vdc is equivalent to 110% full scale voltage over voltage trip. |
| 22 | IREF EXT | Analog Input | External current set point reference, 0-10 Vdc , proportional to the power supply output current. 0 Vdc on IREF EXT is equivalent to 0 Adc output current, and 10 Vdc is equivalent to 100% full scale output current. |

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Table 7.1 – continued from previous page

| 11 | Definition | | - continued from previous page |
|-----------------|------------|---------------------|--|
| User I/O Pin | Definition | Signal Type | Description |
| 23 | TIREF EXT | Analog Input | External over current trip set point reference, 0-10 Vdc , proportional to the power supply output current. 0 Vdc on TIREF EXT is equivalent to 0 Adc trip reference, and 10 Vdc is equivalent to 110% full |
| | | | scale current over voltage trip. |
| 25 | VMOD | Analog Input | Modulation voltage input for non-linear profile emulation or voltage/current addition, subtraction, or multiplication factors. |
| 5 | VO2 | Analog Out- | Output voltage reference, 0-10 Vdc , proportional to the power sup- |
| | | put | ply's real-time output voltage. 0 Vdc on VO2 is equivalent to 0 Vdc |
| | | | output voltage and 10 Vdc is equivalent to 100% full scale output voltage. |
| 24 | IO2 | Analog Out- | Output current reference, 0-10 Vdc , proportional to the power sup- |
| | | put | ply's real-time output current. 0 Vdc on IO2 is equivalent to 0 Vdc |
| | | | output current and 10 Vdc is equivalent to 100% full scale output |
| 1.7 | CT A DT | D1 1 1 1 1 | current. |
| 17 | START | Digital Input | Enables the power supply output. The input contactors are engaged |
| 18 | CLEAR | Digital Input | and the power supply will ramp up to the programmed set points. Clears a fault condition, returning the power supply to standby. |
| 19 | STOP | Digital Input | Disables the power supply output. The input contactors are disen- |
| 17 | 3101 | Digital Input | gaged and the power supply will ramp down to zero voltage and cur- |
| | | | rent. |
| 36 | ARM | Digital Input | Activates autosequencing through memory states. Function only |
| | | | available on the D Version front panel for TS Series, MS Series, |
| | | | and MT Series products. |
| 37 | INTERLOCK | Digital Input | 5 Vdc input for interlock signal. If the power supply output is en- |
| | SET | | abled, and the +5 Vdc signal is removed, the power supply will enter |
| | | | into LOC fault condition, and the AC contactors will disengage. The |
| | | | fault will need to be cleared before re-enabling the output. Interlock |
| 0 | DOWED | Di i I O i | must be enabled to use this functionality. |
| 8 | POWER | Digital Out- put | Indication that the power supply output is enabled. |
| 9 | THERMAL | Digital Out- | Indication that the input power processing devices or output rectifiers |
| | | put | have reached a critical temperature. A resetting thermal switch will |
| 10 | INTEDL OCK | Distant Osa | reset upon cooling. |
| 10 | INTERLOCK | Digital Out- | Indication that the power supply reached a interlock fault condition. This pin will stay active until 5.0 V is restored to INTERLOCK SET |
| | | put | (Pin 37) and the fault is cleared. To restart the supply after the fault |
| | | | has been cleared, simply press the start switch. |
| 11 | CUR CTL | Digital Out- | Indication that the power supply is operating in current-mode con- |
| | | put | trol. |
| 12 | STANDBY/AL | | Indication that the power supply is in standby or alarm condition. In |
| | | put | both states, the output is disengaged. |
| 13 | ALM | Digital Out- | Indication that the power supply is in alarm condition resulting from |
| | | put | a fault. The alarm will need to be cleared before re-enabling the |
| 1.4 | EXTE CET | Di i I O | output. |
| 14 | EXT CTL | Digital Out- | Indication that external start, stop, and clear is activated for use. |
| | | put | |

continues on next page

Table 7.1 – continued from previous page

| | Signal 1 | vne | Description |
|------------|--|---|--|
| Definition | Oigiliai i | ypo | 2000.11.01.1 |
| FUSE | Digital | Out- | Indication that the fuse alarm is activated. In units where circuit |
| | | | breakers are present, in place of fuses, an open circuit breaker con- |
| | | | nection will trigger the fuse alarm. Fuse alarm is only applicable in |
| | | | TS Series, MS Series, and MT Series power supplies. |
| PGM LINE | Digital | Out- | Indication that an analog input signal is beyond the range of control |
| | put | | (greater than 12.50 V). These lines are constantly monitored and if |
| | | | any of these references are set above the normal bounds, program |
| | | | line diagnostics will disable the supply. |
| STANDBY | Digital | Out- | Indication that the control circuits are powered, but the supply is dis- |
| | put | | abled through the AC contactor. This is the power supply's normal |
| | | | off condition. To start the supply, press the start switch. To place the |
| | | | supply in standby, press the stop switch. |
| PHASE LOSS | | Out- | Indication that there's a problem with the power mains voltage. |
| | put | | Phase loss alarm is only applicable in XR Series, TS Series, MS |
| | | | Series, and MT Series power supplies. |
| VOLT CTL | _ | Out- | Indication that the power supply is operating in voltage-mode con- |
| | | | trol. |
| OCT | | Out- | Indication that the supply has exceeded the over current trip refer- |
| | put | | ence. This condition causes the supply to shutdown into a fault state. |
| | | | To clear this condition, the user must press the clear button on the |
| | | | front panel with internal control enabled or by applying 5.0 V to |
| | | | CLEAR (Pin 18) of JS1 with external control enabled. To restart the |
| | | | supply after the fault has been cleared, simply press the start switch. |
| | | | A secondary over current trip diagnostic provides protection of in- |
| | | | ternal circuitry due to abnormal line and load conditions or due to |
| | | | failed internal circuitry. This over current trip condition requires the |
| | | | control power to be recycled by toggling the power switch off and |
| INT CTI | Digital | Out | on. Indication that front panel start, stop, and clear is activated for use. |
| INICIL | | Oui- | indication that from paner start, stop, and clear is activated for use. |
| OVT | ^ | Out- | Indication that the supply has exceeded the over voltage trip refer- |
| | _ | | ence. This condition causes the supply to shutdown into a fault state. |
| | Ĭ | | To clear this condition, the user must press the clear button on the |
| | | | front panel with internal control enabled or by applying 5.0 V to |
| | | | CLEAR (Pin 18) of JS1 with external control enabled. To restart the |
| | | | supply after the fault has been cleared, simply press the start switch. |
| | PGM LINE STANDBY PHASE LOSS VOLT CTL OCT | PGM LINE Digital put STANDBY Digital put PHASE LOSS Digital put VOLT CTL Digital put OCT Digital put INT CTL Digital put | PGM LINE Digital Output STANDBY Digital Output PHASE LOSS Digital Output VOLT CTL Digital Output OCT Digital Output INT CTL Digital Output OVT Digital Output OVT Digital Output Output OUT |

7.1 Analog Inputs

Table 7.2: Analog inputs available on the JS1 37-pin external user I/O connector

| User I/O Pin | Definition | Description |
|-----------------|------------|---|
| 3 | VREF EXT | External voltage set point reference, 0-10 Vdc , proportional to the power supply output voltage. 0 Vdc on VREF EXT is equivalent to 0 Vdc output voltage, and 10 Vdc is equivalent to 100% full scale output voltage. |
| 4 | TVREF EXT | External over voltage trip set point reference, 0-10 Vdc , proportional to the power supply output voltage. 0 Vdc on TVREF EXT is equivalent to 0 Vdc trip reference, and 10 Vdc is equivalent to 110% full scale voltage over voltage trip. |
| 22 | IREF EXT | External current set point reference, 0-10 Vdc , proportional to the power supply output current. 0 Vdc on IREF EXT is equivalent to 0 Adc output current, and 10 Vdc is equivalent to 100% full scale output current. |
| 23 | TIREF EXT | External over current trip set point reference, 0-10 Vdc , proportional to the power supply output current. 0 Vdc on TIREF EXT is equivalent to 0 Adc trip reference, and 10 Vdc is equivalent to 110% full scale current over voltage trip. |
| 25 | VMOD | Modulation voltage input for non-linear profile emulation or voltage/current addition, subtraction, or multiplication factors. |

The TS Series MagnaDC power supply has 5 analog inputs, as detailed in Table 7.2. These analog inputs can accept 0-10 V input signals and have a 10 k input impedance.

To use the analog inputs, the TS Series MagnaDC power supply must be configured for External Program (EXT PGM). When properly enabled, the EXT PGM LED on the front panel will be illuminated. EXT PGM status can also be queried by computer command. For more information on enabling EXT PGM:

- Enabling EXT PGM from the front panel
- Enabling EXT PGM from computer command

Once enabled, all voltage and current programming along with trip reference programming must be done by the JS1 external user I/O connector. Ensure that VREF EXT (Pin 3), TVREF EXT (Pin 4), IREF EXT (Pin 22), and TIREF EXT (Pin 23) are all connected to a programming signal. In most applications, three of the four analog input references are jumpered to the +10V REF (Pin 21) with the user supplied external reference signal used for the remaining signal.

For the best possibility fidelity for analog programming, use the reference ground REF GND (Pin 1 or Pin 2) as the reference for voltage programming inputs VREF EXT (Pin 3) and TVREF EXT (Pin 4) and current programming inputs IREF EXT (Pin 22) and TIREF EXT (Pin 23).

7.1.1 External Voltage Source Programming

For programming using a voltage source, an external 10.0 V voltage source is placed between VREF EXT (Pin 3) and REF GND (Pin 1) of JS1 to control the output voltage.

The current set point, over voltage trip, and over current trip can be programmed in the same manner. Referring to the *Analog Inputs* pin identification, use IREF EXT (Pin 22) to program the current set point, TVREF EXT (Pin 4) to program over voltage trip, and TIREF EXT (Pin 23) to program over current trip. The power supply has been calibrated to produce full scale output voltage and current with 10.0 V inputs at the external reference input terminals. Furthermore, over voltage and over current trip have been calibrated to trip at 110% full scale output voltage and current with 10.0 V inputs at the external reference input terminals. Most commonly, IREF EXT (Pin 22), TVREF EXT (Pin 4), and TIREF EXT (Pin 23) are all jumpered together and tied to +10V REF (Pin 21).

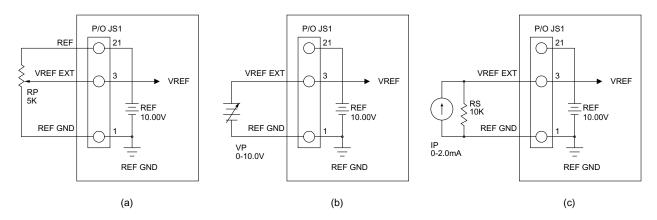


Fig. 7.2: External (a) resistive, (b) voltage, and (c) current programming

7.1.2 External Current Source Programming

To produce an external analog voltage reference to VREF EXT (Pin 3), a current source is applied to a shunt resistor. Using a 2 mA current source, place a 10.0 k precision metal film resistor between VREF EXT (Pin 3) and REF GND (Pin 1). The input impedance between terminals 1 and 3 is 10.0 K and paralleling the additional resistor produces an equivalent resistance of 5 K. The 2 mA current source will produce 10.0 V at the external voltage reference input which will produce full scale output voltage.

The current set point, over voltage trip, and over current trip can be programmed in the same manner. Referring to the *Analog Inputs* pin identification, use IREF EXT (Pin 22) to program the current set point, TVREF EXT (Pin 4) to program over voltage trip, and TIREF EXT (Pin 23) to program over current trip. The power supply has been calibrated to produce full scale output voltage and current with 10.0 V inputs at the external reference input terminals. Furthermore, over voltage and over current trip have been calibrated to trip at 110% full scale output voltage and current with 10.0 V inputs at the external reference input terminals. Most commonly, IREF EXT (Pin 22), TVREF EXT (Pin 4), and TIREF EXT (Pin 23) are all jumpered together and tied to +10V REF (Pin 21).

7.1.3 External Resistive Source Programming

Resistive programming requires connection of an external potentiometer or resistors between +10V REF (Pin 21), VREF EXT (Pin 3), and REF GND (Pin 1) of the JS1 connector. +10V REF (Pin 21) is a 10.0 V precision reference, REF GND (Pin 1) is the reference ground, and VREF EXT (Pin 3) is the voltage set point input. Like front panel rotary control, the precision reference produces a voltage across the potentiometer or resistors which is then used to produce the voltage set point. Metal film resistors or a wire wound potentiometer will result in the lowest temperature coefficient.

The current set point, over voltage trip, and over current trip can be programmed in the same manner. Referring to the *Analog Inputs* pin identification, use IREF EXT (Pin 22) to program the current set point, TVREF EXT (Pin 4) to program over voltage trip, and TIREF EXT (Pin 23) to program over current trip. The power supply has been calibrated to produce full scale output voltage and current with 10.0 V inputs at the external reference input terminals. Furthermore, over voltage and over current trip have been calibrated to trip at 110% full scale output voltage and current with 10.0 V inputs at the external reference input terminals. Most commonly, IREF EXT (Pin 22), TVREF EXT (Pin 4), and TIREF EXT (Pin 23) are all jumpered together and tied to +10V REF (Pin 21).

7.1. Analog Inputs 95

7.2 Analog Outputs

Table 7.3: Analog outputs available on the JS1 37-pin external user I/O port

| User I/O Pin | Definition | Description |
|-----------------|------------|---|
| 5 | VO2 | Output voltage reference, 0-10 Vdc , proportional to the power supply's real-time output voltage. 0 Vdc on VO2 is equivalent to 0 Vdc output voltage and 10 Vdc is equivalent to 100% full scale output voltage. |
| 24 | IO2 | Output current reference, 0-10 Vdc , proportional to the power supply's real-time output current. 0 Vdc on IO2 is equivalent to 0 Vdc output current and 10 Vdc is equivalent to 100% full scale output current. |

Two analog outputs are provided for monitoring output voltage and current on the JS1 37-pin external user I/O connector. As illustrated in Fig. 7.3, output monitoring voltage, VO2 (Pin 5), can be obtained by monitoring the voltage between terminals VO2 (Pin 5) of JS1 and REF GND (Pin 1 or Pin 2) of JS1. Output monitoring current, IO2 (Pin 24), can be obtained by monitoring the voltage between terminals IO2 (Pin 24) of JS1 and REF GND (Pin 1 or Pin 2) of JS1. Like the programming inputs, full scale output voltage and current will produce 10.0 V. The output impedance of the analog monitoring terminals is 100.

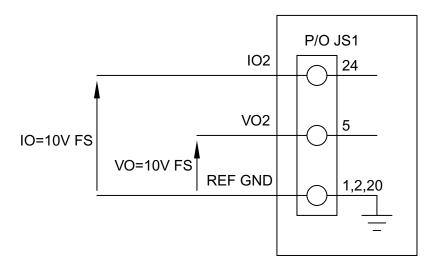


Fig. 7.3: External monitoring output (a) voltage and (b) current

7.3 Digital Inputs

Table 7.4: Digital inputs available on the JS1 37-pin external user I/O port

| | D (' ''' | | |
|---------|------------|--|--|
| User | Definition | Description | |
| I/O Pin | | | |
| 17 | START | Enables the power supply output. The input contactors are engaged and the power | |
| | | supply will ramp up to the programmed set points. | |
| 18 | CLEAR | Clears a fault condition, returning the power supply to standby. | |
| 19 | STOP | Disables the power supply output. The input contactors are disengaged and the power | |
| | | supply will ramp down to zero voltage and current. | |
| 36 | ARM | Activates autosequencing through memory states. Function only available on the D | |
| | | Version front panel for TS Series, MS Series, and MT Series products. | |
| 37 | INTERLOCK | 5 Vdc input for interlock signal. If the power supply output is enabled, and the +5 | |
| | SET | Vdc signal is removed, the power supply will enter into LOC fault condition, and the | |
| | | AC contactors will disengage. The fault will need to be cleared before re-enabling the | |
| | | output. Interlock must be enabled to use this functionality. | |

All digital input lines are located on the JS1 37-pin external user I/O connector located on the rear panel. As illustrated in Fig. 7.4, the digital input lines are START (Pin 17), STOP (Pin 19), CLEAR (Pin 18), and INTERLOCK SET (Pin 37). Functionally, the digital input control lines emulate the functions on the front panel when external control (EXT CTL) is enabled, indicated by the EXT CTL light on the front panel. Digital control lines may be paralleled with other supplies to allow simultaneous control. For more information on enabling EXT CTL:

- Enabling EXT CTL from the front panel
- Enabling EXT CTL from computer command

All digital input lines are triggered by a external momentary (pulsed) +5V signal. If STOP (Pin 19) is left high, it will take presedence over the START (Pin 17) signal.

A +5V reference (+5V REF) is provided on Pin 26 with respect to ground. This reference voltage can be used in combination with user-supplied dry contacts to trigger the digital inputs.

Interlock set requires a either a physical short between +5V REF (Pin 26) and INTERLOCK SET (Pin 37) of the JS1 37-pin external user I/O connector or application of a +5V source with the positive connection at INTERLOCK SET (Pin 37) of JS1 and the negative connection at GND (Pin 7) of JS1. One of these two connections must be made to enable operation of the power supply. If the interlock connection is broken then the LOC (interlock) fault LED lights, the power supply's internal AC contactor opens, and the unit stops processing power. For more information on Interlock functionality:

• Description of Interlock functionality

7.3. Digital Inputs 97

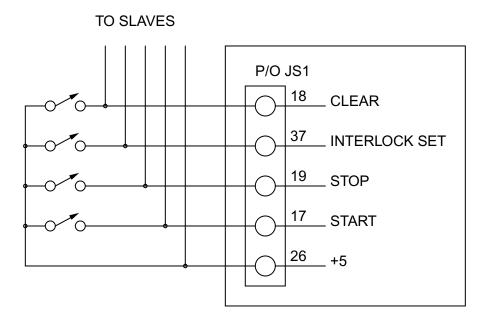


Fig. 7.4: Digital inputs control lines

7.4 Digital Outputs

Table 7.5: Digital outputs available on the JS1 37-pin external user I/O port

| User | Definition | Description |
|---------|------------|---|
| I/O Pin | Deminion | Description |
| 8 | POWER | Indication that the power supply output is enabled. |
| 9 | THERMAL | Indication that the input power supply output is chaored. Indication that the input power processing devices or output rectifiers have reached a |
| | THERWITE | critical temperature. A resetting thermal switch will reset upon cooling. |
| 10 | INTERLOCK | Indication that the power supply reached a interlock fault condition. This pin will stay |
| 10 | INTEREOCK | active until 5.0 V is restored to INTERLOCK SET (Pin 37) and the fault is cleared. |
| | | To restart the supply after the fault has been cleared, simply press the start switch. |
| 11 | CUR CTL | Indication that the power supply is operating in current-mode control. |
| 12 | | MIndication that the power supply is in standby or alarm condition. In both states, the |
| 12 | | output is disengaged. |
| 13 | ALM | Indication that the power supply is in alarm condition resulting from a fault. The alarm |
| | | will need to be cleared before re-enabling the output. |
| 14 | EXT CTL | Indication that external start, stop, and clear is activated for use. |
| 15 | FUSE | Indication that the fuse alarm is activated. In units where circuit breakers are present, |
| | | in place of fuses, an open circuit breaker connection will trigger the fuse alarm. Fuse |
| | | alarm is only applicable in TS Series, MS Series, and MT Series power supplies. |
| 27 | PGM LINE | Indication that an analog input signal is beyond the range of control (greater than 12.50 |
| | | V). These lines are constantly monitored and if any of these references are set above |
| | | the normal bounds, program line diagnostics will disable the supply. |
| 28 | STANDBY | Indication that the control circuits are powered, but the supply is disabled through the |
| | | AC contactor. This is the power supply's normal off condition. To start the supply, |
| | | press the start switch. To place the supply in standby, press the stop switch. |
| 29 | PHASE LOSS | Indication that there's a problem with the power mains voltage. Phase loss alarm is |
| | | only applicable in XR Series, TS Series, MS Series, and MT Series power supplies. |
| 30 | VOLT CTL | Indication that the power supply is operating in voltage-mode control. |
| 32 | OCT | Indication that the supply has exceeded the over current trip reference. This condition |
| | | causes the supply to shutdown into a fault state. To clear this condition, the user must |
| | | press the clear button on the front panel with internal control enabled or by applying |
| | | 5.0 V to CLEAR (Pin 18) of JS1 with external control enabled. To restart the supply |
| | | after the fault has been cleared, simply press the start switch. A secondary over current |
| | | trip diagnostic provides protection of internal circuitry due to abnormal line and load |
| | | conditions or due to failed internal circuitry. This over current trip condition requires |
| 33 | INT CTL | the control power to be recycled by toggling the power switch off and on. |
| 34 | OVT | Indication that front panel start, stop, and clear is activated for use. Indication that the supply has exceeded the over voltage trip reference. This condition |
| 34 | OVI | causes the supply to shutdown into a fault state. To clear this condition, the user must |
| | | press the clear button on the front panel with internal control enabled or by applying |
| | | 5.0 V to CLEAR (Pin 18) of JS1 with external control enabled. To restart the supply |
| | | after the fault has been cleared, simply press the start switch. |
| | 1 | arter the facilities occin cicarea, simply press the start switch. |

All digital output lines are connected to the JS1 37-pin external user I/O connector. Functionally, the digital output lines provide the means to monitor diagnostic functions as functional status. Fig. 7.5 provides terminal identification for the various digital output lines. Each output monitoring line can drive a 5.0 V, 5.0 mA load. An alarm condition will produce a 5.0 V output at the respective terminal.

Table 7.5 provides an explanation of all the available digital output lines.

Diagnostic functions include thermal overload, interlock, power, standby, phase loss, program line, over voltage, and

7.4. Digital Outputs 99

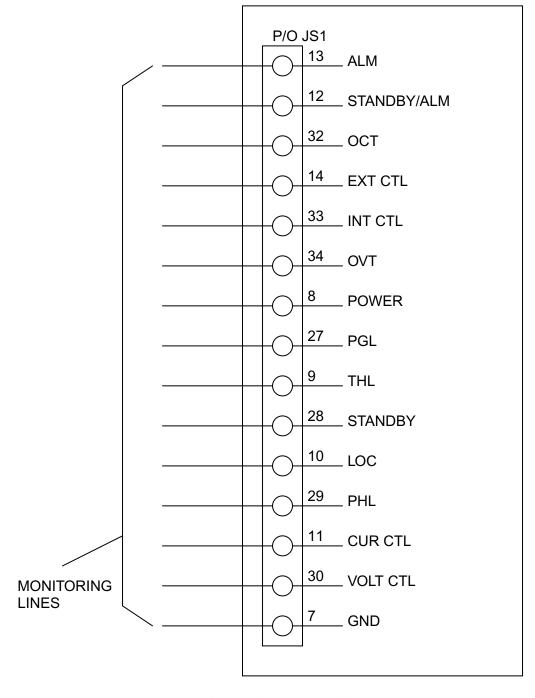


Fig. 7.5: Digital outputs control lines

over current. All diagnostic indicators have memory retention which saves the fault condition until the power supply is reset. To clear a fault condition, the user must press the clear key on the front panel with internal control or by applying +5V to CLEAR (Pin 18) of *JS1* with external control enabled. Alternatively, the supply can be cleared by turning the power supply off and on.

Diagnostic functions and control modes are embedded in the product's closed loop control. The power supply will operate using voltage control or current control depending on which setting is lowest. Voltage control and current control also contain a soft start functionality which causes voltage and/or current to ramp to the desired set point after power is initiated. The soft start circuitry is reset upon power-on or operation of any diagnostic function.

7.5 Reference Signals and Grounds

Definition User Signal Type Description I/O Pin **REF GND** Reference Ground to be used as analog voltage input-output reference Ground 2 **REF GND** Reference Ground to be used as analog voltage input-output reference Ground **GND** Ground Ground to be used as digital input-output reference 6 +2.5V REF Reference +2.5V reference voltage used for calibration purposes **CAL** Voltage 21 +10V REF Reference 10.0 V reference supply, relative to the REF GND pins. Reference capable of supplying a maximum of 25 mA Voltage 26 +5V REF Reference 5.0 V reference supply, relative to the REF GND pins. Reference Voltage capable of supplying a maximum of 25 mA

Table 7.6: Reference signals and grounds on the JS1 37-pin external user I/O port

A variety of reference voltages and grounds are provided on the TS Series MagnaDC power supply *JS1* 37-pin external user I/O connector. Table 7.6 provides an explanation of all the available digital output lines.

The reference grounds (Pin 1, 2; REF GND) are to be used as the reference point for analog inputs and outputs. These ground pins have a series resistance to ground to provide a clean ground reference by mitigate switching noise that may appear on the ground line. It is recommended to use the reference ground pin closest to the analog input or output being used.

The remaining ground (Pin 7; GND) is available as a ground for digital inputs and outputs.

A +5V reference (+5V REF) is provided on Pin 26 with respect to ground. This reference voltage can be used in combination with user-supplied dry contacts to trigger the digital inputs. The +5V REF is capable of supplying a maximum of 25 mA.

A +10V reference (+10V REF) is provided on Pin 21 with respect to ground. While in external program (EXT PGM) mode, this reference voltage can be used to jumper unused analog inputs to their maximum value, instead of providing a user-supplied analog reference voltage. In addition, the +10V REF can be used in conjunction with a user-provided potentiometer for external control at a remote location. The +10V has a 1 impedance and is capable of supplying a maximum of 25 mA.

CHAPTER

EIGHT

OPERATION: COMPUTER PROGRAMMING

There is a variety of methods and interfaces that can be used to program the TS Series MagnaDC power supply from a computer or programmable logic controller. *Standard Commands for Programmable Instrumentation (SCPI)* are provided for basic ASCII interfacing without any necessary drivers. In addition, an IVI-COM Driver is included with the installation CD and is available for download from the Magna-Power Electronics web page for more advanced programming requirements. The driver allows the power supply to communicate through many different programming languages and software environments, namely: Visual C++, Visual C#, Visual Basic .NET, Visual Basic 6.0, LabVIEW, LabWindows/CVI, MATLAB, Measure Foundry, and Agilent VEE Pro. Refer to Section 5.7, "IVI-COM Driver" for further details.

TS Series MagnaDC power supply purchased with optional *LXI TCP/IP Ethernet* (+*LXI*) or *IEEE-488 GPIB* (+*GPIB*) *interfaces* have additional commands and programming instructions.

8.1 Communications Validation

It is import to establish and validate basic communications functions before starting a sophisticated computer interface project. The following instructions are intended to help customers isolate problems with computer settings, wiring, and electrical noise. The validation instructions also provide a common environment for which Magna-Power can reproduce issues in support cases and better serve the customer.

If not already installed, Magna-Power Electronics recommends using the terminal emulation programs called PuTTY for creating serial connections.

These instructions will validate communications over RS232, but the process can be completed over any interface by adjusting the connection settings. To test, make a physical connection between the RS232 connector on the MagnaDC power supply and the RS232 connector on the computer. Pin outs for these connectors are described in RS232.

Open Device Manager and under ports make note of the COM port number, as shown in Fig. 8.1.

Open *PuTTY* and select the *Session* menu. Enter the COM port that was found in *Device Manger* and enter 19200 for the *Speed*. Set the *Connection type* to *Serial*, as shown in Fig. 8.2.

Select the *Terminal* menu and set *Force on* for all options. Press the *Open* button to start the communications session with the MagnaDC power supply, as shown in Fig. 8.3.

Session should open a new blank window. Type the command:

*IDN?

If settings match and wiring connections are correct, the session window should look like Fig. 8.4.

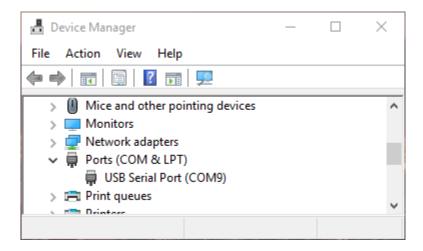


Fig. 8.1: Window Device Manager

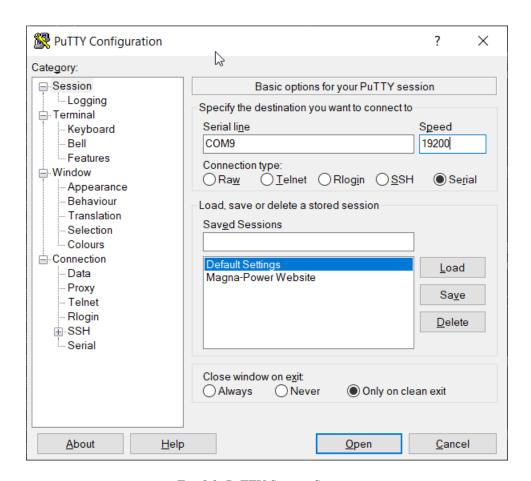


Fig. 8.2: PuTTY Session Settings

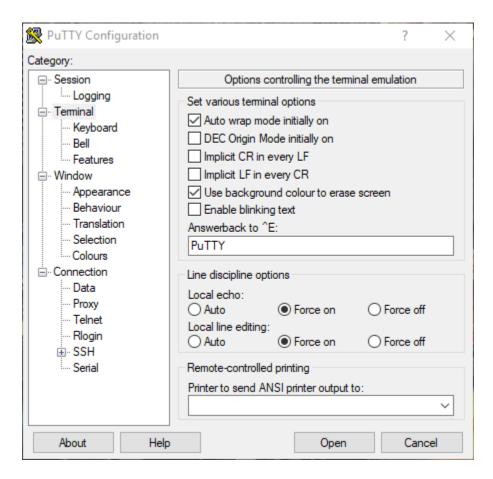


Fig. 8.3: PuTTY Terminal Settings



Fig. 8.4: PuTTY Terminal Session Output

8.2 RS232 Communications

One DB-9 female RS232 port comes standard on all TS Series MagnaDC power supply, which provides the simpliest means to communicate with the power supply. All the commands detailed in *SCPI Command Set* are supported over RS232. Note that LXI TCP/IP Ethernet and IEEE-488 GPIB specific commands will not be available without the respective option.

The RS232 configuration settings are detailed in the following table:

Note: When using external converters that utilize the RS232 port, the settings from Table 5.9, "RS232 Interface Configuration" must be used or the product will not communicate.

The RS232 terminal, connector JS3, is detailed in the following table:

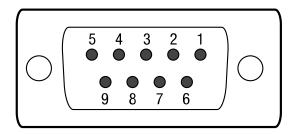


Fig. 8.5: RS232 DB-9 female connector included on the TS Series MagnaDC power supply

| Pin | Definition |
|-----|------------|
| 1 | NC |
| 2 | RX |
| 3 | TX |
| 4 | DTP |
| 5 | GND |
| 6 | DSR |
| 7 | RTS |
| 8 | CTS |
| Q | NC NC |

Table 8.1: RS232 (JS3) Terminal Definition

8.3 LXI TCP/IP Ethernet Communications

MagnaDC programmable DC power supply products are available with an optional LXI TCP/IP Ethernet interface (+LXI). The LXI TCP/IP Ethernet interface meets the LXI Class C, Revision 1.4 standard. When specified at time of order, an Ethernet interface module is installed, providing an embedded Ethernet port for communications.

Ethernet connections can be made Magna-Power supplied software interface application, terminal emulation programs like PuTTY, user written software, National Instruments LabVIEWTM and a wide variety of other software programming interfaces.

8.3.1 Address Negotiation

By default, DHCP is enabled on the MagnaDC power supply. If the Ethernet board does not discover a DHCP server, the MagnaDC power supply will default to the Auto-IP configuration as defined in Table 8.2. The device then automatically selects an IP address from 169.254.###.### and subnet as described in RFC 3927 (Request for Comments 3927 - Dynamic Configuration of IPv4 Link-Local Addresses). This routine is used by most computer operating systems.

| | £ \` |
|-----------------|-------------------|
| IP Address | 169.254.###.### |
| Subnet Mask | 255.255.0.0 |
| Default Gateway | 0.0.0.0 |
| DNS Server | 0.0.0.0 |
| MAC Address | 01:1E:6F:##:##:## |
| Username | admin |
| Password | leave blank |

Table 8.2: Default LXI TCP/IP Ethernet Setting (without DHCP server)

The LAN Reset button provides a way to reset the LAN configuration password and to set the device back to DHCP/Auto-IP mode. To activate the LAN Reset function, ensure the power supply is on and in standby mode. Hold down the LAN Reset button for approximately 4 seconds. Observe that the LAN LED rapidly flashes and after 4 seconds, release the LAN Reset button. The LAN configuration password will be reset to blank and the module will be set to DHCP/Auto-IP enabled.

The MAC address consists of two number groups, in format: ##:##:##:##:##. For Magna-Power Electronics products, the first three bytes are always 01:1E:6F. The second three bytes are determined by the LXI TCP/IP Ethernet interface's serial number, converted to hex. This serial number can be queried from the power supply using the SCPI command SYSTem:COMMunicate:NETwork:SERial.

The LXI TCP/IP Ethernet module supports the mDNS discovery protocol allowing the device to be discovered on the network by software such as National Instruments Measurement and Automation Explorer, Agilent Connection Expert, or the Remote Interface Software supplied with the power supply.

8.3.2 Connectivity

The LAN status LED, located at the rear of the MagnaDC power supply, provides LAN fault and device identification, defined as follows:

On - Normal Operation The device has a properly configured IP address and the network cable is connected.

Flashing - Device Identify The LXI Device Identification function was enabled via the Instrument Identification web page. This identification can help the user to quickly locate the unit and distinguish it from similar devices.

Off - LAN Fault The device is experiencing one or more of the following LAN fault conditions: failure to acquire a valid IP address, detection of a duplicate IP address on the network, failure to renew an already acquired DHCP lease, or the LAN cable is disconnected.

8.3.3 Network discovery

The Ethernet module supports the mDNS discovery protocol allowing the device to be discovered on the network by software such as National Instruments' Measurement and Automation Explorer, Agilent Connection Expert, or the Remote Interface Software (RIS Panel) supplied with the MagnaDC power supply.

NI Measurement and Automation Explorer

To access discovery with NI Measurement and Automation Explorer, the NI-VISA add-on module must be installed along with the standard software package. Start NI Measurement and Automation Explorer, right-click on Devices and Interfaces, and then select "Create New..." Select "VISA TCP/IP Resource" from the list. Click Next and then select Auto-detect of LAN Instrument. Click Next and the software will scan the local network for VXI devices and display them for configuration for further usage with NI-VISA and related software.

Agilent Connection Expert

To access discovery with Agilent Connection Expert, start Agilent Connection Expert. Select your computer's LAN interface and then click the Add Instrument button at the top of the screen. The software will scan the local network for VXI devices and display them for configuration for further use with Agilent VISA compatible software.

Web Browser

The LXI TCP/IP Ethernet interface has an embedded web server that allows the user to view and change the module's network settings. Magna-Power Electronics LXI TCP/IP Ethernet interface is LXI Class C compliant under LXI Standard Revision 1.4.

To access the web server, first determine the module's IP address via one of the discovery methods described in *RIS Panel*. Alternatively, if the host computer supports NetBIOS over TCP/IP, you may use the device's NetBIOS name instead of the IP address.

Open a WC3 compliant web browser such as Google Chrome, Edge (Chromium), or Mozilla Firefox to http://[ipaddress]/ or http://{[}hostname{]}/. The instrument information screen will be displayed as shown in fig-lxi-discovery-web. This figure provides the basic information about the configuration and allows the user to enable or disable the LXI Identification. Click Enable Identify or Disable Identify to change the state of the LXI Identification. When LXI Identification is enabled, the LAN LED on the back of the MagnaDC power supply unit will blink. This can help the user to quickly locate the MagnaDC power supply and distinguish it from similar devices.

To change the Ethernet interface's network settings, click the Configure tab in the upper right. The browser will prompt for a username and password if you have not authenticated the device already. To authenticate, enter admin for the username and leave the password field blank. The instrument configuration screen, *Web interface configuration panel*, will appear. This page enables the user to change the Hostname (which corresponds to the NetBIOS name), the description, password, and TCP/IP configuration. After changes to the configuration are made, click the Save Config button. The configuration will be saved, the Ethernet interface will reboot and instructions will be displayed for reconnecting to the interface.

The browser may prompt for a username and password if you have not authenticated the device already. To authenticate, enter admin for the username and leave the password field blank.

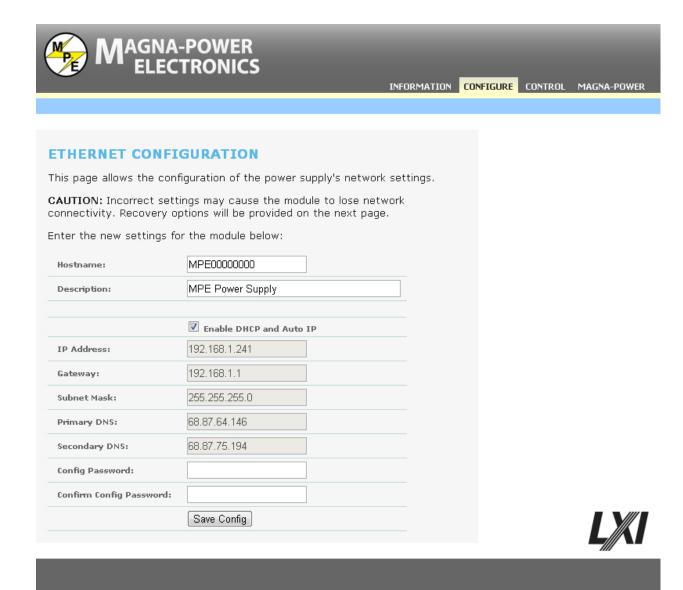


Fig. 8.6: Web interface configuration panel

RIS Panel

Remote Interface Software describes application and configuration of the Remote Interface Software which is shipped with TS Series MagnaDC power supply. This software provides the user with a quick method to operate a MagnaDC power supply under computer control. The software can be configured for a number of communication interfaces; Ethernet is included as one of these interfaces.

To use the Remote Interface Software with optional Ethernet communications, the address parameters in the Remote Interface Software and that encoded in the MagnaDC power supply must match. The factory default for DHCP is 1 (on) allowing the IP address to be automatically set by the DHCP server on the network. If DHCP is off and the address is unknown, the device can be located using the Remote Interface Software supplied with the MagnaDC power supply. To access discovery, press Find Device in the Communication Setup menu. The routine scans all the devices on the network and provides their addresses and identifications. Select the desired device and press OK; this automatically changes the address in the Communication Setup. The same result can be achieved with a double click on the desired device. After communications is established, the address of the device may be changed by pressing Change Device's Settings.

8.4 IEEE-488 GPIB Communications

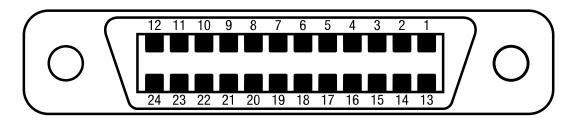


Fig. 8.7: IEEE-488 GPIB connector and pin layout

MagnaDC programmable DC power supply products ere available with an optional IEEE-488 GPIB interface. When specified at time of order, an IEEE-488 GPIB interface module is installed internally, providing an embedded IEEE-488 GPIB port available for communiations. With two UART ports available, RS232 and IEEE-488 GPIB, the one first receiving communications after power on is the port that is activated. Once activated, the other UART port cannot be recognized unless there has been a period of inactivity for 5 minutes. After this period, a new UART port can be recognized by sending communications. The IEEE-488 GPIB terminal, connector JS4, is detailed in

All of the SCPI subsystem commands in the previous section can be initiated using RS232, optional IEEE-488 GPIB (+GPIB), or optional LXI TCP/IP Ethernet (+LXI) communications.

The IEEE-488 standard defines a method for status reporting. As illustrated in [NEED FIGURE], the reporting method uses the IEEE-488 Status Byte (STB). Three bits of this byte are defined as:

- Master Status Summary (MSS) Bit
- Event Status Bit (ESB)
- Message Available (MAV) Bit

The **Master Status Summary (MSS)** is an unlatched bit. When the Status Byte Register is read using a Status Byte Register query, bit 6 will be 1 if there are any conditions requiring service.

The STB is masked by the Service Request Enable Register (SRE) to allow the user to mask specific or all events from setting the MSS bit to 1. The MSS bit is obtained by logical OR'ing the bits of the enabled Status Byte Register.

The **Event Status Bit (ESB)** is set when one of the events defined in the Event Status Register (ESR) [REFERENCE ESR TABLE HERE] has occurred. Like the STB, the ESR is masked by the Event Status Enable Register (ESE) to allow the user to mask specific or all events from setting the ESB to 1.

The Message AVailable (MAV) bit is set to 1 when a message is available in the output buffer.

8.4.1 IEEE-488 GPIB Communications with NI MAX

National Instruments offers Measurement and Automation Explorer (MAX), a Graphical User Interface, as a terminal emulation program for configuring an Interchangeable Virtual Instrument (IVI). MAX is usually installed with one of National Instrument's Application Development Environments such as LabVIEW, Measurement Studio, or with hardware product drivers such as NI-488 and NI-DAQ.

To operate the power supply with MAX, the instrument must first be located for communications. The following steps describe this procedure.

- 1. Run the MAX application program.
- 2. In the Configuration window, press the + sign to the left of Devices and Interfaces to view the installed devices.
- 3. If there is more than one IEEE-488 GPIB device listed, then select the correct GPIB device.
- 4. Press Scan for Instruments on the menu bar and wait several seconds.
- 5. At least one instrument should appear under the GPIB controller. If no instruments appear, then refer to [REF-ERENCE PROGRAMMING GPIB SECTION] to verify the correct setup.
- 6. On the menu bar, press Communicate with Instrument. The NI-488 Communicator dialog box should appear.
- 7. In the NI-488 Communicator dialog box, press the Configure EOS button. The Termination Method dialog box should appear.
- 8. Select the option Send EOI at end of Write. Enter 0 into the EOS byte. Press OK.

Pin Definition Pin Definition DIO1/Data line DIO5/Data line 1 13 2 DIO2/Data line DIO6/Data line 14 3 DIO3/Data line DIO7/Data line 15 4 DIO4/Data line 16 DIO8/Data line 5 EOI/End or Identify 17 REN/Remote Enable DAV/Data Valid 18 DAV/Gnd 6 7 NRFD/Not Ready for Data 19 NRFD/Gnd 8 NDAC/Not Data Accepted 20 NDAC/Gnd 9 IFC/Interface Clear 21 IFC/Gnd 10 SRQ/Service Request 22 SRQ/Gnd ATN/Gnd 11 ATN/Attention 23 Shield 24 Gnd 12

Table 8.3: IEEE-488 GPIB pin definitions

CHAPTER

NINE

CALIBRATION

9.1 Control Board

The control board contains digital potentiometers for fine adjustments of the reference and feedback amplifiers. These potentiometers may be adjusted by using the front panel controls described in *Calibration*. These potentiometers can also be adjusted by using the Calibration Panel of the Remote Interface Software.

9.1.1 Reference Amplifier Calibration

Connect a voltmeter between Pin 6 of JS1 37-pin external user I/O (positive) and Pin 1 of JS1 37-pin external user I/O (negative). With only the control power applied, adjust potentiometer P5 for a 2.5006 V.

9.1.2 Voltage Feedback Amplifier Calibration

Place a DC voltmeter across the output terminals of the power supply and place a second DC voltmeter to monitor VO2, the voltage between Pin 5 of JS1 37-pin external user I/O (positive) and Pin 1 of JS1 37-pin external user I/O (negative). Set the load to 50% rated output current at full scale voltage.

With only the control power applied, adjust potentiometer P2 for 0.000 V at VO2. Using the up/down (V/I DIS or TRIP DIS) keys or RS232 remote interface, set the output voltage to 50% full scale output. Turn on the power supply and adjust potentiometer P1 until the output voltage matches the set point voltage. Now set the output voltage to its full scale rating and measure the output voltage. Adjust potentiometer P1 to equally divide the error between the half scale set point and the full scale point.

9.1.3 Current Feedback Amplifier Calibration

Place a DC ammeter in series with the load of the power supply and place a DC voltmeter to monitor IO2, the voltage between Pin 24 of JS1 37-pin external user I/O (positive) and Pin 1 of JS1 37-pin external user I/O (negative). Set the load to 100% rated output current at 90% full scale voltage.

With only the control power applied, adjust potentiometer P4 for 0.000 V at IO2. Using the up/down (V/I DIS or TRIP DIS) keys or RS232 remote interface, set the output current to 50% full scale output. Turn on the power supply and adjust potentiometer P3 until the output current matches the set point current. Now set the output current to its full scale rating and measure the output current. Adjust potentiometer P3 to equally divide the error between the half scale set point and the full scale point.

9.2 Driver Board

The driver board contains two potentiometers which are used to set under voltage and over current protection in the polyphase chopper circuitry. These potentiometer do not normally need adjustment in the field.

9.2.1 Over Curent Protection

Over current protection should only be calibrated after consultation with the factory.

Caution: Gross misadjustment of the over current protection can cause chopper and inverter failure.

Place a DC voltmeter between test point TP6 (positive) and test point TP7 (negative) on the driver board. With only the control power applied, adjust potentiometer P1 to 6.00 V.

9.2.2 Under Voltage Protection

Under voltage protection should only be calibrated after consultation with the factory.

Caution: Gross misadjustment of the under voltage protection can cause chopper and inverter failure.

Connect the power supply to an adjustable AC source and connect an AC voltmeter to monitor the voltage applied to the input terminals. Tests can be performed under no load conditions. Set the AC source to the power supply's rated input voltage. Turn the control power, press the start switch, and adjust the output voltage to 10% full scale output. Decrease the AC source to a value between 75% to 82% of rated voltage. Adjust potentiometer P2 until the output drops to zero; the transition will be abrupt.

Decrease the AC source to a value between 72% to 79% of rated voltage. The main contactor should turn off.

SCPI COMMAND SET

Standard Commands for Programmable Instrumentation (SCPI) support is provided for all MagnaDC power supply products. These commands provide programming compatibility with other instruments. SCPI commands are ASCII textual strings, which are sent to the instrument over the physical layer, providing support over all communication interfaces. Utilizing these SCPI commands provides the simplest form of programming a MagnaDC power supply product, as they are driver and programming environment independent. Further information about the SCPI standard and conventions are in the section: SCPI Introduction. The full list of linked commands are in section: SCPI Command Reference List.

10.1 SCPI Introduction

10.1.1 Command Structure

There are two types of SCPI messages: program and response.

A *program message* consists of one or more properly formatted SCPI commands sent from the controller to the MagnaDC power supply. The message, which may be sent at any time, requests the MagnaDC power supply to perform some action.

A *response message* consists of data in a specific SCPI format sent from the MagnaDC power supply to the controller. The MagnaDC power supply sends the message only when requested from a program message query.

10.1.2 Data Types

The following datatypes, referenced in the SCPI command descriptions, describe the responses from query SCPI commands:

- <NR1> Digits with an implied decimal point assumed at the right of the least-significant digit. Example: 273
- <NR2> Digits with an explicit decimal point. Example: .0273
- <NR3> Digits with an explicit decimal point and an exponent. Example: 2.73E+2

The following data types, referenced in the SCPI command descriptions, describe the parameters from program SCPI commands:

- <Nrf> Extended format that includes <NR1>, <NR2>, and <NR3>. Examples: 273, 273., 2.73E2
- <Nrf+> Expanded decimal format that includes <NRf> and MIN MAX. MIN and MAX are the minimum and maximum limit values that are implicit in the range specification for the parameter. Examples: 273, 273., 2.73E2, MAX
- **<Bool>** Boolean Data. Example: 0 | 1 or ON | OFF

10.1.3 Termination

A new line <NL> character must be sent to the MagnaDC power supply to terminate a SCPI command string. The IEEE-488 EOI (End-Or-Identify) message is interpreted as a <NL> character and can be used to terminate a command string in place of an <NL>. A carriage return followed by a new line <CR><NL> is also accepted. Command string termination will always reset the current SCPI command path to the root level.

10.1.4 Syntax Conventions

Square brackets [] Used to enclose a parameter that is optional when programming the command; that is, the instrument shall process the command to have the same effect whether the option node is omitted by the programmer or not.

Angle brackets <> Used to enclose mandatory parameters or to indicate a returned parameter. For example, in the CURRent <value> command syntax, the <value> parameter is enclosed in triangle brackets. The brackets are not sent with the command string. You must specify a value for the parameter, for example: CURRent 125

Vertical bar | Used to separate multiple parameter choices for the command string, for example: [SOURce:]CURRent 0 through MAX | MINimum | MAXimum

10.2 SCPI Command Reference List

The subsystems provide more details on all the supported commands. The following table provides a summary of all the available SCPI commands:

| SCPI Command | Description |
|-------------------------------|--|
| MEASure Subsystem | |
| MEASure: VOLTage? | Measures and returns the average voltage at the sense location |
| MEASure: CURRent? | Measures and returns the average current at the sense location |
| OUTPut Subsystem | |
| OUTPut? | Provides the output state of the product |
| OUTPut:ARM | Enables or disables ARM functionality for auto-sequencing |
| OUTPut:START | Enables the power processing circuitry in the product to begin pro- |
| | ducing output |
| OUTPut:STOP | Disables the power processing circuitry in the product to stop pro- |
| | ducing output |
| OUTPut:PROTection:CLEar | Reset soft faults |
| SOURce Subsystem | |
| VOLTage and VOLTage:TRIGgered | Sets the voltage set-point |
| VOLTage:PROTection | Sets the over voltage trip (OVT) set-point |
| CURRent and CURRent:TRIGgered | Sets the current set-point |
| CURRent: PROTection | Sets the over current trip (OCT) set-point |
| PERiod | Sets the time period for present auto-sequencing memory step |
| RECall:MEMory | Selects a memory location for auto-sequencing |
| CONFigure Subsystem | |
| CONTrol:INTernal | Configures the ability start, stop, arm, and clear via the front panel |
| CONTrol:EXTernal | Configures the ability start, stop, arm, and clear via digital inputs |
| | and computer command |
| REMote:SENSe | Configures the sense location and automated compensation values |
| INTErlock | Configures the product's interlock functionality |

continues on next page

Table 10.1 - continued from previous page

| CONFigure:SETPT Configures from which interface the product receives its set points SYSTem Subsystem SYSTem:VERSion? Returns hardware revision and firmware version SYSTem:ERRor? Returns error type and message Returns mumber of errors in queue SYSTem:COMMunicate:NETwork:MAC? Returns MAC address SYSTem:COMMunicate:NETwork:SER Returns Ethernet module serial number SYSTem:COMMunicate:NETwork:AD- DRess SYSTem:COMMunicate:NETwork:GATE Set the static IP address SYSTem:COMMunicate:NETwork:SUBNet SYSTem:COMMunicate:NETwork:PORT Set the socket number SYSTem:COMMunicate:NETwork:DHCP SYSTem:COMMunicate:NETwork:DHCP SYSTem:COMMunicate:GPIB:VERSion Returns firmware version of GPIB module SYSTem:COMMunicate:GPIB:ADDRess STATus Subsystem SCI clear all status register *ESE? Configure Event Status Enable Register *ESER? Read Event Status Register *ESER? Bit values for the running state *IDN? *OPC Operation Complete Bit scpi-status-questionable-condition Returns the value of the Questionable Status register *STE Service Request Enable Register *STE Status Byte Status Byte Status Register Status Status Register Status Register | SCPI Command | Description |
|--|------------------------------------|--|
| SYSTem: VERSion? Returns hardware revision and firmware version SYSTem: VERSion? Returns error type and message scpi-system-error-count Returns number of errors in queue SYSTem: COMMunicate: NETwork: MAC? Returns MAC address SYSTem: COMMunicate: NETwork: SER Returns Ethernet module serial number SYSTem: COMMunicate: NETwork: AD-DRess Set the static IP address SYSTem: COMMunicate: NETwork: GATE Set the Gateway IP address SYSTem: COMMunicate: NETwork: SUBNet Set the subnet IP Mask address SYSTem: COMMunicate: NETwork: HOST-name Return hostname SYSTem: COMMunicate: NETwork: HOST-name Returns firmware version of GPIB module SYSTem: COMMunicate: OPIB: Version Returns address of GPIB module SYSTem: COMMunicate: GPIB: ADDRess Returns address of GPIB module STATus Subsystem Clear all status registers *ESE? Configure Event Status Enable Register *ESR? Read Event Status Register *ESR? Bit values for the running state *IDN? Product identification *OPC Operation Complete Bit scpi-status-questionable-condition Returns the value of the Questionable S | | · |
| Returns hardware revision and firmware version | | Cominguites from which interface the product receives its set points |
| SYSTem:ERRor? Returns error type and message scpi-system-error-count Returns number of errors in queue SYSTem:COMMunicate:NETwork:MAC? Returns MAC address SYSTem:COMMunicate:NETwork:SER Returns Ethernet module serial number SYSTem:COMMunicate:NETwork:AD-DRess Set the static IP address SYSTem:COMMunicate:NETwork:SUBNet Set the Gateway IP address SYSTem:COMMunicate:NETwork:SUBNet Set the subnet IP Mask address SYSTem:COMMunicate:NETwork:PORT Set the socket number SYSTem:COMMunicate:NETwork:HOST-name Return hostname SYSTem:COMMunicate:NETwork:DHCP Set DHCP operation mode SYSTem:COMMunicate:GPIB:VERSion Returns address of GPIB module STATus Subsystem Returns address of GPIB module STATus Subsystem Clear all status registers *ESE? Configure Event Status Enable Register *ESE? Read Event Status Enable Register *ESE? Bit values for the running state *IDN? Product identification *OPC Operation Complete Bit sepi-status-questionable-condition Returns the value of the Questionable Status register *SSTB Service Request Enable Register < | | Returns hardware revision and firmware version |
| scpi-system-error-count SYSTem:COMMunicate:NETwork:MAC? SYSTem:COMMunicate:NETwork:SER SYSTem:COMMunicate:NETwork:AD- DRess SYSTem:COMMunicate:NETwork:AD- DRess SYSTem:COMMunicate:NETwork:GATE SYSTem:COMMunicate:NETwork:GATE SYSTem:COMMunicate:NETwork:SUBNet SYSTem:COMMunicate:NETwork:PORT SYSTem:COMMunicate:NETwork:PORT SYSTem:COMMunicate:NETwork:HOST- name SYSTem:COMMunicate:NETwork:DHCP SYSTem:COMMunicate:NETwork:DHCP SYSTem:COMMunicate:NETwork:DHCP SYSTem:COMMunicate:OFIB:ADDRess Returns firmware version of GPIB module SYSTem:COMMunicate:GPIB:ADDRess Returns address of GPIB module SYSTem:Communicate:GPIB:ADDRess Clear all status registers *ESE? Configure Event Status Enable Register *ESR? *ESR? Bit values for the running state *IDN? Product identification *OPC Operation Complete Bit scpi-status-questionable-condition Returns the value of the Questionable Status register **SSTE Service Request Enable Register **STB Status Byte Scpi-status-register Status Register Status Register Status Register Status Register Status Register Status Register Status Register Status Register Status Register Status Register Status Register Status Register Status Register Status Register Status Register Status Register Status Register Scevete self-test | 12 12 1 11 1 12 11 | |
| SYSTem: COMMunicate: NETwork: MAC? SYSTem: COMMunicate: NETwork: SER SYSTem: COMMunicate: NETwork: AD- DRess SYSTem: COMMunicate: NETwork: GATE Set the static IP address SYSTem: COMMunicate: NETwork: SUBNet SYSTem: COMMunicate: NETwork: SUBNet SYSTem: COMMunicate: NETwork: PORT SYSTem: COMMunicate: NETwork: HOST- name SYSTem: COMMunicate: NETwork: DHCP SYSTem: COMMunicate: NETwork: DHCP SYSTem: COMMunicate: NETwork: DHCP SYSTem: COMMunicate: NETwork: DHCP SYSTem: COMMunicate: OFIB: VERSion SYSTem: COMMunicate: GPIB: VERSion SYSTem: COMMunicate: GPIB: ADDRess STATus Subsystem SCPI-status-cls *ESE? Configure Event Status Enable Register *ESR? Read Event Status Register *ESR? Bit values for the running state *IDN? *OPC Operation Complete Bit scpi-status-questionable-condition Returns the value of the Questionable Status register *RST Reset to factory default states *STE STATUS SUbsyster Status Byte Scpi-status-register Status Register *STE Status Byte Scpi-status-register Status Register *STE Status Register Status Register *STE Status Register Status Register Status Register Scpi-status-register Status Register Status Register Scpi-status-register Status Register Status Register | | |
| SYSTem:COMMunicate:NETwork:AD- DRess SYSTem:COMMunicate:NETwork:GATE SYSTem:COMMunicate:NETwork:GATE SYSTem:COMMunicate:NETwork:SUBNet SYSTem:COMMunicate:NETwork:SUBNet SYSTem:COMMunicate:NETwork:PORT SYSTem:COMMunicate:NETwork:PORT SYSTem:COMMunicate:NETwork:HOST- name SYSTem:COMMunicate:NETwork:DHCP SYSTem:COMMunicate:NETwork:DHCP SYSTem:COMMunicate:OFIB:VERSion SYSTem:COMMunicate:GPIB:VERSion SYSTem:COMMunicate:GPIB:ADDRess STATus Subsystem Scpi-status-cls *ESE? Configure Event Status Enable Register *ESR? Bit values for the running state *IDN? *Product identification *OPC Operation Complete Bit scpi-status-questionable-condition Returns the value of the Questionable Status register *RST Reset to factory default states *STRE *STE Status Syte Scpi-status-register Status Register *STB Status Byte Scpi-status-register Status Register *STB Status Byte Scpi-status-register Status Register *STB Status Byte Scpi-status-register Status Register Status Register | | |
| SYSTem:COMMunicate:NETwork:GATE Set the static IP address SYSTem:COMMunicate:NETwork:GUBNet SYSTem:COMMunicate:NETwork:PORT SYSTem:COMMunicate:NETwork:PORT SYSTem:COMMunicate:NETwork:HOST- name SYSTem:COMMunicate:NETwork:DHCP SYSTem:COMMunicate:NETwork:DHCP SYSTem:COMMunicate:NETwork:DHCP SYSTem:COMMunicate:OPIB:VERSion SYSTem:COMMunicate:GPIB:VERSion SYSTem:COMMunicate:GPIB:VERSion SYSTem:COMMunicate:GPIB:ADDRess Returns firmware version of GPIB module SYSTem:COMMunicate:GPIB:VERSion SYSTem:COMMunicate:GPIB:VERSion SYSTem:COMMunicate:GPIB:VERSion SYSTem:COMMunicate:GPIB:VERSion SYSTem:COMMunicate:GPIB:VERSion SYSTem:COMMunicate:GPIB:VERSion Returns firmware version of GPIB module SYSTem:COMMunicate:GPIB:VERSion Set urns address of GPIB module STATus Subsystem scpi-status-cls Clear all status registers *ESR? Read Event Status Enable Register *ESR? Bit values for the running state *IDN? Product identification Operation Complete Bit scpi-status-questionable-condition Returns the value of the Questionable Status register **RST Reset to factory default states *STB Status Byte scpi-status-register Status Register | | |
| DRess SYSTem:COMMunicate:NETwork:GATE Set the Gateway IP address SYSTem:COMMunicate:NETwork:SUBNet Set the subnet IP Mask address SYSTem:COMMunicate:NETwork:PORT Set the socket number SYSTem:COMMunicate:NETwork:HOST-name Return hostname SYSTem:COMMunicate:NETwork:DHCP Set DHCP operation mode SYSTem:COMMunicate:GPIB:VERSion Returns firmware version of GPIB module SYSTem:COMMunicate:GPIB:ADDRess Returns address of GPIB module STATus Subsystem Set DHCP operation mode scpi-status-cls Clear all status registers *ESE? Configure Event Status Enable Register *ESR? Read Event Status Register *ESR? Bit values for the running state *IDN? Product identification *OPC Operation Complete Bit scpi-status-questionable-condition Returns the value of the Questionable Status register *RST Reset to factory default states *STB Status Byte scpi-status-register Status Register scpi-status-register Status Register | | |
| SYSTem:COMMunicate:NETwork:SUBNet SYSTem:COMMunicate:NETwork:SUBNet SYSTem:COMMunicate:NETwork:PORT SYSTem:COMMunicate:NETwork:HOST- name SYSTem:COMMunicate:NETwork:DHCP SYSTem:COMMunicate:NETwork:DHCP SYSTem:COMMunicate:NETwork:DHCP SYSTem:COMMunicate:GPIB:VERSion SYSTem:COMMunicate:GPIB:VERSion SYSTem:COMMunicate:GPIB:ADDRess Returns firmware version of GPIB module SYSTem:COMMunicate:GPIB:ADDRess STATus Subsystem Scpi-status-cls Clear all status registers *ESE? Configure Event Status Enable Register *ESR? Read Event Status Register *ESR? Bit values for the running state *IDN? Product identification *OPC Operation Complete Bit Scpi-status-questionable-condition Returns the value of the Questionable Status register *STE Service Request Enable Register *STB Status Byte scpi-status-register Status Register Status Register Status Register Status Register Status Register Status Register Status Register Status Register Status Register | | Set the state if address |
| SYSTem: COMMunicate: NETwork: SUBNetSet the subnet IP Mask addressSYSTem: COMMunicate: NETwork: PORTSet the socket numberSYSTem: COMMunicate: NETwork: HOST-nameReturn hostnameSYSTem: COMMunicate: NETwork: DHCPSet DHCP operation modeSYSTem: COMMunicate: GPIB: VERSionReturns firmware version of GPIB moduleSYSTem: COMMunicate: GPIB: ADDRessReturns address of GPIB moduleSTATUS SUBSYSTEMClear all status registers*ESE?Configure Event Status Enable Register*ESR?Read Event Status Register*ESR?Bit values for the running state*IDN?Product identification*OPCOperation Complete Bitscpi-status-questionable-conditionReturns the value of the Questionable Status register*RSTReset to factory default states*SREService Request Enable Register*STBStatus Bytescpi-status-registerStatus Registerscpi-status-tstExecute self-test | | Set the Gateway IP address |
| SYSTem:COMMunicate:NETwork:PORTSet the socket numberSYSTem:COMMunicate:NETwork:HOST- nameReturn hostnameSYSTem:COMMunicate:NETwork:DHCPSet DHCP operation modeSYSTem:COMMunicate:GPIB:VERSionReturns firmware version of GPIB moduleSYSTem:COMMunicate:GPIB:ADDRessReturns address of GPIB moduleSTATus SubsystemClear all status registers*ESE?Configure Event Status Enable Register*ESR?Read Event Status Register*ESR?Bit values for the running state*IDN?Product identification*OPCOperation Complete Bitscpi-status-questionable-conditionReturns the value of the Questionable Status register*RSTReset to factory default states*SREService Request Enable Register*STBStatus Bytescpi-status-registerStatus Registerscpi-status-registerStatus Registerscpi-status-tstExecute self-test | | |
| SYSTem: COMMunicate: NETwork: HOST- nameReturn hostnameSYSTem: COMMunicate: NETwork: DHCPSet DHCP operation modeSYSTem: COMMunicate: GPIB: VERSionReturns firmware version of GPIB moduleSYSTem: COMMunicate: GPIB: ADDRessReturns address of GPIB moduleSTATus SubsystemStatus registersscpi-status-clsClear all status registers*ESE?Configure Event Status Enable Register*ESR?Read Event Status Register*ESR?Bit values for the running state*IDN?Product identification*OPCOperation Complete Bitscpi-status-questionable-conditionReturns the value of the Questionable Status register*RSTReset to factory default states*SREService Request Enable Register*STBStatus Bytescpi-status-registerStatus Registerscpi-status-tstExecute self-test | | |
| nameSYSTem:COMMunicate:NETwork:DHCPSet DHCP operation modeSYSTem:COMMunicate:GPIB:VERSionReturns firmware version of GPIB moduleSYSTem:COMMunicate:GPIB:ADDRessReturns address of GPIB moduleSTATus SubsystemStatus registersscpi-status-clsClear all status registers*ESE?Configure Event Status Enable Register*ESR?Read Event Status Register*ESR?Bit values for the running state*IDN?Product identification*OPCOperation Complete Bitscpi-status-questionable-conditionReturns the value of the Questionable Status register*RSTReset to factory default states*SREService Request Enable Register*STBStatus Bytescpi-status-registerStatus Registerscpi-status-registerStatus Registerscpi-status-tstExecute self-test | | |
| SYSTem:COMMunicate:NETwork:DHCPSet DHCP operation modeSYSTem:COMMunicate:GPIB:VERSionReturns firmware version of GPIB moduleSYSTem:COMMunicate:GPIB:ADDRessReturns address of GPIB moduleSTATus SubsystemClear all status registers*ESE?Configure Event Status Enable Register*ESR?Read Event Status Register*ESR?Bit values for the running state*IDN?Product identification*OPCOperation Complete Bitscpi-status-questionable-conditionReturns the value of the Questionable Status register*RSTReset to factory default states*SREService Request Enable Register*STBStatus Bytescpi-status-registerStatus Registerscpi-status-registerStatus Registerscpi-status-tstExecute self-test | | Tetari nostitaine |
| SYSTem: COMMunicate: GPIB: VERSion SYSTem: COMMunicate: GPIB: ADDRess Returns address of GPIB module STATus Subsystem scpi-status-cls *ESE? Configure Event Status Enable Register *ESR? Read Event Status Register *ESR? Bit values for the running state *IDN? Product identification *OPC Operation Complete Bit scpi-status-questionable-condition Returns the value of the Questionable Status register *RST Reset to factory default states *SRE Service Request Enable Register *STB Status Byte scpi-status-register Status Register Status Register Status Register Status Register Status Register Execute self-test | | Set DHCP operation mode |
| SYSTem: COMMunicate: GPIB: ADDRess STATus Subsystem scpi-status-cls *ESE? Configure Event Status Enable Register *ESR? Read Event Status Register *ESR? Bit values for the running state *IDN? Product identification *OPC Operation Complete Bit scpi-status-questionable-condition Returns the value of the Questionable Status register *RST Reset to factory default states *SRE Service Request Enable Register *STB Status Byte scpi-status-register Status Register Scpi-status-register Status Register Execute self-test | | |
| STATus Subsystemscpi-status-clsClear all status registers*ESE?Configure Event Status Enable Register*ESR?Read Event Status Register*ESR?Bit values for the running state*IDN?Product identification*OPCOperation Complete Bitscpi-status-questionable-conditionReturns the value of the Questionable Status register*RSTReset to factory default states*SREService Request Enable Register*STBStatus Bytescpi-status-registerStatus Registerscpi-status-registerExecute self-test | | |
| scpi-status-clsClear all status registers*ESE?Configure Event Status Enable Register*ESR?Read Event Status Register*ESR?Bit values for the running state*IDN?Product identification*OPCOperation Complete Bitscpi-status-questionable-conditionReturns the value of the Questionable Status register*RSTReset to factory default states*SREService Request Enable Register*STBStatus Bytescpi-status-registerStatus Registerscpi-status-tstExecute self-test | | |
| *ESE? Configure Event Status Enable Register *ESR? Read Event Status Register *ESR? Bit values for the running state *IDN? Product identification *OPC Operation Complete Bit scpi-status-questionable-condition Returns the value of the Questionable Status register *RST Reset to factory default states *SRE Service Request Enable Register *STB Status Byte scpi-status-register Status Register Status Register Execute self-test | | Clear all status registers |
| *ESR? Read Event Status Register *ESR? Bit values for the running state *IDN? Product identification *OPC Operation Complete Bit scpi-status-questionable-condition Returns the value of the Questionable Status register *RST Reset to factory default states *SRE Service Request Enable Register *STB Status Byte scpi-status-register Status Register Status Register scpi-status-tst Execute self-test | | |
| *ESR? Bit values for the running state *IDN? Product identification *OPC Operation Complete Bit scpi-status-questionable-condition Returns the value of the Questionable Status register *RST Reset to factory default states *SRE Service Request Enable Register *STB Status Byte scpi-status-register Status Register Scpi-status-tst Execute self-test | *ESR? | |
| *IDN? Product identification *OPC Operation Complete Bit scpi-status-questionable-condition Returns the value of the Questionable Status register *RST Reset to factory default states *SRE Service Request Enable Register *STB Status Byte scpi-status-register Status Register scpi-status-tst Execute self-test | *ESR? | |
| *RST Reset to factory default states *SRE Service Request Enable Register *STB Status Byte scpi-status-register Status Register *Execute self-test | *IDN? | |
| scpi-status-questionable-conditionReturns the value of the Questionable Status register*RSTReset to factory default states*SREService Request Enable Register*STBStatus Bytescpi-status-registerStatus Registerscpi-status-tstExecute self-test | *OPC | Operation Complete Bit |
| *RST Reset to factory default states *SRE Service Request Enable Register *STB Status Byte scpi-status-register Status Register scpi-status-tst Execute self-test | scpi-status-questionable-condition | |
| *SRE Service Request Enable Register *STB Status Byte scpi-status-register Status Register scpi-status-tst Execute self-test | | |
| *STB Status Byte scpi-status-register Status Register scpi-status-tst Execute self-test | *SRE | |
| scpi-status-tst Execute self-test | *STB | |
| 1 | scpi-status-register | Status Register |
| scpi-status-wai Wait till complete | scpi-status-tst | Execute self-test |
| | scpi-status-wai | Wait till complete |

10.3 CALibration Subsystem

10.3.1 CALibrate:IDN

This command updates the power supply's identification string for the power supply model. The CAL: IDN string can have up to 100 characters. Before this command can be used, a password must be validated by CAL: PASS. Typically, this command is for Magna-Power Electronics use only.

Command Syntax CALibrate:IDN <string>

Parameters Company Name, Power Supply Model, Serial Number

Example CAL:IDN Magna-Power Electronics Inc., TSD16-900, S/N: 1161-5225

Query Syntax CAL: IDN?

Return Param <string>

Related Commands *IDN

10.3.2 CALibrate: PASS

This command protects against system calibration corruption and initiates the calibration sequence.

Command Syntax CAL: PASS <NR1>

Examples CALIBRATE: PASSWORD 1234, CAL: PASS 1234

10.3.3 CALibrate:POT

This command sets the value for the specified potentiometer. The variable specifies the potentiometer to be adjusted, 1 thru 5, and the second variable specifies the potentiometer setting, 0 through 255.

Command Syntax CALibrate:POT <NR1>,<NR2>

Examples CALIBRATE: POT 1,123, CAL: POT 5,11

Query Syntax CALibrate:POT?

Return Param <NR1>

10.3.4 CALibrate:SCALe:VOLTage

This command sets the voltage scale factor for the power supply.

Command Syntax CALibrate:SCALe:VOLTage <NRf>

Examples CALIBRATE: SCALE: VOLTAGE 16.0, CAL: SCAL: VOLT 16.0

Query Syntax CALibrate: SCALe: VOLTage?

Return Param <NR3>

10.3.5 CALibrate:SCALe:CURRent

This command sets the current scale factor for the power supply.

Command Syntax CALibrate:SCALe:CURRent<NRf>

Examples CALIBRATE:SCALE:CURRENT 900.0, CAL:SCAL:CURR 900.0

Query Syntax CALibrate: SCALe: CURRent?

Return Param <NR3>

10.3.6 CALibrate:SCALe:INPut

This command sets the full scale external programming inputs for voltage, current, over voltage trip, and over current trip. The scaling factor for the programming inputs must match the scaling factor set with hardware on the control board.

Command Syntax CALibrate:SCALe:INPut<NRf>

Examples CALIBRATE: SCALE: INPUT 10.0, CAL: SCAL: INP 10.0

Query Syntax CALibrate:SCALe:INPut?

Return Param <NR3>

10.3.7 CALibrate: DEFaults

This command sets the Calibration potentiometers to the factory defaults.

Command Syntax CALibrate:DEFaults Examples CALibrate:DEFaults, CAL:DEF

10.3.8 CALibrate:STOP

This command terminates the calibration subsystem.

Command Syntax CALibrate:STOP

Examples CALibrate:STOP, CAL:STOP

10.4 CONFiguration Subsystem

10.4.1 CONTrol:INTernal

This command enables or disables the front panel switches and keys for start, stop, arm, and clear. For more information, see *Commands*.

The query, CONT: INT?, returns the status of internal control.

Command Syntax [CONFigure]:CONTrol:INTernal <bool>
Parameters 0 (OFF) | 1 (ON)

Examples CONF:CONT:INT ON, CONT:INT 0

Query Syntax [CONFigure]:CONTrol:INTernal?

Return Param 0 (OFF) | 1 (ON)

10.4.2 CONTrol:EXTernal

This command enables or disables the external inputs for start, stop, arm, and clear. For more information, see *Commands*.

The query, CONT: EXT?, returns the status of external control.

Command Syntax [CONFigure]:CONTrol:EXTernal <bool>

Parameters 0 (OFF) | 1 (ON)

Examples CONF:CONT:EXT ON, CONT:EXT 0

Query Syntax [CONFigure]:CONTrol:EXTernal?

 $\textbf{Return Param} \;\; 0 \; (OFF) \; | \; 1 \; (ON)$

10.4.3 REMote:SENSe

This command sets voltage sensing to remote or local mode. *Remote sensing* improves the degradation of regulation which will occur at the load when the voltage drop in the connecting wires is appreciable. The local sense mode monitors the voltage at the output terminals of the power supply.

The query, REM: SENS?, returns the state of the sense lines.

Command Syntax [CONFigure]:REMote:SENSe <bool>

Parameters 0 (OFF) | 1 (ON)

Examples CONF:REM:SENS ON, REMOTE:SENSE 0

Query Syntax [CONFigure]:REMote:SENSe?

Return Param 0 (OFF) | 1 (ON)

10.4.4 INTErlock

This command enables or disables the external interlock feature. *Interlock (LOC)* is used for applications where the power supply needs to be disabled under external conditions.

The query, INTE?, returns the status of external interlock.

 $\textbf{Command Syntax} \hspace{0.1cm} \texttt{[CONFigure]:INTErlock}$

Parameters 0 (OFF) | 1 (ON)

Examples CONF: INTE ON, INTE O

Query Syntax [CONFigure]:INTErlock?

Return Param 0 (OFF) | 1 (ON)

10.4.5 CONFigure:SETPT

This command sets the operational mode of the power supply: ROTARY, KEYPAD, EXT PGM, or REMOTE. The operational mode determines from which interface the power supply receives its set points.

Note: KEYPAD configuration is only available for TS Series, MS Series, and MT Series supplies with the D-Version front panel.

The query, CONF: SETPT?, returns the operation mode of the power supply.

Command Syntax [CONFigure]:SETPT <NR1>

Parameters 0 (ROTARY) | 1 (KEYPAD) | 2 (EXT PGM) | 3 (REMOTE)

Examples CONF: SETPT 0, SETPT 0

Query Syntax [CONFigure]: SETPT?

Return Param <NR1>

10.5 MEASure Subsystem

10.5.1 MEASure: VOLTage?

This command queries the power supply's measured output voltage. The output voltage measurement provided is the avereage of a number of samples over a fixed time interval.

Query Syntax MEASure:VOLTage[:DC]?

Examples MEAS: VOLT?, MEASURE: VOLTAGE: DC?

Return Param <NR2>

10.5.2 MEASure: CURRent?

This command queries the power supply's measured output current. The output current measurement provided is the avereage of a number of samples over a fixed time interval.

Query Syntax MEASure:CURRent[:DC]?

Examples MEAS:CURR?, MEASURE:CURRENT:DC?

Return Param <NR2>

10.6 MODulation Commands

The Modulation Subsystem adjusts the output voltage or current according to the voltage measured on the external analog input, MOD Pin 25 of JS1, named VMOD. This signal has an allowed input range 0-10V. Modulation requires the power supply to be configured for Keypad or Remote mode. Rotary control mode or external program control mode cannot be used with these commands.

Modulation allows a set point adjustment of voltage or current by another input. The modulation signals can be derived from an external device, such as a thermistor, or from the sampling of the output current or voltage. When used with software containing advanced numerical methods, feeding the output voltage or current to adjust the set point current or voltage allows user defined output profiles. The system, incorporating this feature, introduces another negative feedback path with gain controlled by a user programmed attenuator.

Modulation can be introduced into the control loop either adding a variable to the set point or by multiplying a variable with the set point. Additive functions are useful for introducing series and parallel impedances and multiplier functions are useful for adjusting voltages or currents sources. Table 10.2 describes the four options: control input 1 and 2 for voltage and current control and control type 0 and 1 for multiplier and additive functions.

10.6.1 MODulation:TYPE:SELect

This command is composed of two comma separated, modulation parameters. The first parameter, control input, defines whether the modulation table adjusts output voltage or output current. When the control input is set to 1, VMOD selects the modulation table to adjust output voltage. When control input is set to 2, VMOD selects the modulation table to adjust output current. Setting the control input to the default value of 0, disables the modulation function. Information on programming the lookup table is provided in Table 10.2.

The second command parameter, control type, defines the expression for modulating output voltage or current. With type set to 0, table data points are used in a multiplying expression. With type set to 1, table data points are used in an addition expression.

The choice of using type 0 or type 1 modulation depends on the application. Only one set point can be modulated at any given time. The query command returns two comma separated parameters, the control input followed by the control type.

Table 10.2: Modulation Subsystem parameters control input

| Control Input | Control Type 1 | Control Type 2 |
|---------------|---------------------------------------|----------------------------------|
| 0 (Default) | Disabled | Disabled |
| 1 | $V_o = G_v[V_{ref} \times Mod(VMOD)]$ | $V_o = G_v[V_{ref} + Mod(VMOD)]$ |
| 2 | $I_o = G_v[I_{ref} \times Mod(VMOD)]$ | $I_o = G_v[I_{ref} + Mod(VMOD)]$ |

Notes:

- 1. V_o is the adjusted output voltage as a function of the modulation operator
- 2. Io is the adjusted output current as a function of the modulation operator
- 3. V_{ref} is input voltage set point reference
- 4. I_{ref} is input current set point reference
- 5. VMOD is the input modulation set point reference
- 6. G_v is the system gain as define by the full scale output voltage, V_{fs} , divided by the maximum input voltage set point reference, $V_{ref,max}$
- 7. G_i is the system gain as define by the full scale output current, I_{fs} , divided by the maximum input current set point reference, $I_{ref,max}$

Mod(VMOD), modulation, can be an expression, constant, or other numerical operator. A user friendly method chosen by Magna-Power Electronics is a table based algorithm using piecewise linear approximation. This numerical method allows linear or non-linear modulation to be introduced simply be defining the constants in a table.

Command Syntax MODulation:TYPE:SELect <NR1>[,<NR1>]

Examples MOD: TYPE: SEL 1,0, MOD: TYPE: SEL 2,1, MODulation: TYPE: SELect 0

Query Syntax MODulation:TYPE:SELect?

Return Param <NR1>, <NR1>

10.6.2 MODulation:TABLe

This command programs the user defined modulation table described in *MODulation:TYPE:SELect*. The feature allows the user to program non-linear output voltage and current profiles to fit their application needs, such as source emulation or output adjustments with respect to an external sensor. Modulation functionality may be used either by issuing SCPI commands as detailed in this section or by entering the values into a table from the RIS Panel software.

The lookup table contains 4 columns and up to 50 rows; it stores an output profile as a function of the analog input voltage applied to terminal 25 of JS1, VMOD. As shown in Table 10.3, the first column stores the table row and the second column sets an analog input VMOD. The third column store the Mod value associated with VMOD for that table row.

The fourth column of the lookup table, Loc, defines whether the table is stored in an active or temporary location. Certain applications may need to transition between different tables while the power supply is still running. For example, emulation of solar panel's voltage/current characteristics requires continuous external data acquisition along with quick and smooth table loading . The modulation subsystem provides two storage locations, Loc 0 or 1, to help improve table loading performance. With Loc set to 0, data will be stored to the Active Table, the table which is actively applied to the modulation function. With Loc set to 1, data will be stored to the Cache Table, the table intended to be accessed in the next in the profile. During the power on cycle, modulation tables stored in EPROM are copied into volatile RAM.

Modulation linearly interpolates between data points to form a piecewise-linear curve. Each column has to have data in an acceptable range. All tables less than 50 rows must be terminated with a VMOD value of 9999. Mod values at and past a row with VMOD of 9999 does not affect modulation.

Table 10.3: Modulation table parameters

| Description | Column 1: Row | Column 2: VMOD | Column 3: Mod | Column 4: Loc |
|------------------|---------------|----------------|-------------------|---------------|
| Acceptable Range | 1 to 50 | 0.0 to 10.0 | -1000.0 to 1000.0 | 0 to 1 |

While the table will store any value within the acceptable range, the power supply is limited by its output voltage and current specifications. For example, when using type 1 modulation, MOD:TYPE:SEL 1, 1, a user can store a Mod value of -1000, but the power supply will only output a voltage down to 0 V. From row 1 to 50, VMOD has to be in ascending order.

Modulation points are read with two comma separated parameters, formatted as: Row, Loc. The query will return four parameters, formatted in the same way as the save table command above.

```
Command Syntax MOD: TABL <NR1>(<NRF>,<NRF>,<NR1>)

Examples MOD: TABL 12(0.13, 1.6, 1), MODulation: TABLe 20(2.0, 15.002, 0), MOD: TABL 13(1.5, -1.29, 0), MOD: TABL 14(9999, 0, 1)

Query Syntax MOD: TABL? <NR1>,<NR1>

Return Param <NR1>(<NRF>,<NRF>,<NR1>)
```

10.6.3 MODulation:SAVE

This command copies the Active Table in RAM to a non-volatile, EEPROM memory. The Active Table, which is stored in RAM, loses its data on power down cycles. This command allows this data to be recovered at the power on cycle.

```
Command Syntax MOD:SAVE, MODulation:TABLe:SAVE
Examples MOD:SAVE
```

10.6.4 MODulation:TABLe:LOAD

This command copies all data stored in the Cache Table to the Active Table. The command provides two optional parameters for initiating the activate set points for voltage and current. The command lets users quickly load tables and simultaneous change the power supply's output operating point.

```
Command Syntax MOD:TABL:LOAD [<NRF>, <NRF>]

Examples MOD:TABL:LOAD, MODulation:TABL:LOAD 93.4, 30.3
```

10.7 OUTPut Subsystem

10.7.1 **OUTPut?**

This query returns the output state of the power supply. A 1 indicates the product's power processing circuit is active and processing power, while and a 0 indicates the power supply is in standby or faulted state.

```
Query Syntax OUTPut[:STATe]?
Examples OUTP?
Return Param 0 | 1
```

10.7.2 OUTPut:ARM

This command selects between fixed programmed set points and auto sequence mode. Fixed programmed set points energizes the product to voltage and current settings until the product is stopped. Auto sequence mode sequentially steps through the memory states, updating the supply's set points at user defined increments. Each memory location contains the voltage set point, current set point, over voltage trip, over current trip, and period. The period parameter, in milliseconds, specifies the time period for operating at the memory location when auto sequence operation is active. When enabled, the ARM light lights on the front panel.

To initiate a program sequence, select the starting memory location, execute this command, and issue an OUTP: START command or use the front panel start switch. The ARM light will blink after the start command. If this process reaches the upper memory limit, memory location 99, the following memory location will revert back to 0 and continue. Auto sequence operation will continue until an OUTP: STOP is commanded or a memory location with period set to 0 is encountered.

ARM? returns the ARM status of the power supply unit (i.e. whether ARM is enabled or disabled).

Note: The OUTPut: ARM command is only available on TS Series, MS Series, and MT Series products with the D Version front panel.

Command Syntax OUTP:ARM <bool>

Parameters 0 (OFF) | 1 (ON)

Examples OUTP: ARM OFF, OUTP: ARM 1

Query Syntax OUTP: ARM

Return Param 0 | 1

10.7.3 OUTPut:START

This command closes the power supply's input contactor and initiates either normal or auto sequence mode. Auto sequence mode will be initiated if the ARM option is enabled. Normal mode energizes the power supply with the current parameters for voltage set point, current set point, over voltage trip, and over current trip. Auto sequence mode will sequentially step through memory locations until the stop is commanded, OUTP:STOP, or a terminating condition is reached (see #REF PER, OUTP:STOP).

Command Syntax OUTP: START

Examples OUTP:START, OUTPut:START

10.7.4 OUTPut:STOP

This command opens the power supply's input contactor and initiates either normal or auto sequence mode.

Command Syntax OUTP: STOP

Examples OUTP:STOP, OUTPut:STOP

10.7.5 OUTPut:PROTection:CLEar

This command clears the alarm latches. There are seven alarm latches, namely: interlock, program line, phase balance, thermal, over voltage trip, over current trip, and input. When a fault is detected, the power supply is rendered to an alarm state. The power supply cannot be restarted until the protection condition is cleared and the latch is reset.

Command Syntax OUTPut:PROTection:CLEar

Examples OUTP:PROT:CLE, OUTPUT:PROTection:CLEar

10.8 SOURce Subsystem

10.8.1 VOLTage and VOLTage:TRIGgered

These commands set the power supply's immediate voltage level or the pending triggered voltage level. The immediate level is the voltage programmed for the immediate power supply output. The pending triggered level is a stored voltage value that is transferred to the power supply when a trigger occurs. A pending triggered level is unaffected by subsequent VOLT commands and remains in effect until the trigger subsystem receives a trigger or is aborted with an ABORt command. In order for VOLT:TRIG to be executed, the trigger subsystem must be initiated (see #REF INIT).

VOLT: TRIG? return presently programmed immediate and triggered voltage levels. If no triggered level is programmed, then the voltage level is returned for both values. The queries VOLT? MAX and VOLT? MIN return the maximum and minimum programmable immediate voltage levels. The queries VOLT: TRIG? MAX and VOLT: TRIG? MIN return the maximum and minimum programmable triggered voltage levels.

10.8.2 VOLTage:PROTection

This command sets the *over voltage trip (OVT)* level of the power supply. If the output voltage exceeds the OVT level, then the power supply output is disabled and the Questionable Condition status register OV bit is set (see #REF Table 5.6, "Bit Configuration of the Questionable Register"). An over voltage trip condition can be cleared with the OUTP: PROT: CLE command after the condition that caused the OVT trip is removed.

The query VOLT:PROT? returns presently programmed OVT level. The queries VOLT:PROT? MAX and VOLT:PROT? MIN return the maximum and minimum programmable OVT levels.

```
Command Syntax [SOURce]:VOLTage:PROTection[:LEVel] <NRf+>
Examples VOLT:PROT 21.5, `` VOLTAGE:PROTECTION:LEVEL 145E-1``
Query Syntax [SOURce]:VOLTage:PROTection[:LEVel]?, [SOURce]:VOLTage:PROTection[:LEVel]?
MIN, [SOURce]:VOLTage:PROTection[:LEVel]? MAX
```

Return Param <NR2>

10.8.3 CURRent and CURRent:TRIGgered

These commands set the immediate current level or the pending triggered current level of the power supply. The immediate level is the current programmed for the power supply output. The pending triggered level is a stored current value that is transferred to the power supply output when a trigger occurs. A pending triggered level is unaffected by subsequent CURR commands and remains in effect until the trigger subsystem receives a trigger or is aborted with an ABORt command. In order for CURR: TRIG to be executed, the trigger subsystem must be initiated (see #REF INITiate)

CURR? and CURR: TRIG? return the presently programmed immediate and triggered levels. If no triggered level is programmed, then the CURR level is returned for both values. The queries CURR? MAX and CURR? MIN return the maximum and minimum programmable immediate current levels. The queries CURR: TRIG? MAX and CURR: TRIG? MIN return the maximum and minimum programmable triggered current levels.

10.8.4 CURRent:PROTection

This command sets the *over current trip (OCT)* level of the power supply. If the output current exceeds the OCT level, then the power supply output is disabled and the Questionable Condition status register OC bit is set (see #REF Table 5.6, "Bit Configuration of the Questionable Register"). An over current trip condition can be cleared with the OUTP: PROT: CLE command after the condition that caused the OCT trip is removed.

The query CURR:PROT? returns presently programmed OCT level. The queries CURR:PROT? MAX and CURR:PROT? MIN return the maximum and minimum programmable OCT levels.

```
Command Syntax [SOURce]:CURRage:PROTection[:LEVel] <NRf+>
Examples CURR:PROT MAX CURRENT:PROTECTION:LEVEL 145E-1
Query Syntax [SOURce]:CURRent:PROTection[:LEVel]?, [SOURce]:CURRent:PROTection[:LEVel]?
    MIN, [SOURce]:CURRent:PROTection[:LEVel]? MAX
Return Param <NR2>
```

10.8.5 **PERiod**

This command sets the period of time that the power supply will remain in the state during auto sequence operation. The minimum unit for the period command is 10 msec and the maximum unit is 9997 sec. There are 3 reserved numbers associated with this command, namely: 0, 9998 and 9999. When a 0 is detected in auto sequence operation, the power supply will stop as if a Stop command condition occurred. When a 9998 is detected, the following memory location will be zero. When 9999 is detected, the power supply will operate at that memory state indefinitely or until Stop is commanded. The period's duration can be overridden by using the Start command to advance the memory to the next state or the Stop command to stop the power supply.

Note: The PERiod command is only available on TS Series, MS Series, and MT Series products with the D Version front panel.

```
Command Syntax [SOURCE]:PERiod <NRf+>
Examples SOUR:PER 200, SOURCE:PERIOD 1345, SOUR:PER MAX
Query Syntax [SOURCE]:PERiod?, [SOURCE]:PERiod? MIN, [SOURCE]:PERiod? MAX
Return Param <NR1>
```

10.8.6 Save

PER

This command stores the present state of the power supply at the specified location in memory. Data can be saved in 100 memory locations. The following power supply parameters are stored by *SAV:

```
VOLT[:LEV][:IMM]CURR[:LEV][:IMM]VOLT:PROT[:LEV]CURR:PROT[:LEV]
```

Note: The RECall: MEMory command is only available on TS Series, MS Series, and MT Series products with the D Version front panel.

```
Command Syntax *SAV <NR1>
Parameters 0-99
Examples *SAV 1
Query Syntax None
```

10.8.7 RECall:MEMory

The recall command sets the current memory location of the power supply. In remote mode, 100 (0-99) memory locations are available for programming. In KEYPAD mode, the 10 (0-9) memory locations are available for programming.

Note: The RECall: MEMory command is only available on TS Series, MS Series, and MT Series products with the D Version front panel.

```
Command Syntax [RECall]:MEMory <NR1>
Examples REC:MEM 10, MEM 99

Query Syntax RECall:MEMory?

Return Param <NR1>
```

10.9 STATus Subsystem

Status commands let you determine the condition of the MagnaDC power supply at any time, grouping together multiple feedback parameters into one returned value.

10.9.1 *CLS

This command clears all status register (ESR, STB and error queue).

```
Command Syntax *CLS
Parameters None
Examples *CLS
Return Param None
*RST Value N/A
```

10.9.2 *ESE?

This command programs the Event Status Enable Register (ESE). The programming determines which events of the *Event Status Register (ESR)* set the Event Status Bit (ESB) of the Status Byte Register (STB). A "1" in the bit position enables the corresponding event. All of the enabled events of the ESE are logically OR'd to cause the ESB of the STB to be set.

```
Command Syntax *ESE <NR1>
Parameters Register Bit Position
Examples *ESE 255
Query Syntax *ESE?
Return Param <NR1>
*RST Value N/A
```

10.9.3 *ESR?

This query reads the Event Status Register (ESR). After reading the ESR, the register is cleared. The bit configuration of the ESR is the same as the Event Status Enable Register (*ESE). The return parameter is weighted as shown in table below.

The Power On Bit (PON) is set every time the MagnaDC power supply is reset. It can be used to detect a power outage or MagnaDC power supply reset.

Command Syntax *ESR?

Parameters None

Examples *ESR?

Return Param <NR1>

*RST Value N/A

Event Status Register

| Bit | Weight | Abbreviation | Description |
|-----|--------|--------------|----------------------------------|
| 0 | 1 | OPC | Operation Complete |
| 1 | 2 | NU | Not Used |
| 2 | 4 | QYE | Query Error |
| 3 | 8 | DDE | Device Dependent Error |
| 4 | 16 | EXE | Execution Error |
| 5 | 32 | CME | Command Error |
| 6 | 64 | NU | Not Used |
| 7 | 128 | PON | Power On Event, 1 after power on |

10.9.4 *IDN?

This query requests MagnaDC power supply to identify itself, returning a string composed of three fields separated by commas.

Query Syntax *IDN?

Examples *IDN?

Return Param Company Name, MagnaDC power supply Model, Serial Number, Firmware Version

Return Example Magna-Power Electronics Inc., ARx16.75-1000-14, 1201-0001, 0.029

*RST Value N/A

10.9.5 *OPC

Note: This command is only available with the IEEE-488 GPIB (+GPIB) option.

This command clears the operation complete bit found in the event status register (*ESR*). Should be used in application programming when delay exists between sending a SCPI command and the execution of the command. When all commands have completed, the OPC bits gets set back to 1.

Query Syntax *OPC?

Examples *OPC

Return Param <NR1>
*RST Value N/A

10.9.6 *RST

This command resets the various settings and functions in the MagnaDC power supply to their factory default state. This command is commonly used in initialization routines to restore the MagnaDC power supply to a known configuration. Factory default settings for each command are indicated in the description for respective SCPI commands. SCPI commands with RST Value indicated as *N/A either are not affected by the *RST or do not have a parameter that can be changed.

Command Syntax *RST
Parameters None
Examples *RST
*RST Value N/A

10.9.7 *SRE

This command sets the Service Request Enable Register (SRE). This register, defined in the table "Service Request Enable Register", determines which bits from the Status Byte Register (see *STB for its bit configuration) are allowed to set the Service Request (RQS) Bit. A 1 in any SRE bit position enables the corresponding Status Byte Register bit. All Status Byte Register enabled bits are then logically OR'd and placed in bit 6 of the Status Byte Register. When *SRE is cleared (by programming it with 0), the power supply cannot generate a service request to the controller.

Command Syntax *SRE

Parameters Register Bit Position

Examples *SRE 20

Query Syntax *SRE?

Return Param <NR1>
*RST Value N/A

Service Request Enable Register

| Bit | Weight | Abbreviation | Description |
|-----|--------|--------------|-------------------------|
| 0 | 1 | NU | Not Used |
| 1 | 2 | NU | Not Used |
| 2 | 4 | NU | Not Used |
| 3 | 8 | QUES | Questionable Status Bit |
| 4 | 16 | MAV | Message Available Bit |
| 5 | 32 | ESB | Event Status Bit |
| 6 | 64 | RQS | Request Service Bit |
| 7 | 128 | NU | Not Used |

10.9.8 *STB

This query gets the Status Byte (STB). Registers are cleared only when the signals feeding it are cleared.

Command Syntax *STB?

Parameters None

Examples *STB?

Return Param <NR1>

*RST Value N/A

10.9.9 STATus: OPERation: CONDition?

This query returns the value of the Operation Register which is a read-only register that holds the real-time (unlatched) condition of the operational status of the power supply. The bit configuration of the Operation Register is shown in Table 10.4.

Query Syntax STATus: OPERation: CONDition?

Examples STAT: OPER: COND?, STATUS: OPERATION: CONDITION?

Return Param <NR1> (Register value)

Table 10.4: Bit configuration of the Operation Register

| Bit | Weight | Abbreviation | Description |
|-----|--------|--------------|----------------------------------|
| 0 | 1 | ARM | Arm |
| 1 | 2 | SS | Soft Start |
| 2 | 4 | LOCK | Locked |
| 3 | 8 | INT | Internal Control |
| 4 | 16 | EXT | External Control |
| 5 | 32 | WTG | Interface is Waiting for Trigger |
| 6 | 64 | STBY | Standby |
| 7 | 128 | PWR | Power |
| 8 | 256 | CV | Constant Voltage |
| 9 | 512 | RSEN | Remote Sense |
| 10 | 1024 | CC | Constant Current |
| 11 | 2048 | STBY/ALM | Standby or Alarm |
| 12 | 4096 | NU | Not Used |

10.9.10 STATus: QUEStionable: CONDition?

This query returns the value of the Questionable Register. The Questionable Register is a readonly register that holds the real-time (unlatched) condition of the questionable status of the power supply. The bit configuration of the Questionable Register is shown in Table 10.5.

Query Syntax STATus:QUEStionable:CONDition?

Examples STAT:QUES:COND?, STATUS:QUESTIONABLE:CONDITION?, SOUR:PER MAX

Return Param <NR1> (Register value)

Bit Weight Abbreviation Description 0 OV Over Voltage Tripped 2 OC Over Current Tripped 2 4 PB Phase Balance Protection Tripped 3 8 PGM Program Line Protection Tripped 4 16 OT Over Temperature Protection Tripped 5 32 FUSE Fuse Protection Tripped 64 NU Not Used 6 7 **ALM** Alarm Protection Tripped 128 8 256 **ILOC** Interlock 9 512 **REM** Remote 1024 Not Used 10 NU

Table 10.5: Bit configuration of the Questionable Register

10.10 SYSTem Subsystem

10.10.1 SYSTem: VERSion?

The SYST: VERS? query returns the firmware and hardware version of the power supply. The returned value has the form Firmware Rev. X.X, Hardware Rev. X.X.

Query Syntax SYSTem: VERSion?

Examples SYST: VERS?, SYSTEM: VERSION?

Return Param <Firmware Rev. XX.Y, Hardware Rev. XX.Y>

10.10.2 SYSTem: ERRor?

The SYST: ERR? query returns the error messages that have occurred in the system. The format of the return string is an error number followed by corresponding error message string. The errors are stored in a FIFO (first-in, first-out) buffer. As the errors are read, they are removed from the queue. When all errors have been read, the query returns 0, "NO ERROR." If more errors have accumulated than the queue can hold, the last error in the queue will be -350, "Queue Overflow." When system errors occur, the Standard Event Status Register (ESR), records the error groups as defined in Table 10.7. Table 10.7 lists system errors that are associated with SCPI syntax errors and with interface problems.

Query Syntax SYSTem: ERRor?

Examples SYST: ERR?, SYSTEM: ERROR?

Return Param <error number> | <error string>

Table 10.6: Standard Event Status Register Error Bits

| Bit | Error Code | Error Type |
|-----|------------------|------------------|
| 5 | 100 through -199 | Command |
| 4 | 200 through -299 | Execution |
| 3 | 300 through -399 | Device Dependent |
| 2 | 400 through -499 | Query |

Table 10.7: Error Messages

| Error | Error String | Error Description | |
|-------|-------------------|---|--|
| -100 | Command error | Generic command error | |
| -102 | Syntax error | Unrecognized command or data type | |
| -108 | Parameter not al- | Too many parameters | |
| | lowed | | |
| -222 | Data out of range | E.g., outside the range of this device | |
| -350 | Queue overflow | Errors lost due to too many errors in queue | |
| -400 | Query error | Generic query error | |

10.10.3 SYSTem:COMMunicate:NETwork:VERSion?

This query reads the firmware and hardware versions of the Ethernet communications module.

Query Syntax [SYSTem][:COMMunicate]:NETwork:VERSion?

Examples SYST:COMM:NET:VERS?, NET:VERS?

Return Param <Firmware Ver. XX.Y, Hardware Rev. XX.Y>

10.10.4 SYSTem:COMMunicate:NETwork:MAC?

This query returns the MAC address of the Ethernet module. MAC address consist of two number groups: the first three bytes are known as the Organizationally Unique Identifier (OUI), which is distributed by the IEEE, and the last three bytes are the device's unique serial number. The six bytes are separated by hyphens. The MAC address is unique to the instrument and cannot be altered by the user.

Query Syntax [SYSTem][:COMMunicate]:NETwork:MAC?

Examples SYST:COMM:NET:MAC?, NET:MAC?
Return Param <XX-XX-XX-YY-YY-YY>

10.10.5 SYSTem:COMMunicate:NETwork:SER

This command sets the serial number of the Ethernet module. The serial number is an integer ranging from 1 to 16777215 and cannot be altered by the user.

Query Syntax [SYSTem][:COMMunicate]:NETwork:SER?

Examples SYST:COMM:NET:SER?, NET:SER?

Return Param <NR1>

10.10.6 SYSTem:COMMunicate:NETwork:ADDRess

This command sets the static address of the Ethernet module of the MagnaDC power supply. In absence of a DHCP server, the address automatically selects 169.254.###.###

Command Syntax [SYSTem][:COMMunicate]:NETwork:ADDRess <string>

Parameters IP address is represented with 4 bytes each having a range of 0-255 separated by periods

Examples SYSTem: COMM: NET: ADDR 192.168.10.2, NET: ADDR 192.168.10.2

Query Syntax [SYSTem][:COMMunicate]:NETwork:ADDRess?

Return Param <string>

10.10.7 SYSTem:COMMunicate:NETwork:GATE

This command sets the Gateway IP address of the Ethernet module of the MagnaDC power supply. The Gateway IP defaults to 0.0.0.0 in absence of a DHCP server.

```
Command Syntax [SYSTem][:COMMunicate]:NETwork:GATE <string>
```

Parameters Gateway IP address is represented with 4 bytes each having a range of 0-255 separated by dots

```
Examples SYSTem: COMM: NET: GATE 192.168.10.2, NET: GATE 192.168.10.2
```

Query Syntax [SYSTem][:COMMunicate]:NETwork:GATE?

Return Param <string>

10.10.8 SYSTem:COMMunicate:NETwork:SUBNet

This command sets the subnet IP Mask address of the Ethernet module of the MagnaDC power supply. The factory subnet mask setting is 255.255.255.0.

```
Command Syntax [SYSTem][:COMMunicate]:NETwork:SUBNet <string>
```

Parameters IP mask address is represented with 4 bytes each having a range of 0-255 separated by periods.

```
Examples SYSTem: COMM: NET: SUBNet 255.255.255.128, NET: SUBNet 255.255.255.128
```

Query Syntax [SYSTem][:COMMunicate]:NETwork:SUBNet?

Return Param <string>

10.10.9 SYSTem:COMMunicate:NETwork:PORT

This command sets the Socket (Port) of the Ethernet module of the MagnaDC power supply. The factory default port setting is 50505. The factory recommends port values greater than 49151 to avoid conflicts with registered Ethernet port functions.

```
Command Syntax [SYSTem][:COMMunicate]:NETwork:PORT <NR1>
```

Parameters 16-bit socket number (1 to 65,535)

Examples SYSTem: COMM: NET: PORT 50505, NET: PORT 50505

Query Syntax [SYSTem][:COMMunicate]:NETwork:PORT?

Return Param <NR1>

10.10.10 SYSTem:COMMunicate:NETwork:HOSTname

This query reads the host name of the Ethernet communications module.

Query Syntax [SYSTem][:COMMunicate]:NETwork:HOSTname?

Examples SYST:COMM:NET:HOST?, NET:HOST?

Return Param <string>

10.10.11 SYSTem:COMMunicate:NETwork:DHCP

This command sets the DHCP operating mode of the Ethernet module. If DHCP is set to 1, the module will allow its IP address to be automatically set by the DHCP server on the network. If DHCP is set to 0, the default IP address is set according to .

Command Syntax [SYSTem][:COMMunicate]:NETwork:DHCP <NR1>

Parameters 0 (DHCP Off) | 1 (DHCP On)

Examples SYST:COMM:NET:DHCP 0, NET:DHCP 1

Query Syntax [SYSTem][:COMMunicate]:NETwork:DHCP?

Return Param <NR1>

10.10.12 SYSTem:COMMunicate:GPIB:VERSion

This query is available only for units with the IEEE-488 GPIB (+GPIB) option installed. This query reads the firmware version of the GPIB communication module.

Query Syntax [SYSTem][:COMMunicate]:GPIB:VERSion?

Examples SYST:COMM:GPIB:VERS?, GPIB:VERS?

Return Param <Firmware Ver. XX.Y>

10.10.13 SYSTem:COMMunicate:GPIB:ADDRess

This command is available only for units with the IEEE-488 GPIB (+GPIB) option installed. This command sets the address of the GPIB module of the MagnaDC power supply. The address can be 1 to 30 where address 0 is normally assigned to the GPIB Master. The factory default address is 1.

Command Syntax [SYSTem][:COMMunicate]:GPIB:ADDRess <NR1>

Parameters 1 - 30

Examples SYST:COMM:GPIB:ADDR 27, GPIB:ADDR 27

Query Syntax [SYSTem][:COMMunicate]:GPIB:ADDR?

Return Param <NR1>

10.11 TRIGger Commands

10.11.1 TRIGger

This command controls remote triggering of the power supply. When the trigger subsystem is enabled, a TRIG command generates a trigger signal. The trigger signal will then initiate a pending level change as specified by CURR[:LEV]:TRIG or VOLT[:LEV]:TRIG. Afterwards, the Operation Register will be cleared. If INIT:CONT is on, the trigger subsystem is immediately reenabled for subsequent triggers. As soon as it is cleared, the WTG bit is again set to 1.

Command Syntax TRIGger[IMMediate]
Examples TRIG, TRIGGER: IMMEDIATE

10.11.2 INITiate

This command enables the trigger system. When the initiate command is enabled, a TRIG command allows specified triggering action to occur. If the initiate subsystem is not enabled, all trigger commands are ignored. If INIT:CONT is OFF, then INIT enables the trigger subsystem only for a single trigger action; INIT must then be repeated prior to further trigger commands. If INIT:CONT is ON, then the trigger subsystem is continuously enabled.

INIT:CONT? returns the state of the continuous trigger mode.

The following sytaxes are for INITiate[:IMMediate]

Command Syntax INITiate[:IMMediate]

Parameters None

Examples INIT, INITIATE: IMMEDIATE

Query Syntax None

The following sytaxes are for INITiate[:CONTinuous]

Command Syntax INITiate:CONTinuous <bool>

Parameters 0 (OFF) | 1 (ON)

Examples INIT: CONT 1, INITIATE: CONTINUOUS OFF

Query Syntax INIT: CONT?

Return Param 0 | 1

10.11.3 ABORt

This command cancels any trigger actions presently in process. Any pending trigger levels are reset to their immediate values. ABORt also resets the WTG bit in the Operation Register. If initiate continuous is enabled (INIT:CONT ON), the trigger subsystem immediately re-initiates itself after ABORt, thereby setting WTG. ABOR is executed at power turn on and upon execution of *RCL or *RST.

Command Syntax ABORt

Examples ABOR